HUMAN MORPHOMETRICS. MOTION, AND PERFORMANCE RESEARCH

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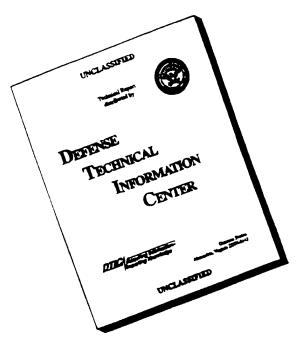
This technical report has been reviewed and is approved for publication.

FOR THE COMMANDER

KENNETH R. BOFF, Chief Human Engineering Division Armstrong Laboratory

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This report is the last in a series of 14 quarterly progress reports under Air Force Contract F33615-89-C-0572. Over the course of the three-and-a-half year contract period, the work was focused on a wide variety of tasks which were all united by a common theme: the application of one-, two-, and three-dimensional anthropometric data to problems of design and personal protection. The tasks that were active during the final quarter are reported here in detail, but these represent only a subset of all the tasks carried out over the entire contract period. This report includes an index to tasks reported in the preceding 13 reports.

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PREFACE

This document is the final report for a research contract spanning three-and-one-half years. Incremental progress was reported in quarterly reports throughout the period, and in the interest of brevity and conserving resources, that earlier material is not presented here. However, an index to those earlier is provided here. Requests for access to previously reported research should be directed to Kathleen M. Robinette, Armstrong Laboratory, Wright-Patterson Air Force Base, Ohio 45433-7022.

The author list for this report consists of those who contributed materially to the research, however, this work builds substantially on work that has gone before. It is therefore appropriate to recognize the contributions of those who worked on this program in previous quarters. The authors gratefully acknowledge the work of the following individuals: Charles E. Clauser, Shirley Kristensen, John T. McConville, and Phillip Walker, Anthropology Research Project, Inc.; Robert M. Beecher, Beecher Research Company; Jerome Brainard, Robert Bolia, and Kevin Nuse, Systems Research Laboratories, Inc.; Dennis Burnsides, Sytronics, Inc.; Joseph Nurre, Ohio University; Makarand V. Ratnaparkhi, Wright State University. From Anthropology Research Project, Inc., Ilse O. Tebbetts edited and revised the text of this report and all previous quarterly reports. Belva M. Hodge and Jennifer Schinhofen prepared this and previous report manuscripts.

The work reported here and in previous reports was guided throughout by Kathleen M. Robinette, the technical monitor of this contract. Other valuable assistance was provided by Capt John T. Crist, Jennifer J. Whitestone, and Gregory F. Zehner, all of Armstrong Laboratory.

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SUMMARY

This report is the last in a series of 14 quarterly progress reports under Air Force Contract F33615-89-C-0572. Over the course of the three-and-a-half year contract period, the work was focused on a wide variety of tasks which were all united by a common theme: the application of one-, two-, and three-dimensional anthropometric data to problems of design and personal protection. The tasks that were active during the final quarter are reported here in detail, but these represent only a subset of all tasks carried out over the entire contract period. This report includes an index to tasks reported in the preceding 13 reports.

A study to determine whether automated methods of obtaining anthropometric data are more reliable than traditional methods was designed and partially completed. The experimental design and data analysis procedures are reported here. The analysis is separated into two phases: the repeatability of traditional anthropometry and the repeatability of laser scanner anthropometry.

One of the most time consuming tasks associated with processing scanner images of heads is the identification of the subject's anatomical landmarks on the scanned images. A blackboard system has been developed to automate this process. Major effort during the final reporting period was applied to the development of high-reliability knowledge sources for use in the blackboard system. This report summarizes the current state of the blackboard system and identifies the direction needed for future work.

A number of tasks were undertaken to support the Helmet-Mounted Systems Technology (HMST) program office. The fit assessment of the HGU-53/P helmet received the most attention during this period. A measuring team travelled to four Air Force bases and collected data from 185 subjects. Data were collected on: traditional anthropometry, laser scan, helmet fit, and sound attenuation. As the data were collected only a short time before the contract period concluded, detailed analysis is not provided here.

Fit assessment were also done for the Advanced Technology Anti-G Suit (ATAGS). The measurement team travelled to five Air Force bases and collected data from 269 air crew. As with the HGU-53/P evaluations, data collection was completed only days before the end of the contract period, so analysis is not reported here.

To improve the effectiveness of the Computerized Anthropometric Research and Design (CARD) Laboratory, we began a structured analysis of the functions and goals of the laboratory. The functions of the laboratory were structured into an Enterprise Model in the previous reporting period. During this period, problems and approaches to solving them were identified for the four highest level functions in the laboratory. These high level functions are: Provide Research and Services; Promote the Laboratory; Provide Software and Hardware Support; and Manage the Laboratory. A structured approach to solving the problems is presented.

Work continued on the cockpit accommodation database, and significant tasks were completed. The initial version of the database on the VAX was completed, and validation of the algorithms for the F-16A and C-141A are underway. The database was ported to INFORMIX, a

SUMMARY (cont'd)

UNIX-based DBMS, so that it can be operated on the Silicon Graphics (SG) workstations. This serves the laboratory's long-term goal of becoming hardware independent. A procedures document, covering both the initial collection of the accommodation data and its subsequent analysis, has been prepared in draft form, and will be included in the database available on the SG. Additionally, we developed a prototype software program to facilitate the input of raw reach data from the field. While currently residing on the VAX, subsequent versions will be available for a DOS-based laptop so it can be easily used in field situations.

In the area of cockpit accommodation analysis, a technical report, entitled "Anthropometric Accommodation in Aircraft Cockpits: A Methodology for Examination," was submitted for review. Additionally, our subcontractor conducted a follow-on cockpit evaluation of the T-38 aircraft, and conducted a technical review of a U.S. Navy report, "Procedural Guide to Aircrew Anthropometric Accommodation Assessment," TM 92-74 SY.

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INTRODUCTION

Although the research outlined in the Air Force RFP for this three-and-a-half-year contract period was differentiated into 12 separate tasks, a central theme common to much of the work was the collection, processing, and use of three-dimensional anthropometric data.

With the capability for gathering 3-D data well-established, at least with respect to head and face segments of the body, completion of the minisurveys of Air Force and Navy aviator personnel presented few unforeseen problems. Most of the research challenges during this time were focused on finding ways to access and use 3-D data. Great strides were made in the development and improvement of the INTEGRATE program which now enables users to visualize, manipulate, and edit such data on-screen, and to calculate measurements such as point-to-point distances and volumes. Considerable progress was also made in automatic landmark identification of both marked and unmarked points through the use of color and outline recognition techniques.

The growing 3-D database was added to the CARD laboratory's data system, and software was modified and improved to enable users to access and use this information. As yet unresolved is the problem of summarizing 3-D data, although a number of methodologies investigated during this contract period may yet prove to bear fruit. Among them are a mathematical approach known as curvature analysis (Ratnaparkhi); a computerized technique which seeks to determine an "average face," (Beecher); and KRIGing, a method which produces, in effect, three-dimensional regression equations (Robinson and Grant).

The ability to scan and record head/face shape was put to use in a number of studies conducted for the Air Force and its contractors. In one such study, for example, investigators established facial clearances available between helmet and mask for the design and placement of optical equipment such as night vision goggles. In another, representative heads were selected from scan data files for use in the construction of generic head forms. In still another application, the scanning capability was used to study face casts of aviators with atypical faces with the aim of minimizing the need for custom masks.

A sizable number of clothing and personal protective items were evaluated in the past three years. Major efforts included fit evaluations of Navy and Air Force womens' uniforms, for purposes of creating size selection charts, establishing tariffs, and providing guidance for the design and modification of patterns. In a joint Air Force/Navy project, a variety of helmet-mounted systems were tested to determine fit, comfort, and optical function of these ensembles. Updated fit testing procedures were documented in various ways — among them an in-house guide for creating SAS formatted files, and a draft manual designed for use by the Air Standardization Coordinating Committee (ASCC).

A somewhat different form of fit testing was carried out during the three-year cockpit accommodation study in which subjects were used as "tools" to establish body-size parameters for functioning safely and effectively in a variety of aircraft. Techniques for collecting and analyzing . these data were developed and applied in field studies involving nearly a dozen U.S. and many foreign aircraft. Methods for establishing cockpit accommodation limitations for overhead clearance, ejection clearances, rudder-pedal operation, visual access, and hand reach to controls, were documented in a draft technical report along with results of studies conducted on specific aircraft.

Tri-service matters received considerable attention during this contract period. Matching procedures developed by ARP and Air Force personnel were used to assess the possibilities of standardizing sizing for Army, Navy, and Air Force clothing, with promising results. Work was also done on identifying a headform best suited to represent the U.S. military population, and on determining the feasibility of developing a single analogue or family of models to represent tri-service females.

Under contract to the Air Force, ARP developed and maintained the much-used AAMRL data bank which, for many years, supplied body size information to the Air Force and to many other users. This contract period has seen the rapid development of the next-generation anthropometric resource: the CARD data base system. Maintenance, up-dating, and improvement of this facility have been ongoing tasks throughout this contract period. Adding new survey data, upgrading memory and graphics, improving software required to access and use data, and conducting various SAS and statistical analyses in support of numerous other projects have been among our on-going tasks. An updated CARD users guide was published as AL-TR-1992-0036. Attention has also been given to updating multivariate models which have increasingly come to supplant percentiles in solving a variety of design problems.

Finally, on-going support services provided by ARP staff and subcontractors included evaluation and installation of new hardware and software, and maintenance of both old and new computer systems.

All of the work completed during the contract period has been described in detail in a series of 13 progress reports. This final report describes the tasks completed during the past three months. An index provides a guide to descriptions and reports of all the earlier work by task and project.

Staff

During this reporting period the staff of the Anthropology Research Project (ARP) was made up of the following people:

Bruce Bradtmiller	President
Belva M. Hodge	Business Manager
James F. Annis	Senior Research Associate
Henry W. Case	Research Associate
Daniel Mountjoy	
Sherri Upchurch Blackwell	Research Associate
Thomas Churchill	Senior Computer Programmer
Shirley Kristensen	Research Assistant
Teresa Mayfield	
Ilse Tebbetts	Editor/Technical Writer
Jennifer A. Schinhofen	Secretary

Travel

On 7-24 July 1993, Dan Mountjoy and Bob Bolio travelled to Ft. Walton Beach, Florida for the HGU-53/P fit evaluation. On 1-14 August 1993, Henry Case and Sherri Blackwell travelled to Nellis AFB, Nevada for the ATAGS fit testing. On 1-21 August 1993, Dan Mountjoy and Bob Bolio travelled to Shaw AFB, South Carolina for the HGU-53/P fit evaluation. On 23-30 August 1993, Henry Case and Sherri Blackwell travelled to Langley AFB, Virginia for the ATAGS fit testing. Also, on 13-25 September 1993, Henry Case and Sherri Blackwell travelled to Tyndall AFB, Florida for the ATAGS fit testing.

Major Purchases

Quantity	<u>Item</u>	<u>Amount</u>	Task Number
1	Optical Disk Cartridge	\$499.00	12

TECHNICAL DISCUSSION

The statement of work for this contract calls for a series of separate but interrelated tasks. Each of these tasks is discussed below.

TASK 1

...shall perform an anthropometric survey of USAF personnel using a threedimensional measuring device provided by the Air Force....The survey plans shall include sampling for age, race, sex, job category, and rank, and their effect on body size...

Work under this task was not initiated.

TASK 2

...shall conduct analyses in order to determine the three-dimensional locations of specific anatomical landmarks; consistent and repeatable methods of defining and locating these structures or points must be derived...Data editing shall include...visual inspection...of datasets...as well as a more thorough inspection of the data after the survey is complete. Initial data analysis shall include the calculation of point-to-point distances, arcs, and circumferences...

Reliability Study of Head and Face Measurement Methods

The advent of automated methods of obtaining anthropometric data, raises the question of how these methods compare with traditional anthropometry. A study to answer this question with regards to linear head measurements was designed and partially completed. The ultimate goal of the study was to determine which method of gathering anthropometric data is most reliable. This draft report documents the experimental design and data analysis procedures for this study. The data analysis is

separated into two phases: the repeatability of traditional anthropometry, and the repeatability of scanner anthropometry.

Dimensions and Landmarks

Linear measurements were the focus of the study, because of their simplicity. With arcs and circumferences there is the question of whether the measurement should follow or span the hollow of the body. For instance, for a waist circumference, should the tape follow the hollow of the back or should it span the hollow. The question becomes more critical when dealing with scans, because it is necessary to tell the software how to calculate the measurement using the scan data. The following measurements were taken in the experiment: menton-sellion length, glabella-pronasale, minimum frontal breadth, bizygofrontale breadth, bizygomatic breadth, bitragion breadth, bigonial breadth, and interpupillary distance. Anatomical landmarks associated with these dimensions are: frontotemporale, glabella, gonion, menton, pronasale, pupil, sellion, tragion, zygion, and zygofrontale.

Experimental Design

Three people trained as landmarkers and measurers participated. One person ran the scanner, three served as data recorders, three served as landmarkers/measurers, and another three people served as subjects.

In the experimental design, three markers marked each subject three times. Each time a subject was marked by a marker, each of three measurers measured the subject twice and the subject was scanned twice. The experimental design for one subject and one marker is shown in Tables 2.1 and 2.2.

In order to actually conduct the experiment, it was necessary to schedule the marking and measuring sessions so that all three landmarkers/measurers and subjects could be working simultaneously and so that data collection could be broken up into sections spanning several days with breaks to reduce the memory effect. Therefore, the schedule shown in Table 2.3 was developed. In this schedule, data collection was divided into three trials containing three phases. Each phase represents the marking of each subject by one landmarker and the measuring of each subject by each measurer twice.

In one trial of three phases each subject was marked one time by each landmarker, scanned six times, and measured six times by each measurer. The purpose of conducting three trials was to allow each landmarker to mark each subject three times. By the completion of three trials, each subject had been marked three times by each landmarker, measured 18 times, and scanned 18 times by each measurer. In summary, there were three subjects with 54 repeated measures each of traditional anthropometry.

The experimental data were gathered in 4.5 days. For four days, two phases of a trial were conducted. Data were collected in one morning and one afternoon session per day. On the fifth day, data were collected in one afternoon session.

TABLE 2.1

Traditional Anthropometry
Experimental Design for One Subject, One Marker

Subject	Marker	Marking Session	Measurer	Measuring Session
	(LNDMRKR)	(TRIAL)	(MEASR)	(REP)
1	1	1	1	1 2
			2	1 2
			3	1 2
		2	1	1 2
			2	1 2
			3	1 2
		3	1	1 2
			2	1 2
			3	1 2

TABLE 2.2

Scanner Anthropometry
Experimental Design for One Subject, One Marker

Subject	Marker	Marking Session	Scan Session	Picker	Picking Session
1	1	1	1	1	1 2
				2	1 2
				3	1 2
			2	1	1 2
				2	1 2
				3	1 2
		2	1	1	1 2
				2	1 2
				3	1 2
			2	1	1 2
				2	1 2
				3	1 2
		3	1	1	
				2	1 2 1 2

TABLE 2.3
Schedule of Events for Each Trial of the Experiment

Marker/Measurer	M 1	M2	M 3
Phase 1			
Subject Marked/Scanned	S 1	S2	S 3
Subject Measured	S1 S3	S2 S1	S3 S2
	\$2 \$1	S3 S2	S1 S3
	S3	S 1	S2
Phase 2	S 2	S 3	S1
Subject Marked/Scanned	S3	S1	S2
Subject Measured	S3 S2	S1 S3	S2 S1
	S1 S3	S2 S1	S3 S2
	S2 S1	S3 S2	S1 S3
Phase 3			
Subject Marked/Scanned	S2	S 3	S 1
Subject Measured	S2 S1	S3 S2	S1 S3
	S3 S2	S1 S3	S2 S1
	S1 S3	S2 S1	\$3 \$2

The data collection schedule was as follows:

Day 1: Trial 1, Phase 1 and Trial 1, Phase 2

Day 2: Trial 1, Phase 3 and Trial 2, Phase 1

Day 3: Trial 2, Phase 2 and Trial 2, Phase 3

Day 4: Trial 3, Phase 1 and Trial 3, Phase 2

Day 5: Trial 3, Phase 3

Data Analysis

Statistical Methods:

In a single group situation with one repeated measures factor and k repeated measures, the univariate repeated measures analysis is a two-way mixed effects model with subjects as a random effect and the repeated measures factor as a fixed effect. Several repeated measures factors were studied in this analysis. Not all interactions between them are of interest because in some cases: (1) the analysis was rendered powerless due to a small number of error degrees of freedom, and (2) interactions did not make sense and were uninterpretable. Furthermore, the repeated measures factors were treated as random effects rather than fixed effects, because variance components were estimated.

The statistical assumptions common to a univariate single group repeated measures design are:

- (1) Independence of subjects
- (2) Multivariate normality
- (3) A linear model
- (4) Sphericity

Sphericity occurs when the variances among all possible pairwise differences of the levels or treatments on the repeated measures factors are equal. It is reasonable to assume that the repeatability data satisfy the four assumptions required for a univariate analysis.

Each anthropometric dimension was examined separately for significant effects and for estimates of variance components. A significance level of .05 was used to test for significant effects.

The plan was to divide the analysis of the experimental data into two parts: Determining repeatability for traditional anthropometry, and determining the repeatability of scanner anthropometry.

Repeatability of Traditional Anthropometry

The main questions to by answered by this analysis were:

- (1) How great is the variation among the repeated measures as a result of the landmarking process?
- (2) How great is the variation among the repeated measures as a result of the measuring process?

Sources of error expected to affect the variability in traditional anthropometry and of interest to this study were the landmarking process (within and between landmarker) and the measuring process (within and between measurer).

The repeatability of traditional anthropometry for linear head measurements was measured using analysis of variance with subjects blocked and three within-subject factors (trial with three levels, landmarker with three levels, and measurer with three levels). The dependent variables consisted of the eight anthropometric dimensions producing eight separate univariate analyses.

A random effects model was appropriate because we were not interested in making inferences about the three landmarker/measurers. We were interested in the population of landmarker/measurers. With a random effects model, the variance of subject, trial, and repetition can be estimated using the error sums of squares since all interactions involving these factors are assumed to be insignificant as they do not make sense. Since the interaction between landmarker and measurer was being tested, the variance of landmarker and of measurer could be estimated using the error sums of squares for their interaction.

The proportion of the total variance due to trial was the between-trial or within-landmarker error. The proportion of the total variance due to landmarker was the between-landmarker error. The proportion of the total variance due to measurer was the between-measurer error. The proportion of the total variance due to repetition was the between-repetition error or within-measurer error.

There were 162 (3 trials x 3 landmarkers x 3 measurers x 2 repetitions x 3 subjects) observations and 161 degrees of freedom (d.f.) for univariate statistical analysis of traditional anthropometry. The sums of squares can be partitioned into the following terms:

Subject	(2 d.f.)
Landmarker	(2 d.f.)
Subject*Landmarker	(4 d.f.)
Trial	(2 d.f.)
Subject*Trial	(4 d.f.)
Trial*Landmarker	(4 d.f.)
Subject*Trial*Landmarker	(8 d.f.)
Measurer	(2 d.f.)
Subject*Measurer	(4 d.f.)
Landmarker*Measurer	(4 d.f.)
Subject*Landmarker*Measurer	(8 d.f.)

Trial*Measurer	(4 d.f.)
Subject*Trial*Measurer	(8 d.f.)
5	` ,
Trial*Landmarker*Measurer	(8 d.f.)
Subject*Trial*Landmarker*Measurer	(16 d.f.)
Repetition	(1 d.f.)
Subject*Repetition	(2 d.f.)
Landmarker*Repetition	(2 d.f.)
Subject*Landmarker*Repetition	(4 d.f.)
Trial*Repetition	(2 d.f.)
Subject*Trial*Repetition	(4 d.f.)
Trial*Landmarker*Repetition	(4 d.f.)
Subject*Trial*Landmarker*Repetition	(8 d.f.)
Measurer*Repetition	(2 d.f.)
Subject*Measurer*Repetition	(4 d.f.)
Landmarker*Measurer*Repetition	(4 d.f.)
Subject*Landmarker*Measurer*Repetition	(8 d.f.)
Trial*Measurer*Repetition	(4 d.f.)
Subject*Trial*Measurer*Repetition	(8 d.f.)
Trial*Landmarker*Measurer*Repetition	(8 d.f.)
Subject*Trial*Landmarker*Measurer*Repetition	(16 d.f.)

To test for significant within-subjects effects, the p-values for the univariate unadjusted F tests are given below for each anthropometric dimension (labeled M1 through M8) and each within-subjects factor:

Effect	M1	M2	М3	M4	M5	M6	M7	M8
Trial	.01	.11	.00	.18	.11	.15	.35	.75
Landmarker	.00	.01	.00	.00	.57	.01	.00	.29
Measurer	.00	.00	.00	.00	.00	.00	.00	.00
Repetition	.57	.83	.31	.87	.15	1.0	.39	.93
Interaction	.53	.95	.96	1.0	.99	.69	.87	.02
M1=Promenton-Sellion Lth			M2=Glabella-Pronasale Lth					
M3=Min Frontal Brdth			M4=Bizygofrontale Brdth					
M5=Bizygomatic Brdth M6=Bitragion Brdth			L					
M7=Bigonial Brdth M			M8=Interpupillary Brdth					

With a .05 significance level, Trial is significant for Promenton-Sellion Lth and Min Frontal Brdth. Landmarker is significant for all dimensions except Bizygomatic Brdth and Interpupillary Brdth. Measurer is significant for all dimensions. Repetition is insignificant for all dimensions. The Landmarker/Measurer interaction is insignificant for all dimensions except Interpupillary Brdth which is considered a fluke, because pupils are not landmarked.

The SAS procedure VARCOMP was used to estimate the variance components of the model for each dimension. They showed that the estimated variances for Trial, Landmarker, Measurer, Repetition, and the interaction between Landmarker and Measurer were near zero or very small for all

anthropometric dimensions except for Bigonial Breadth. Estimated variances of Landmarker and Measurer were quite high relatively speaking. This outcome was not surprising as Bigonial Breadth was considered the hardest dimension to landmark, because the bigonion landmarks are not very pronounced in some people. It was also the hardest to measure, because there may be a lot of tissue in the area on some people making it quite sensitive to the amount of pressure applied by the measurer.

The overall conclusion for this part of the study was that linear measurements of the head and face obtained through traditional measuring techniques are quite repeatable for measurements defined by easily distinguishable landmarks that are not surrounded by much tissue.

Repeatability of Scanner Anthropometry:

This part of the study was not completed, but it was designed as follows:

There will be 324 (3 landmarkers x 3 trials or landmarking sessions x 2 scanning sessions x 3 point pickers x 2 picking sessions x 3 subjects) observations (323 d.f.) for statistical analysis of scanner anthropometry.

Sources of error that are expected to affect the variability in scanner anthropometry and that are of interest to this study are the landmarking process (within and between landmarker), the scan point picking process (within and between point picker), and the scanner point randomization. Scanner point randomization refers to the fact that when two identical bodies are scanned, the resulting scanned images will not be identical due to a random error in the scanner.

The scanner anthropometry will consist of point-to-point distances between landmarks. These point-to-point distances will be comparable to the traditional anthropometric measurements mentioned above.

The repeatability of scanner anthropometry for linear head measurements can be measured using an analysis of variance with subjects blocked and five within-subject factors (trial with three levels, landmarker with three levels, scanning session with two levels, point picker with three levels, and point picking session with two levels). The dependent variables consist of the eight dimensions producing eight separate univariate analyses.

Using a random effects model, the variance of each factor can be estimated. The proportion of the total variance due to marking session is the within-landmarker error. The proportion of the total variance due to landmarker is the between-landmarker error. The proportion of the total variance due to scanning session is scanner point randomization error. The proportion of the total variance due to point picker is the between-point-picker error. The proportion of the total variance due to point picking session is the within-point-picker error.

Comparison of Traditional and Scanner Anthropometry:

To determine the repeatability of traditional measuring techniques versus computerized measuring techniques, we believe that the estimated variances for each method of anthropometric measurement can be statistically compared, measurement by measurement. Research will have to be conducted to develop the exact methodology for doing this.

...shall develop automated methods of extracting specific measurements from high density, three-dimensional datasets...These methods shall be capable of extracting distance data between both pre-marked specific points and specific points which have not been pre-marked...

Blackboard Systems

Work continued on Dr. Randy Pollack's blackboard system. Initial rework was complete. Major effort during the final reporting period was applied to development of robust high-reliability knowledge sources. The focus was on identifying which landmark is associated with each of the blue spots. As work progressed, more and more possibilities for exploiting the data were recognized. For instance, with "positive" identification of the midsagittal landmarks (Glabella, Sellion, Pronasale, and sometimes Promenton), it has become possible to identify the exact midsagittal longitude with absolute certainty. The present state of the blackboard system is as follows:

- a. The neck and top-of-head are being positively identified. These algorithms have been tested on a small sample of the HGU-53/P survey.
- b. The midsagittal longitude is being estimated using the previously discussed algorithm which depends on head length > head width. This algorithm appears less certain on the HGU-53/P data than on the minisurvey data, due to an apparent tendency of the subjects to tilt their heads in the HGU-53/P survey, and due to slightly less precise positioning of the heads with respect to the center of scan. This algorithm works most of the time on a small sample of the HGU-53/P data, but appears less reliable than was hoped.
- c. The midsagittal longitude is being estimated using the median longitude of the blue-colored spots. The original (FIT) algorithm used the average, which proved too sensitive to the nuchale and various noise points. The new algorithm works on many of a small sample of HGU-53/P subjects, but its reliability has not yet been quantified.
- d. The combination of algorithms b and c above has proved 100% reliable in correctly identifying the midsagittal longitude on the small sample of HGU-53/P subjects examined so far. The blackboard works since it successfully combines two knowledge sources to produce a better result than either one can obtain individually.
- e. Using the knowledge of the midsagittal longitude, an algorithm has been developed which reliably identifies the pronasale for any scan in which the head is approximately upright (Frankfort plane nearly horizontal). This algorithm has been tested on three scans from the minisurvey and a small subset of the HGU-53/P data, with very high reliability.
- f. An algorithm has been developed which uses knowledge of the midsagittal longitude and the position of the pronasale to assign blue-colored spots to midsagittal landmarks. The center of the spot closest to the identified pronasale position is added as a

hypothesis for the pronasale position. The closest spot above the pronasale spot is hypothesized to be the sellion, and the next spot above the sellion is hypothesized to be the glabella. If a midsagittal spot occurs below the pronasale, it is hypothesized to be the promenton. Surprisingly, a large percentage of the scans examined so far (possibly approaching 50%) appear to have problems with the promenton. Not too surprisingly, few scans have a detectable menton spot, and so far, no scans have detectable submandibular spots.

Future work will be to identify the remaining blue spots, probably using the statistical information developed for use with the constraint network.

After all blue spots are successfully being identified, work will turn to identifying other landmarks, such as subnasale (first minimum below pronasale?), supramenton (first minimum above promenton?), and stomion (minimum between two close maximums above supramenton and below subnasale?).

Dr. Pollack's plan for future Blackboard development appears as a report in Attachment 3.1.

ATTACHMENT 3.1

Areas for Additional Development of the Blackboard System

Short Term

- Add a constraint network, incorporating relationships between landmarks (the sellion is below the glabella, etc.), statistical data on those relationships (the min, max, average distances and standard deviation between the sellion and the glabella on previous scans) for use by the blackboard system. The network will help in determining the confidence that the system has in its hypotheses, and possibly it will also be used in the generation of new hypotheses.
- 2. Investigate the idea of separating hypotheses into latitude hypotheses and longitude hypotheses rather than posting a set of coordinates. This is due to the fact that some knowledge sources have expertise in finding either latitude or longitude but not both. Currently, these knowledge sources must post both coordinates, so they have to "make up" the one they don't really know about, not differentiating the confidence that they have in these two different coordinates. The Integrating Knowledge Sources, when looking at a hypothesis, cannot currently tell whether the latitude or longitude location was the focus of the knowledge source that posted it. This information should improve the performance of the Integrating Knowledge Sources.
- Develop and improve the Integrating Knowledge Source algorithms, and integrate the use of the constraint net into the algorithms. In addition, develop the ability of the Integrating Knowledge Sources to manipulate hypotheses - remove old hypotheses, alter confidence levels, etc.
- 4. Use bounding boxes (regions) rather than specific locations in hypotheses. The bounding box should be a class with a set of methods including SET, SAME_AS, INTERSECTION, IS_POINT, and possibly others.
- 5. Develop a list of strategies used to find each landmark.
- 6. Evaluate existing knowledge sources, modify as necessary, and develop new knowledge sources in the following areas:
 - Use patches more extensively to find landmarks
 - Use the constraint network to generate hypotheses
 - Use color data more extensively to find landmarks
- 7. Evaluate the use of differently colored patches on non-landmark locations to help in confirming landmark or region positions.

Intermediate Term

8. Regional Knowledge Sources - allow the system to focus on one area of the head, such as eye, mouth, etc.

Long Term

 Control Blackboard and Knowledge Sources - implement dynamic priorities, allowing the system to try different strategies, foci, etc. by monitoring the results of the problem-solving process.

Constraint Network

The constraint network will be an auxiliary data structure that is part of the blackboard data. There will be one node for each landmark, and they will be indexed by landmark number. Each constraint node will contain the following statistics:

	Neighbor	MaxDiff	MinDiff	AvgDiff	StdDeviation
Lat >					
Lat <					
Lon >					
Lon <					

In addition, each node will include a bounding box which will contain the current bounds of the region that must contain that landmark.

The concept of the constraint network is that each landmark will be linked to up to four different neighbors, which are those landmarks that are related to it in the following ways: (1) the nearest neighbor that must have a lower latitude, (2) the nearest neighbor that must have a higher latitude, (3) the nearest neighbor that must have a lower longitude and (4) the nearest neighbor that must have a higher longitude. For example, the pronasale would be linked to the subnasale, sellion, and possibly the right and left chelions. These relationships must be true 100% of the time, because these links will be used to propogate constraints from one landmark node to another. The bounding boxes in the constraint network will be "firm" information; we are confident with a very high degree of probability that the landmark location is within the bounding box. In contrast, bounding box locations in hypotheses are not firm; a knowledge source with only one strategy has posted a belief that the landmark is in that bounding box.

The constraint net will be used by the POST_HYPOTHESIS routine to help set the confidence value of each hypothesis. If the hypothesized location is outside the bounds of the boundary box in the constraint net node, it will have a very low confidence value.

It will also be used by a new knowledge source to combine the statistical data with known landmark locations to extrapolate the regions in which related landmarks should be found. Based on preliminary investigation, it is possible that the maximum and minimum differences may not be useful information because of (1) possible errors in the existing data, and (2) the extreme cases which make the regions defined by max and min too large to be useful. It may be more productive to use the average + 2 standard deviations (or 3 standard deviations if we want a higher probability of being correct) to generate bounding box hypotheses for linked landmarks.

Current Strategies for Locating Landmarks

1. RTragion

Define a region 10 lats above and 15 below infraorbitale and defined by infraorb longitude + 75 and the max number of radii in a region (MaxRadii). Look for a very negative slope toward the front of the region. (KS 66)

- 2. RZygion
- 3. RInfraZygion
- 4. RGonion
- 5. RMidlatInfrMan
- 6. RFrontotemp

Patch in a region defined by LFrontotemporale and glabella. (KS 84)

Patch in a region defined by glabella. (KS 80)

7. RZygofrontale

Patch in region defined by LZygofrontale. (KS 86)

Patch in region defined by RFrontotemporale. (KS 83)

8. RinfraMalar

Patch in a region defined by Linframalar. (KS 77)

Patch in a region defined by pronasale and stomion. (KS 67)

9. REctocanthus

Color data and pupil location. (KS 94)

10. REndocanthus

Color data and pupil location. (KS 93)

Neural net on a region defined by right infraorbitale (KS 70) (KS doesn't get called - doesn't work)

* REndo is posted based on LEndo and sellion (KS 64)

Lat slopes are used, with the sellion and glabella as reference points. The endocanthus lon is hypothesized to be 4 lats past the point at which the slope down from the nose stops.

* Endocanthus lat is hypothesized to be 7 below the sellion (KS 57)

11. Rinfraorb

Patch in a region defined by RInframalar (KS 68)

12. Glabella

Latitude of the highest max feature is located, then the patch nearest the midsag plane at that lat is picked as the glabella. (actually more complicated than that, but this logic will work once we know the midsag plane) (KS 60)

13. Sellion

Slope change above the pronasale. (KS 73)

14. Pronasale

Slope change above subnasale. (KS 75)

First max feature above the subnasale (KS 56)

15. Subnasale

Slope change above the stomion. (KS 74)

First min feature above the stomion (KS 55)

16. Promenton

Maxes, Mins and Patches are used to locate midsagittal plane and then the promenton is located by finding the longest Max feature (KS 52)

Menton

* Menton is 10 lats below the promenton (KS 54)

18. RChelion

Color data and stomion location. (KS 95)

* Rchelion is posted based on LChelion (KS 62)

First min at the stomion ion is followed to its end; chelion ion is hypothesized at the end of the min feature. (KS 59)

Lat slopes are used to locate chelion by working outward from stomion lon and following first positive then negative shopes.

* Chelion latitude is posted as stomion lat - 4. (KS 58)

19. Stomion

Slope changes in the area defined by midsag plane above promenton (KS 72)

* The Min feature closest to 23 lats above the promenton (KS 53)

20. LChelion

Color data and stomion position, (KS 91)

* Hypothesize Lchelion based on Rchelion position (KS 61)

First min at the stomion ion is followed to its end; chelion ion is hypothesized at the end of the min feature. (KS 59)

Lat slopes are used to locate chelion by working outward from stomion lon and following first positive then negative shopes.

* Chelion latitude is posted as stomion lat - 4. (KS 58)

21. Submandibular

Slope changes on the midsag plane below the promenton (KS 71)

22. Linfraorb

Patch in a region defined by RInframalar. (KS 79)

23. LEndocanthus

Left pupil and color data. (KS 89)

* LEndo is posted based on sellion and REndo (KS 63)

Lat slopes are used, with the sellion and glabella as reference points. The endocanthus lon is hypothesized to be 4 lats past the point at which the slope down from the nose stops.

* Endocanthus lat is hypothesized to be 7 below the sellion (KS 57)

24. LEctocanthus

Color data and left pupil location. (KS 90)

25. LMidlatInfrMan

26. LFrontotemp

Patch in a region defined by RFrontotemp and glabella. (KS 85)

Patch in a region defined by the glabella. (KS 81)

27. LZygofrontale

Patch in a region defined by RZygofrontale. (KS 87)

Patch in region defined by LFrontotemporale. (KS 82)

28. LinfraMaiar

Patch in a region defined by Rinframalar. (KS 78)

Patch in a region defined by the stomion. (KS 76)

29. LZygion

30. LinfraZygion

31	1	G	ากเ	on
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32. LTragion

Define a region based on Linfraorbitale; look for very negative slope toward the front of the region. (KS 69)

33. Nuchale

34. RPupil

Color data and sellion location. (KS 92)

35. RSupraEcto

36. RSupraPupil

37. RSupraEndo

38. LPupil

Color data in latitudes near the sellion. (KS 88)

39. LSupraEcto

40. LSupraPupil

41. LSupraEndo

42. SupraMenton

Supramenton is found using min features at lease 5 lats above promenton (KS 65)

TASK 4

...shall develop and evaluate sizing systems for new, modified, or existing items of personal protective equipment and clothing including some uniform items...The contractor shall develop estimated procurement tariffs (estimates of how many people will wear each size), and estimated size assignment criteria...

Helmet Mounted Systems Technology

Task HEG-1: Fit Envelope Definition

Headforms:

Although initially considered acceptable, continued examination of scans of the first headform received from Advent Programming indicated that the headform did not match the data files from which the headform was made. A careful review of the original data and the headform data revealed that a vertical inaccuracy in the scanning process was responsible for the incongruity between the sets of data. (This vertical inaccuracy may have been introduced when the new color system was installed in the scanner.) Because the vertical increment is a parameter of the original set-up file for the scanner itself, it was not possible to reset the parameter within that file. It was possible, however, to correct the increment in the header of each scan file by running the file through the software program, INTEGRATE. Once the vertical inaccuracy was corrected in the original scan files, it was possible to properly evaluate the accuracy of the additional eight headforms.

The eight headforms received from Advent Programming during the last reporting period were scanned and then visually compared to the data sets from which they were made. The headform scans closely match the original data sets.

HGU-53/P Fit Assessment

Background:

The Air Force is considering replacing the current flyer's helmet (HGU-55/P) with the HGU-53/P. This survey was conducted to test a modified sizing system for the HGU-53/P based on a laboratory fit test conducted with a civilian population at Wright-Patterson Air Force Base. The survey was also conducted in support of the design of next generation night vision goggles and helmet mounted displays which will be using the HGU-53/P as a platform. Results of the preliminary fit test at Wright-Patterson indicated redundancy in the sizing system; specifically, two of the helmet sizes (sizes 3 and 5) could accommodate the same population as well as the available six sizes.

HGU-53/P Preliminary Fit Test:

The objectives of the preliminary fit test were to determine: 1) whether any sizes can be eliminated from the sizing system, and 2) what anthropometry is key to size selection. The data analysis from the preliminary fit test resulted in a new size selection scheme that was incorporated into the HGU-53/P survey.

The data for subject 20 was dropped from the analysis due to biased responses. Therefore, the sample consisted of 50 civilian subjects.

Data Scores:

Each subject was tested in his/her T.O. (Technical Order) size, the next size smaller, and the next size larger. The resulting fit data from the questionnaire were used to score the sizes as either "pass" (the helmet fit) or "fail" (the helmet did not fit).

The data were then combined into an overall pass/fail score for each subject in each size tested. If a subject received a fail for any one of the above questions, then the overall score for that size was a "fail." In other words, for a size to pass, it had to get a pass for all the questions. Using these criteria, it was possible, in fact likely, for a subject to score a pass in more than one helmet.

Size Elimination:

Technical Order Sizing System

To potentially eliminate a size from the system, all subjects who received a pass in that size were arbitrarily assigned to another size in which they also received a pass. If a subject did not receive a pass in another size in the system, then the subject was considered "not accommodated" by the proposed new sizing system.

It was initially suggested that every other size might be eliminated from the sizing system. When sizes 2, 4, and 6 were eliminated, nine subjects were not accommodated. Examination of the data for those subjects showed that five failed in size 1, passed in size 2, but were not tested in size 3 because they wore T.O. size 1. We suspected that these subjects would have received a pass in size 3, so they were assigned to that size. Another subject who wore T.O. size 3, failed in sizes 2 and 3, passed in size 4, but was not tested in size 5. We suspected that this subject would have received a pass in size 5, so he/she was assigned to that size. The other three subjects did not receive a pass in any size in which they tested; these were the only subjects not accommodated by a system with sizes 1, 3, and 5. One of these subjects had extremely large head dimensions and failed in sizes 5 and 6. This suggests that another size which is larger than size 5 might be needed, especially since the dimension specifications for those sizes are identical.

Since none of the subjects who were not accommodated passed in helmet size 1, it is also reasonable to eliminate size 1 from the system. The final sizing system consists of sizes 3 and 5. A comparison of the original technical order and the modified sizing system is provided in Table 4.1.

TABLE 4.1

Comparison of Technical Order and Modified Sizing Systems

Modified Sizing System

Head Circumference (cm)	HGU-53/P Size	Head Circumference (cm)	HGU-53/P Size
53.34 - 54.61	1	< 55.0	3
54.61 - 55.88	2	> 55.0	5
55.88 - 57.15	3	·	
57.15 - 58.42	4		
58.42 - 59.69	5		
59.69 - 60.96	6		

Key Dimensions for Size Selection:

A bivariate plot of head breadth and head circumference showed that sizes 3 and 5 were well defined by head circumference. A single exception was a subject with a head circumference of 555 mm, who was assigned to size 5 in the midst of many size 3's. This subject, unlike most of the other subjects, was quite experienced with wearing helmets. It is reasonable to expect that this data are more representative of the data that will be gathered on pilots during future fit tests. It is also expected that many of the subjects assigned to size 3 above the 550 mark would have received a pass in size 5 had they been tested in it and had they been pilots. There is also the possibility that there is no real difference in fit between sizes 3 and 5.

HGU-53/P Survey:

Four bases were selected as test sights for the HGU-53/P helmet fit evaluation: Griffiss AFB, NY; Eglin AFB, FL; Hurlburt Field, FL; and Shaw AFB, SC. Ten to eleven subjects per day were scheduled at each of the first three sites, and eight per day at Shaw AFB. The evaluation team spent two weeks each at Griffiss AFB and Shaw AFB and one week each at Eglin AFB and Hurlburt AFB. The goal was to collect data on 250-300 subjects. However, due to difficulties encountered by the scheduler at Griffiss AFB, and a one-day shut- down due to equipment problems at Hurlburt Field, a total of 185 subjects were processed during the survey. Only one female participated as a subject.

Procedure:

Traditional Anthropometry:

Subjects were briefed as to the purpose of the survey and asked to sign a voluntary consent form. Following the briefing, the subjects were landmarked for traditional anthropometry of the head and face. Blue paper dots were placed over each landmark to be used for automatic landmark picking at a later time. Seventeen different dimensions were measured with no head covering, and five repeated after the subject was fitted with a bald cap.

The following landmarks were located on each subject:

Glabella Zygion
Sellion Infrazygion
Pronasale Tragion
Promenton Inframalar
Menton Gonion

Frontotemporale Mid Inframandibular

Zygofrontale Nuchale Infraorbitale Mastoid

Three-Dimensional Anthropometry:

Once the traditional anthropometry was finished, the subjects (wearing the bald caps) were scanned with the 3-D digitizer. A black cape was placed about the subjects' neck and

shoulders to eliminate any possible artifacts from their flight suits that would interfere with the automatic landmark picking procedure. The scanned image was viewed to determine whether the subject moved, and if needed, the scan was repeated.

Helmet Fitting:

Each subject was custom fit with a thermal plastic liner (TPL) by life support personnel from Brooks AFB. The fitting process involves heating the TPL in an oven until it begins to melt, and subsequently placing the TPL on the subject's head. The TPL is then covered by a fitting shell of the same shape as the inside of the HGU-53/P. A weighted ring is hung on top of the shell and kept in place for about two minutes in order to compress the layers of the TPL into the correct shape. When this process is complete, the edges of the TPL are cut to match the fitting shell, it is inserted into a cloth cover, and attached by Velcro inside the helmet shell. The subjects then donned the helmet to verify proper ear cup placement. Subjects whose head circumferences fell between 55 and 56 cm were asked to wear both sizes (3 and 5) of helmets to help clarify the position of the dividing line in the modified sizing system. Therefore, these subjects were fit with two different helmet liners.

Sound Attenuation:

Once satisfied with the ear cup placement, a sound attenuation study was performed with both the HGU-55/P and the HGU-53/P helmet. Sound attenuation was used as a fit indicator based on the premise that too little attenuation indicates that a helmet is loose on the sides of the head. The subject was asked to sit between two stereo cassette players placed at head level. Broad band noise was played through each stereo system at sound pressure levels (SPL) of approximately 110 dB. Baseline SPL measurements were taken at each ear while the subject wore only ear plugs. The subject was then instructed to don the HGU-53/P. At this time the noise level was measured inside each ear cup of the helmet. If the sound attenuation was deemed insufficient (i.e., SPL readings greater than or equal to 89 dB inside the ear cup), pads were added behind the ear cups of the HGU-53/P to create a tighter seal against the head. The measurements were repeated and then performed in a like manner with the HGU-55/P (no additional padding was added to the HGU-55/P). A set of Bose Active Noise Reduction (ANR) ear cups were installed into an HGU-53/P helmet at Shaw AFB and were tested with the ANR both active and passive. The active test was discontinued due to lack of proper equipment for realistic attenuation measurement (the microphone attached to the Sound Pressure Level meter used for measuring the noise levels was too large and interfered with the microphone used inside the ANR ear cups themselves).

Fit Evaluation:

Following the attenuation test, the subjects were asked to wear the helmet for fifteen minutes, at which time a fit evaluation was performed. The subjects were asked a series of questions regarding tightness and comfort of the shell and the earcups. A stability test was conducted by applying two pounds of force upwards from the helmet's rear edge roll. The magnitude of the deflection was measured on the forehead. Following the evaluation, subjects were asked to record any comments they had about the HGU-53/P, in general, and how it compared to their current helmet. Finally, subjects were scanned in the HGU-53/P and in their

the HGU-53/P shell before the scan so that they could be evaluated later in conjunction with the data from the unhelmeted scan.

Combat Edge Questionnaire:

A late addition to the survey was a questionnaire on the Combat Edge mask. This was initiated at Shaw AFB where 42 subjects had flown sorties with the mask. Those subjects were asked to identify the location of any hot spots they experience from the mask, at which points stickers were placed. These subjects were also scanned while wearing the Combat Edge mask.

Results:

Results of the HGU-53/P Survey were not compiled by the end of this contract period.

Task CFH-02: Concept VI Optical System Fit Assessment

Scheduling conflicts with the trained optical specialist who was to assist in the Concept VI fit assessment continued to delay the dry-run testing of that optical system. These delays prevented further work on this task under this contract.

Determination of the Preferred-Line-of-Sight

Although the needed equipment (the RK416 Pupil Tracking System and the Rose Imaging Surface Scanner) was identified, money was not available on this contract for its purchase. Therefore, work on this task was not completed by contract end.

Evaluation of the Advanced Technology Anti-G Suit (ATAGS)

Data collection for ATAGS was completed during this reporting period. Fit assessments were conducted on 54 pilots at Nellis Air Force Base, 20 pilots at Langley AFB and 65 pilots at Tyndall AFB. Demographic data from the first four test sites are presented in Table 4.2.

Changes in ATAGS Evaluation

Initial analysis of data from Randolph AFB and Laughlin AFB revealed the need to revise the rating procedure for ATAGS in order to distinguish between suits which did not fit in the waist, and suits which did not fit in the waist as well as in multiple other areas. Because the Technical Order (T.O.) for ATAGS states that suit fit is dictated by waist fit, any subject for whom the waist did not fit received a "5" rating. Therefore, a size rated "5" with a fit evaluation performed represents a non-fit by T.O. standards but does not necessarily suggest that major alterations would have to be made to that pattern in order to afford the subject an acceptable fit in that size. (In other words, the waist does not fit, but other areas of the G-suit do.) Accordingly, a size rated "5" with no evaluation performed represents a non-fit not only by T.O. standards, but also suggests that major alterations must be made to the pattern in order to afford the test subject an acceptable fit in that size.

TABLE 4.2

ATAGS Demographic Data

AIR FORCE BASE	FREQUENCY	PERCENT
Randolph	61	29.9
Laughlin	69	33.8
Nellis	54	26.5
Langley	20	9.8
Total	204	100.0
SEX	FREQUENCY	PERCENT
Male	200	98.0
Female	4	2.0
Total	204	100.0
	-	
RACE	FREQUENCY	PERCENT
White	200	98.0
Black	3	1.5
Other	1	0.5
Total	204	100.0
AGE GROUP	FREQUENCY	PERCENT
20-24	56	27.5
25-29	63	30.9
30-34	70	34.3
35-39	12	5.9
40-44	3	1.5

Changes in Sock Evaluation

A review of the data from Randolph AFB and Laughlin AFB also indicated the need to evaluate an additional dimension for the ATAGS sock. The unique shape of the sock made it too narrow for many subjects across the widest part of the foot. For this reason, a new dimension, Width at Foot Breadth, was added to the list of areas evaluated on the sock.

Both the revised "5" (or "unable to don") rating for the G-suit and the new sock dimension were incorporated in the data collection procedures at Nellis, Langley, and Tyndall Air Force Bases.

Analysis

Analysis of the ATAGS data was not performed under this contract due to the fact that data collection was completed only days prior to contract end.

TASK 5 ...shall fabricate three-dimensional forms of body segments...ranging from as small as a hand to as large as a whole body clothing manikin...

This task was largely inactive during the current contract period.

<u>TASK 6</u> ...shall maintain and update the on-line CARD anthropometric database...The contractor shall document how to use the modified database...

CARD Lab Function and Goals

This document presents overall observations and recommendations made by our subcontractor, Micah Systems, Inc., based on the interviews and analysis conducted at the CARD Lab. It is intended to provide guidance as the Lab takes subsequent steps in developing and adopting information technologies.

This report has been structured around the four highest level functions in the CARD Lab Enterprise Model. Problems observed in these functional areas have been addressed and approaches to solving them are proposed.

Provide Research & Services

- This functional area is at the heart of the Lab's mission. Much of the Lab's current efforts are in this area -- 13 of 31 lower level functions shown on the Function/Goals Matrix (see Appendix A) fall into this area.
- Many of the goals identified by Lab staff are aimed at improving and enhancing this functional area -- 28 of 42 lower level goals are supported by functions in this functional area. However, virtually all of the goals, if accomplished, will ultimately enhance the Lab's ability to provide research and services to its customer base.

- The Lab has numerous goals that would advance anthropology in general, and specifically contribute to the medical applications area. However, the Lab needs to do much more to accomplish these goals. Goals such as:
 - 2.3.3 Compare Surface of Objects
 - 2.4 Develop Finite Element Tools
 - 2.5 Develop Bio-Mech. Modeling
 - 2.6 Move Towards Virtual Reality

are receiving minimal functional support.

• We have identified five key leverage points in this functional area. [We define a key leverage point as a lower level function that supports the accomplishment of numerous and varied goals.]

<u>Function</u>	Goals Supported
1.1.1.1 Formulate Question	12
1.1.1.2 Hypothesize Approach	12
1.1.1.3 Prototype Approach	10
1.1.1.4 Test Method	10
1.1.6 Serve on Working Groups	22

Promote Lab

- This functional area is becoming a more important aspect of the Lab operation as DoD budgets shrink and dual use technologies are increasingly emphasized. The medical and healthcare industry is one in which there is a possible synergy with CARD Lab expertise and which is growing in importance in national policy considerations.
- The Lab is doing much to advance in this functional area. Advertising, participating on national and international working groups, educating users and designers, participating on standards committees, and delivering papers and presentations at conferences and symposia all contribute to promoting the Lab, even though the primary purpose of some of these functions is something other than promotion. However, the Lab should develop a service strategy (see Goal 4.1). Such a strategy is critical to the success of this functional area, but developing one currently receives minimal functional support; and no current function has that as a primary focus. A service strategy should guide the Lab's promotional efforts in terms of target markets and service offerings. Results of a survey of potential users are given in Appendix B.
- Many of the goals intended to enhance this functional area (goals under 4.0 Expand Market and Services) are receiving significant support. However, Goal 4.2.3 Educate Lab Personnel and Goal 4.6 Maintain Global Awareness are receiving minimal functional support. Of these two, Goal 4.2.3 Educate Lab Personnel, which is focused on training Lab personnel about the design process and what designers need, should, no doubt, be receiving more support given that it can have a significant impact on accomplishing the core mission of the Lab.

• We have identified one key leverage point in this functional area.

Function 2.2 Educate Users and Designers

Goals Supported

9

- Some activities undertaken by Lab personnel contribute to both functional area 1.1 Advance Anthropology and functional area 2.0 Promote Lab, even though they may only be shown in the functional area related to their primary purpose. These include:
 - Publish/Present Results
 - Serve on Working Groups
 - Establish Standards

Problem: The Lab does not have a defined service strategy (or "marketing plan") by which to guide the efforts at promoting the Lab. Without such a plan, the efforts of Lab staff and the allocation of resources will not be as focused as with a plan.

Recommendation: Take the steps necessary to accomplish Goal 4.1, the intent of which is to develop a strategy for providing services to Lab customers. This strategy should detail the markets, potential customers, and customers to be targeted, the services each of these may need, the approach to be followed in promoting Lab services to these customers, the resources required and the timeframe over which the marketing will take place.

Provide SW/HW Support

- This is an absolutely critical element of the Lab's operation. This functional area is not only a leverage point for goal accomplishment, it is also a leverage point supporting many of the other Lab functions. Information technologies, including computer hardware, software, databases, and access to communication networks, play a central role in the Lab's vision. And these technologies will only increase in importance with growth in the quantity and complexity of Lab data repositories.
- The Current System Assessment Matrix indicates a lack of integration. The Matrix shows two major computing platforms and two major DBMSs. Current tools support segmented user groups, with minimal cross over. For example, the Cockpit Accommodation users have their own system and the Fit Testing/Analysis users have their own system. Among other drawbacks, a lack of system integration typically results in:
 - higher system maintenance costs
 - more effort required to answer questions which cut across the enterprise
 - difficulty in incorporating new system functionality
 - difficulty in sharing data across the enterprise.
- Given the Lab's vision, mission and goals, the CARD Lab has taken an important step in issuing an RFP for an on-line system of anthropometric and human system interface data. However, this RFP did not stress the need for integration in the data system architecture.

The Lab should ensure that the proposed development effort results in an integrated data system.

• We have identified six key leverage points in this functional area.

Function	<u>on</u>	Goals Supported
3.1	Monitor Technological Trends	13
3.3.1	Determine Requirements	12
3.3.2	Evaluate & Select SW/HW	10
3.4	Develop I.S. Methods	14
3.5.1	Develop Routines	20
3.5.2	Develop Data Systems	16

- The Lab needs to evaluate and select an environment as a base for developing the new CARD Lab Data System. Components of this development environment include:
 - Computer Aided Software Engineering (CASE) Tools
 - Database Management System (DBMS) relational and object oriented
 - Computing Environment (Silicon Graphics)
 - Data Administration
 - Development Methodology.

The elements of this development environment should be selected to fit together and complement each other.

• Data Administration plays a very important role in the development environment. Data Administration is responsible for developing standards for data naming, ensuring adherence to those standards, eliminating synonyms, homonyms and redundant data elements, coordinating data naming across a project team or development group, and contributing to data analysis and design. Our review of a list of measurement numbers and titles in the CARD Database indicates that data administration is required. For example, we found the following:

1013	RACE-AFW68
1037	RACE-AFM67
1039	RACE-AFM65
1042	RACE-ARW77
1052	RACE-NAVY88
1053	RACE-ARMY88
1063	RACE-MINI

These all appear to be the same data element, race. If so, then only one field is required, not seven. Based on our brief review, this is not an isolated example.

• The Lab needs to develop plans for the migration from the VAX computing platform, which currently runs SAS, the RIM database management system, the CARD Database, and the Cockpit Accommodation Database. The Digital VAX computing platform and the

software and databases which run on the VAX are clearly very important to the Lab. Therefore, careful planning is required for the transition away from the VAX to ensure that there is a smooth migration to a new computing platform and that the computing requirements currently satisfied by the VAX platform continue to be met without interruption. This transition planning should be done in conjunction with the planning for the new CARD Lab Data System, to the extent possible. The target environment (including DBMS, hardware platform, etc.) for the new system should be identified before the migration of VAX systems is undertaken.

- Data collection is frequently done at sites remote from the Lab; for example, at an Air Force base while doing a fit study. The future integrated CARD Lab Data System should be designed to make this very easy. Mobile data entry routines should be designed around the same database management system and user interface as the integrated Data System. The integrated Data System should include an option for easy upload of data from the laptop.
- Information Engineering is a structured systems development methodology that has as its underlying purpose the development of systems that fit the business context. The boundaries of the business context can be documented in the form of a vision, mission, and goals of the enterprise, the functions performed by the enterprise, and the data required by the enterprise to perform those functions. We have prepared this level of documentation for the Lab in the form of the Mission and Goals Hierarchy and the Enterprise and Conceptual Data Models. The next steps for the Lab in using these documents to drive the development of an integrated data system are:
 - Complete the planning steps for goal accomplishment proposed in the Function/Goals Matrix. Doing so will help further define data requirements [to be reflected in the Conceptual Data Model (Appendix C)], as well as any new functions that need to be added to the Enterprise Model (Appendix D).
 - Carry data and process analysis and design to the next level of detail. See Figure 6.1 for an overview of the Information Engineering Approach that embodies the necessary steps.

Object Oriented Development:

- The Lab has shown some interest in object oriented development, primarily through the use of C++. While these techniques and tools may offer some advantages to the Lab, they are far from mature. Currently there is no strong integrated object oriented toolset commercially available.
- Using our knowledge of the Lab, we completed a quiz¹ designed to help determine whether object oriented database management or relational database management would be the

¹ Baum, David, "Object-oriented databases: Are they for you?," <u>Computerworld</u>, Vol. 27, No. 24, June 14, 1993, pp. 109, 116.

better choice for a given situation. The results of this quiz indicated that object oriented database management would be best for the Lab. The key issues in this consideration for the Lab were:

- storage and use of 3D images
- storage and use of design information from/for CAD, CAM, or CIM applications
- current use of object oriented development tools (C++).

We recommend that the Lab investigate both relational and object oriented database management systems to determine which best meets its requirements for data storage, retrieval, management, and processing. The evaluation and selection of database management systems should be done in conjunction with the evaluation and selection of supporting computer aided software engineering (CASE) tools.

The Lab Conceptual Data Model could be implemented under either of these approaches to data management.

 Below we have listed a number of leading object oriented methodologies and object oriented CASE tools². The Lab's investigation and selection of an appropriate development environment should include consideration of these object oriented alternatives, as well as object oriented database management systems.

Object Oriented Methodologies:

- Object Modeling Technique (Rumbaugh)
- OOD (Shlaer Mellor)
- ObjectOry (Ivar Jacobsen)
- Object Oriented Design (Booch)

Object CASE Toolsets:

- Objectory -- Objective Systems
- Rose -- Rational Systems, Inc. (Rose is tied to Booch methodology)
- TeamWork -- Cadre Technologies, Inc.

Problem: The Lab anticipates losing the Digital VAX computing environment by the end of 1993. As far as we know, the Lab has done little planning for the migration from the VAX to another computing environment.

Recommendation: Given the importance of the VAX computing environment to the Lab, it is absolutely essential that the Lab develop plans for the migration away from the VAX. However, the Lab should not develop these migration plans in isolation from the planning necessary to put in place the development environment for the new CARD Lab Data System. Two of the most important pieces

² Radding, Alan, "To methodology or not to methodology?," <u>Computerworld</u>, Vol. 27, No. 24, June 14, 1993, p. 114.

in this plan are the evaluation and selection of statistical analysis software and database management software.

Problem: The Lab's current information technology infrastructure is not integrated. In addition, the RFP for the new CARD Lab data system did not stress the need for integration in the data system architecture.

Recommendation: The Lab should take the necessary steps to ensure that components of any new systems are integrated. Figure 6.2 depicts the facets of integration of importance to the CARD Lab:

- system capabilities
- categories of data
- categories of users.

System capabilities and data resources should be designed so that they fit together seamlessly and are easily available to users, whether those users are accessing the system from within the Lab (internal users), from an external agency or organization (external users), or Lab personnel who are on TDY assignment for a survey or other Lab business (mobile users).

Manage Lab

- The use of a project management package (such as TimeLine) could improve Lab operations if it were used consistently and regularly to schedule the workload of all contractor personnel and if the resulting schedules were made available to Government and contractor personnel. These schedules could be used as the basis for communicating and agreeing upon Lab priorities and allocating the resources consistent with those priorities.
- We have identified two key leverage points in this functional area.

Function	<u>on</u>	Goals Supported
4.1	Manage Lab Budgets	39
4.2.2	Manage Workload	25

INFORMATION ENGINEERING APPROACH

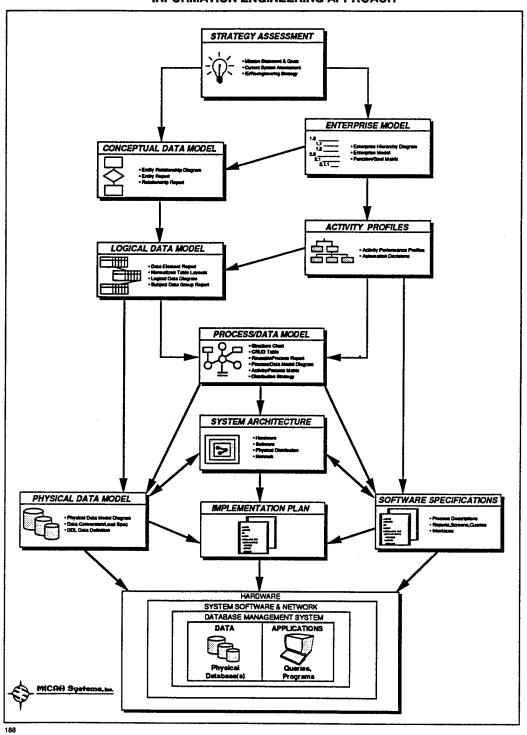


FIGURE 6.1
Information Engineering Approach

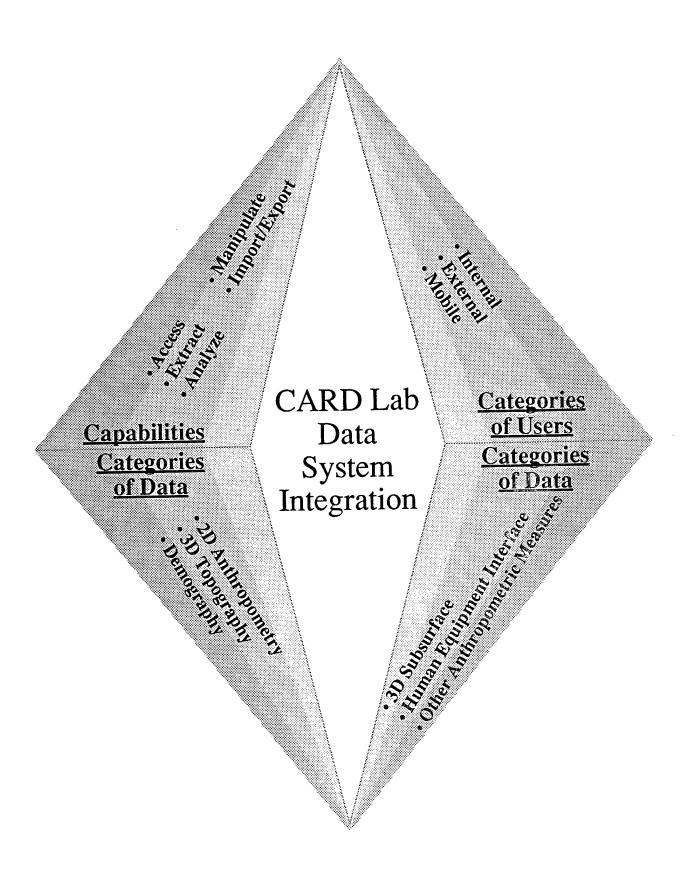


FIGURE 6.2

Facets of Integration

These functions clearly affect all aspects of the Lab and will be instrumental in accomplishing numerous goals. However, it is our assessment that the Lab needs to improve in this area, particularly in managing workload (Function 4.3.2). We further explore this issue in the following points.

- We have observed minimal support by this functional area for the following goals:
- Goal 5.1 Enhance Staff Skills
- Goal 5.2 Prioritize Lab Activities
- Goal 5.3 Improve Communications
- Goal 5.4 Improve Workload Management
- Most of the Lab "staff" are contractor personnel. Contractor personnel are basically organized as a general resource pool available to do work for any of the key Government Lab personnel.

Problem: The Lab appears to have minimal management structure. Contractor personnel are not well informed about the vision, mission, and goals of the Lab. They do not appear to know what the priorities of the Lab are. They appear to be pulled between extremes — at times not enough work to do, and at times too much work to do for several Government personnel.

Recommendation: Government Lab personnel should take the lead in instituting a Lab management structure that includes the following elements:

- agreement among key Government Lab personnel on Lab priorities, work assignments, and allocation of personnel resources
- clear and regular communication between Government and contractor Lab personnel regarding Lab priorities, work assignments, and allocation of personnel resources
- a clear definition of what is expected when a work assignment is given
- regular status reporting and accountability for the completion of work assignments, and
- an organizational structure that will alleviate some of the management problems the Lab has experienced. Below, we have presented several possible organizational structures.

Alternative Organizational/Management Structures:

- 1. Designate one of the 3 key Government personnel as Lab Manager. This person would coordinate all aspects of Lab operations:
 - budget and funding
 - regular communication sessions ("staff meetings") involving all contractor and Government personnel
 - staffing
 - work assignments and workload
 - etc.

- 2. Form permanent teams led by each of the key Government personnel, and staffed with contractor personnel. In addition, the Government personnel would form a coordinating team to coordinate all aspects of Lab operations (see above).
- 3. Form two teams, a coordinating team made up of the key Government personnel and a self-directed work team of contractor personnel. A self-directed work team is one in which team leadership and management is provided from within the team itself. As in #2 above, the Government coordinating team would coordinate all aspects of the Lab operation. The contractor self-directed work team would serve as a resource pool out of which temporary teams would be formed to meet a specific need (project, study, etc.) and disbanded when the need is satisfied. See Figure 6.3 for a diagram of this fluid organizational structure.
- 4. Appoint a contractor team member to act as "Lab Manager." This role would involve coordinating priorities, work assignments, resource allocation, and schedules between key Government Lab personnel and the contractor staff pool, and ensuring that regular communication sessions are held involving Government and contractor personnel.

Any of the above will work, but the key is discipline. Government Lab personnel must coordinate with each other regarding direction, priorities and resource allocation, and then must communicate with the contractor resource pool to staff projects, surveys, or tasks. However, we recommend that the Lab adopt option #3. Our assessment is that this structure would be best suited to the nature of the project work undertaken by the Lab and the personalities of the key Government personnel.

Summary Recommendations

Below we have summarized our major recommendations and conclusions, and listed them in the order of importance.

- 1. Introduce improvements in the Lab management/organizational structure.
- 2. Prepare criteria to guide the selection of a development environment. Evaluate, select, and acquire the development environment based on those criteria.
- 3. Develop plans for the migration from the VAX computing platform, based on the development environment.
- 4. Evaluate, select, and acquire statistical analysis software consistent with the development environment and the migration plans.
- 5. Execute the VAX migration plans to position the Lab for the loss of the VAX platform.
- 6. Complete the planning steps for goal accomplishment proposed in the Function/Goals Matrix document.
- 7. Using the newly acquired development environment, carry data and process analysis and design for the integrated CARD Lab Data System to the next level of detail.

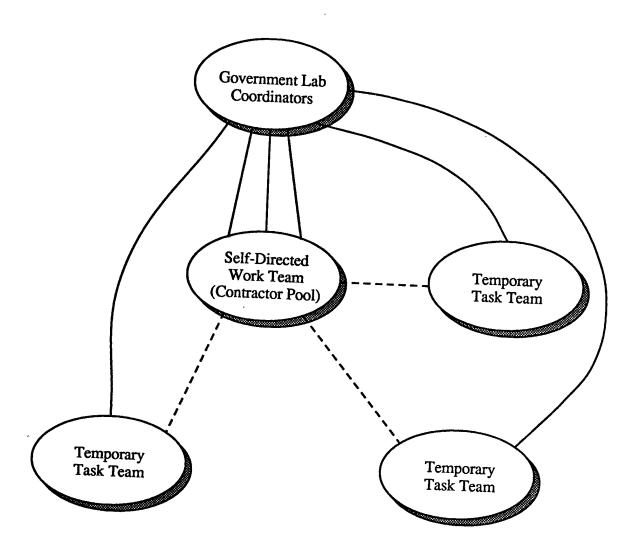


FIGURE 6.3

Lab Organizational Structure

Database Modification and Maintenance

ASCC

During this reporting period the female ASCC report was put on hold due to funding considerations. The current female ASCC report resides on FALCON in the directory ANTHRO\$DISK:[ANTHRODATA.TAPE.FEM]. This report was in LATEX format. Files in this directory include RIM database files which contain data for those surveys to be included in the report. Software to extract data from the RIM database and to format the data for LATEX reside in the files ASCC.FOR and SURVEY_STATS.FOR.

Cockpit Accommodation Database

Four tasks were identified in support of this project. These included completion of the CADB on the FALCON VAX, development of procedures for CADB use, and the rehosting of the CADB to a UNIX DBMS. Each of these tasks and their status will be discussed.

<u>Overview</u>

The CADB software currently on the FALCON VAX resides in the directory ANTHRO\$DISK:[ANTHRODATA.ACCOMDB]. Files in this directory and its subdirectories are identified as follows:

Directory ANTHRO\$DISK:[ANTHRODATA.ACCOMDB]

CACCOM1.DAT CACCOM2.DAT CACCOM3.DAT	These files are the MASTER RIM files for the CADB. The database name is CACCOM and the password is COCKPIT. Updates should be made to these files and new copies of these files transferred to where they are needed.
CACCOM1.SAV0393 CACCOM2.SAV0393 CACCOM3.SAV0393	These are the backup files for the CACCOM saved in March of 1993.
CACCOM1.NEW CACCOM2.NEW CACCOM3.NEW	These RIM files contain modifications to the VISION relation.
SCHEMA.DAT;1	CADB database SCHEMA

Directory ANTHRO\$DISK:[ANTHRODATA.ACCOMDB.INFORMIX]

This directory contains backup files for the CADB residing on the UNIX system in the CCCD lab. It is mostly here for archiving and for printing purposes.

Directory ANTHRO\$DISK:[ANTHRODATA.ACCOMDB.RIMDAT]

These files are the input files to the CACCOM database. These files are input into the database using the RIM LOAD and INPUT commands. Each file represents data for the associated relation.

Directory ANTHRO\$DISK:[ANTHRODATA.ACCOMDB.SASREG]

These are the SAS procedures used to produce the regression constants and coefficients entered into the database.

Directory ANTHRO\$DISK:[ANTHRODATA.ACCOMDB.SOURCE]

This directory contains the source code for the CADB applications interface program ACCOM. The RIM database is accessed using RIM FORTRAN interface routines. The user interface uses the VAX Screen Management (SMG) routine interface. This directory also contains a copy of the CACCOM RIM database file for software testing purposes.

ACCLIB.OLB	The FORTRAN library containing ACCOM subroutines
------------	--

ACCOM.COM Command file to compile and link ACCOM

ACCOM.EXE ACCOM executable

ACCOM.FOR ACCOM FORTRAN source code
AIRBLK.FOR ACCOM "include" common block file
AIRCRAFT_DATA.FOR Routines which retrieve data from database.

BLDALIB.COM Command file which builds ACCOM subroutine library.

C141_DESC.TEXT C-141 description text file.
C141_SEATADJ.FOR C-141 seat adjustment routine.

CACCOM1.DAT Local copy of CACCOM RIM database for testing

CACCOM2.DAT CACCOM3.DAT

COCKPIT WELCOME3.TEXT

CHGCODE.COM Command file for updating subroutine in ACCOM library

CLEARANCE.FOR Clearance subroutines

COCKPIT_WELCOME1.TEXT CADB program introduction text. COCKPIT WELCOME2.TEXT

CONTROL_DATA.FOR Subroutines to process control data information

CONVERT.FOR Conversion routines

DBACOM.FOR Database application "include" common block file

DESC.FOR Subroutines for aircraft description

F16_DESC.TEXT F-16 description text

F16_SEATADJ.FOR F-16 seat adjustment routine

HEADING.TEXT

LIST.FOR

QRYLIB.OLB

REACH.FOR

Subroutines to handle heading screens
Subroutines to list aircraft categories
Database application routine library
Subroutines handling reach data

SEAT.FOR Subroutines handling seat options
SELECT_AIRCRAFT.FOR Subroutines handling aircraft selections
SELECT_OPTIONS.FOR Subroutines handling menu options
The DESC TEXT.

T1A DESC.TEXT T-1A description text

T1A SEATADJ.FOR T-1A seat adjustment routine

T37 DESC.TEXT T-37 description text

T37 SEATADJ.FOR T-37 seat adjustment routine

T38 DESC.TEXT T-38 description text

T38 SEATADJ.FOR T-38 seat adjustment routine

VISION.FOR Vision subroutines

The CADB software being written on the Silicon Graphics Platforms reside in:

SG 4D/25 machine: nuthatch

Directory: /usr/people1/kevin/db

X-window Graphical User Interface (GUI)

Directory: /usr/people1/joyce/informix

INFORMIX cockpit database input files

Directory: /usr/people1/joyce/informix/code

Applications interface routines for the CADB

SG 4D/440 machine: v1sg16 (in CCCD laboratory)

user: card

password: cockpit1

The database files are stored in the dbspace designated by CCCD. These files may be accessed by using isql and requesting the database name cockpit. Default directory for user card is /dvp/people/card.

Completion of the CADB

Validation of database algorithms for the F-16A and C-141A:

We have found that this task is an ongoing task as new relationships of the data are identified through further analysis of the cockpit accommodation data. We are aware that organization of these data into an electronic database was not a consideration when data were collected. Often this has resulted in incomplete data for an aircraft. Although relationships between data types were identified and a database schema derived, we have found that due to the nature of the data it is often difficult to analyze the data routinely across all aircraft. For example, although description of seat adjustment parameters across all aircraft can be standardized, the actual positioning of the seat for each of the

subjects is aircraft specific. In this case, the need to code separate algorithms for each aircraft was a necessity although the actual seat adjustment parameters are retrieved from the database.

Existing database algorithms have been verified although these algorithms have also been updated since that time. Again additional analysis of the data identified the need to add an additional parameter into the VISION relation. This new parameter was added to a working copy of the database stored in ANTHRO\$DISK:[ANTHRODATA.ACCOMDB] in the files CACCOM1.NEW, CACCOM2.NEW, and CACCOM3.NEW. Updates to the vision algorithm to accommodate new parameters in the relation VISION have not been incorporated.

Entry of TRAINING A/C Measurements Into the Database:

Additional data have been entered into the database including the T-37B, T-38A, and T-1A data. Seat adjustment algorithms were also coded and incorporated into the database to accommodate the addition of these training aircraft.

Development of Procedures for CADB Use

The procedure for obtaining and analyzing cockpit accommodation data will be accessible through the rehosted database on the Silicon Graphics (SG) workstation. Currently a technical report is being reviewed which contains the procedures for the cockpit measurements taken. Upon completion of this report, the text will be electronically transferred to the SG and incorporated into the CADB. The Graphical User Interface (GUI) has been coded to allow for the insertion and access of this text on the SG. In addition to procedures text, allowance has been made to display an associated photograph to assist in the description of the measurement taken. These photographs need to be scanned into the Macintosh computer and transferred in GIF format on the SG.

PORT the CADB to a UNIX (SG Iris-Compatible) DBMS

Port the data to the new database:

The data from the existing CADB RIM database has been ported to the INFORMIX database resident on the CCCD SG 4D/440 workstation (v1sg16). This includes the schema definition (Appendix F) and the actual data from the RIM database as shown in Appendix F. Data was unloaded from the RIM database, reformatted into a command file, and loaded directly into the INFORMIX database using the file CPLOAD.COM as shown in Appendix F. The INFORMIX dbload command was used to accomplish the load. The INFORMIX database schema is shown in Appendix F. This schema was loaded into the database using the dbimport command. The data files used reside on the SG4D/440 in the directory /dvp/people/card.

Develop a user interface compatible with the CDS:

The Graphical User Interface (GUI) was developed using X-windows on the SG workstation. Currently this software resides on the 4D/25 (nuthatch) located in the CARD laboratory. This interface consists primarily of windows and menus which guide the user in selection of data from the database.

Currently the algorithms necessary for data reporting have not been coded. Routines to extract commonly requested data from the database into memory have been rehosted. Seat adjustment algorithms have also been coded but not yet compiled and tested. Database interface routines are included in Appendix E. While common variables to allow the GUI and the applications have been identified, the integration of these two subsystems has not been accomplished.

The following describes the location and functionality of the source code files, as well as an explanation of how the new Cockpit Accommodation Database interface works.

All source files used to create the GUI are found on nuthatch under the /usr/people/kevin/db directory. These source files are compiled to create the GUI using the makefile found in that same directory. They are found in Appendix F.

buildmenu.c is used to build popup, option, pulldown, and pullright menus, which are defined by declaring an array of menu item structures.

popupclearancemenue.c is used to pop up the overhead clearance menu.

setwidgetcolorscheme.c is used to set the color attributes of a given widget.

dataentry.c is used to create and manage the data entry screen, and pass information to the database querying code.

popupdataselection.c is used to pop up the data menu when the data button on the data entry screen is pressed.

displaypicture.c is used to display pictures when information is requested while processing the data button on the data entry screen.

displaytechinfo.c is used to display technical information about a selected data subject.

generatorport.c is used to create, display, and print report listings.

infowindow.c is used to contain textual information about a selected subject.

motifi.c is the main module of the GUI, and processes inputs to the main menu.

readtextfile.c is used to read textual information from technical data found in the textdesc subdirectory.

reportwindow.c is used to contain textual information of a report, and allows one to print the report to a hardcopy printer.

updateclearanceselection.c is used to update the current clearance selection.

utils.c is a collection of utility routines to destroy or find various widgets.

dataentry.h contains definitions used to drive the data entry screen.

typedefs.h contains various special types definitions.

menu.h contains menu structures used by the GUI.

constants.h contains definitions of constants used throughout the GUI.

The Database Introduction window is an information window created by infowindow.c. It is scrollable and is dismissed by clicking the left mouse button on the OK button.

The Survey Description display consists of three windows: a selection window, an information window, and a picture window (see Figures 6.4 through 6.6). To display information about an aircraft survey, one simply selects an aircraft from the selection window, and an information window as well as a picture window will be displayed.

The Data Entry window is used to gather data from the user for the Individual Body Type Fit Analysis. In this window the user enters various individual measurement data describing the Thumbtip Reach, Shoulder Height, Knee Height, Buttock-Knee Length, Sitting Height, and Eye Height. The user then selects an Aircraft, Crewstation, and either enters or has the computer compute the proper seat position based on the data entered. Once this data is entered, the user may select the Data button, and choose to view a variety of reports from a cascading menu. To dismiss this window, the user clicks the mouse on the Exit button.

Data Input Program

In order to facilitate analysis of accommodation data collected in the field, an effort has begun to automate input of data and formatting of that data for analysis using statistical packages such as SAS. A software program was written which allows for the input of raw reach data collected in the field. Actual field data for accommodation analysis of the T-38A aircraft was entered using this program.

This program was coded in FORTRAN. This prototype which resides on the VAX will ultimately be transferred to an MS/DOS personal computer which will allow for input of data in the field. This will eliminate the requirement to transfer data from handwritten data sheets to an electronic data format.

Program CINPUT allows input of both aircraft data and subject reach data. Aircraft data specifications must be entered first as this determines the information to be entered for each subject. Aircraft data includes input of aircraft crewstations, seat adjustment specifications, and reach control descriptions. Once the aircraft data is entered, subject data may be entered. The user will be prompted for each control by hand and by zone.

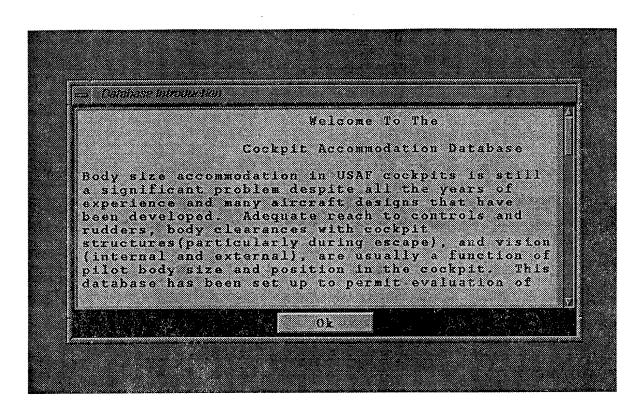


FIGURE 6.4
Selection Window

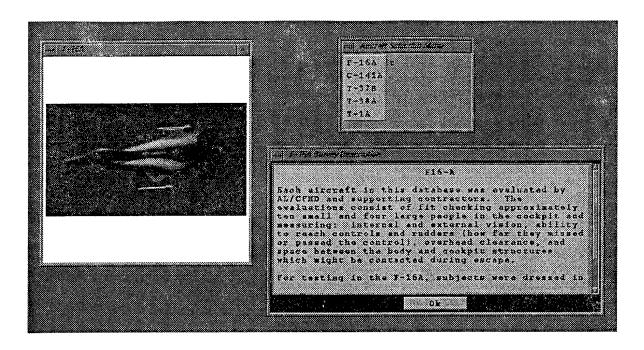


FIGURE 6.5
Information Window

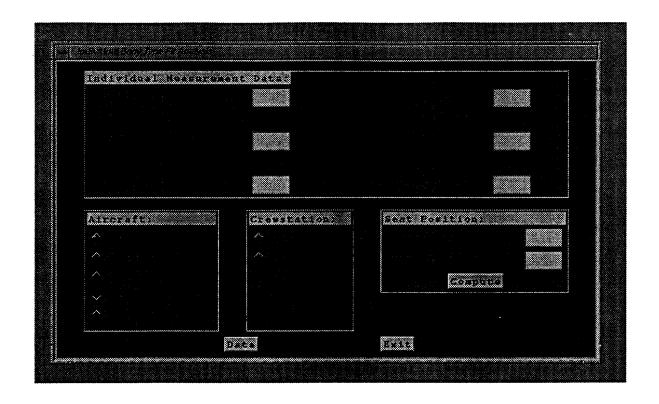


FIGURE 6.6

Picture Window

Code for CINPUT resides in the FALCON directory ANTHRO\$DISK: [ANTHRODATA.KEN]. Currently data for the T-38A aircraft also resides in this directory. The file T-38A.DAT contains aircraft specific data, and SUBJECT.T-38A contains subject raw data. A program listing and excerpts from the data files appear in Appendix G. A sample script for data input is also given in Appendix G.

T-38 Data

The T38 data is currently being reanalyzed. Those conducting the analysis have requested that a set of SAS and Fortran Procedures be developed that will enable them to do the analysis without assistance. In order to better understand the needs of the analysts, a set of procedures outlining the perceived analysis methodology were written and distributed to them. They also detailed the data and format currently needed to create regression coefficients using SAS for the cockpit database. These procedures are given below:

1. Gather data. Data records should be entered on disk in the following format:

SBJNUM CONT POS SIDE HAND ZONE SHLDRHT TTREACH

where SBJNUM is the subject number,
CONT is the instrument control number,
POS is 'FU' for Full-up,
SIDE is either 'FC' for forward cockpit or 'AC' for aft cockpit,
HAND is either 'LH' for left hand or 'RH' for right hand,
ZONE is either 'Z1' for Zone 1 or 'Z2' for Zone 2,
SHLDRHT is the shoulder height sitting in inches,
TTREACH is the thumb tip reach to the control in inches.

There should be for data files: 1) forward cockpit, left hand; 2) forward cockpit, right hand; 3) aft cockpit, left hand; 4) aft cockpit, right hand. Suggested names for these files are NFCLH38.DAT, NFCRH38.DAT, NACLH38.DAT, and NACRH38.DAT.

- 2. Edit and run a SAS procedure for each of the data files to get the data in SAS format. Suggested names for the new SAS datasets are NFCLH38, NFCRH38, NACLH38, and NACRH38. (These files will automatically be given the extension .SASEB\$DATA.) (See [anthrodata.crewstation.t38]create.sas).
- 3. Edit and run FL38REG.SAS, FR38REG.SAS, AL38REG.SAS, OR AR38REG.SAS to get predicted thumb tip reaches for test data based on existing T38 data. (Test data refers to the data that will be used to compare the existing T38 data to the new T38 data.)
- 4. Edit and run NFL38REG.SAS, NFR38REG.SAS, NAL38REG.SAS, and NAR38REG.SAS to get predicted thumb tip reaches for test data based on the new T38 data.

VAX Conversion Status

There is a possibility that the CARD database and SAS processing will be migrated to the CCCD VaxStation III/GPX. Previously the CCCD lab was operating two VaxStations, the III/GPX and a II/GPX. During this report period software from the II/GPX was migrated to the III/GPX. AL/CFHD is exploring the possibility of obtaining SAS for one of the VAX workstations and porting RIM to the same allowing for the porting of the CARD 2D database on one of these VaxStations. In order to determine the feasibility of the rehost, several factors will need to be studied including memory and storage requirements, cost factors, user accessibility and software compatibility. It is important to note, especially when determining third party software requirements, that the VaxStation III/GPX is a VaxStation 3100 CPU in the VaxStation II enclosure. This distinction will need to be made to any third party vendors to ensure software/hardware compatibility.

TASK 7

...shall perform cockpit and workstation body size accommodation analyses. This includes determining the minimum and maximum values of reach and clearance for safe operation and escape at each crew station, as well as quantification of the visual field...This shall include methodology, anthropometric measures to be taken, and a questionnaire directed at users of each crew station.

Accommodation Analysis

The final draft of an Air Force technical report entitled "Anthropometric Accommodation in Aircraft Cockpits: A Methodology for Examination" was completed during this past reporting period and is submitted under separate cover. Some additional work was done on expanding an outline of a plan to extend the cockpit accommodation effort to the remaining USAF inventory aircraft; this will require considerably more work, however, to become a full-scale proposal.

Re-Analysis of the T-38

At the request of the USAF, Dr. Kennedy travelled to Randolph Air Force Base, San Antonio, Texas to participate in a follow-on examination of the anthropometric accommodation offered in the cockpits of the T-38A aircraft. Travel was commenced on Sunday, 13 June and completed on Thursday, 17 June 1993. Mr. G. Zehner, 2d Lt J. Helfter, and 2d Lt G. Bailey participated in the evaluation. The following examinations were performed:

- 1. Overhead Clearance: 5 subjects
- 2. Operational Leg Clearance: 3 subjects
- 3. Ejection Clearances: 3 subjects
- 4. Rudder Pedal Operation: 9 subjects
- 5. Vision: 13 subjects
- 6. Hand Reach To and Actuation of Controls: 5 subjects

Evaluation of Computer Models

The final draft of a report entitled "Validating Computerized Human Analogues Used to Predict Cockpit Accommodation" was completed and appears here as Appendix I. This study, which made use of empirical accommodation data collected in an evaluation of the F-16A, was originally intended as a means of validating the COMBIMAN model. Very little actual COMBIMAN data was made available, however (beyond a series of Zone 2 reaches for the left hand to 13 controls on the main instrument panel of the F-16A). Thus, the report serves in part as an outline which can be used for this purpose if desired, and in part as the basis for developing a USAF Technical Report describing techniques for validating computer man models.

U.S. Navy Cockpit Accommodation Guide

At the request of Mr. Zehner, Dr. Kennedy reviewed a report entitled, "Procedural Guide to Aircrew Anthropometric Accommodation Assessment," by Scott A. Price, Systems Engineering Test Directorate, Naval Warfare Center, Patuxent River NAS. A copy of the review appears as Attachment 7.1.

Miscellaneous

A SAS program was written at the request of Mr. Zehner to compute regression equations using the ANSUR data to predict selected anthropometry from weight, sitting height, and leg length (derived from the summation of buttock-knee-length-buttplate and knee-height-sitting). The program also outputs predicted values plus and minus two standard errors for user-input dimensions. This program is given below:

```
LIBNAME HOME "HEG$DISK:[GZEHNER]";
OPTIONS LINESIZE=75;
DATA QUERYSET:
 SET HOME.ARW88WT
 (KEEP= M529 M195 M758 M805 M957 M122 M236 M230 M459 M378 M921 M852 M856
 M678 M751 M375 M25 M330 M1057);
 IF (M1057 GE 31);
 LEGG=M195 + M529;
 LABEL M195 = "BUTTOCK-KNEE-LTH-BUTTPLATE";
 LABEL M758 = "SITTING-HT";
 LABEL M805 = "STATURE";
 LABEL M957 = "WEIGHT";
 LABEL M122="SHOULDER-BRDTH";
 LABEL M236="CHEST-DEPTH";
 LABEL M459 = "HIP-BRDTH-SIT";
 LABEL M751 = "SHOULDER-ELBOW-LTH";
 LABEL M375 = "FOREARM-HAND-LTH";
```

```
LABEL M529 = "KNEE-HT-SIT";
 LABEL M852 = "THIGH-CIRC";
 LABEL M921 = "WAIST-CIRC";
 LABEL M856="THIGH-CLEARANCE";
 LABEL M678 = "POPLITEAL-HT";
 LABEL M1057="RANK";
DATA NEW;
 INPUT M758 LEGG M957;
CARDS:
32.8 40.0 103.0
32.8 40.0 138.0
31.0 38.9 92.0
31.0 38.9 136.0
34.9 49.8 131.0
34.9 49.8 205.0
40.0 52.1 151.0
40.0 52.1 245.0
38.0 52.7 151.0
38.0 52.7 245.0
38.5 43.3 123.0
38.5 43.3 194.0
DATA ALL;
 SET QUERYSET NEW;
%MACRO REDO(predict, dataset, yhat, mse, low, high);
PROC REG OUTEST=EST;
 MODEL &predict=M957 M758 LEGG;
 OUTPUT OUT=STATS P=&yhat;
DATA &dataset;
 SET STATS(FIRSTOBS = 200);
 KEEP M758 LEGG M957 &yhat MSE;
 &mse=\_MSE_
 &low=&yhat- MSE;
 &high=&yhat+ MSE;
RUN;
%MEND REDO;
DATA MERGE;
 MERGE TEMP1 TEMP2 TEMP3 TEMP4 TEMP5 TEMP6 TEMP7 TEMP8 TEMP9 TEMP10
TEMP11;
PROC PRINT;
RUN:
%REDO(M378,TEMP1,YHAT1,MSE1,LOW1,HIGH1)
%REDO(M122,TEMP2,YHAT2,MSE2,LOW2,HIGH2)
```

- %REDO(M459,TEMP3,YHAT3,MSE3,LOW3,HIGH3)
- %REDO(M230,TEMP4,YHAT4,MSE4,LOW4,HIGH4)
- %REDO(M236,TEMP5,YHAT5,MSE5,LOW5,HIGH5)
- %REDO(M921,TEMP6,YHAT6,MSE6,LOW6,HIGH6)
- %REDO(M852,TEMP7,YHAT7,MSE7,LOW7,HIGH7)
- %REDO(M856,TEMP8,YHAT8,MSE8,LOW8,HIGH8)
- %REDO(M678,TEMP9,YHAT9,MSE9,LOW9,HIGH9)
- %REDO(M751,TEMP10,YHAT10,MSE10,LOW10,HIGH10)
- %REDO(M375,TEMP11,YHAT11,MSE11,LOW11,HIGH11)

ATTACHMENT 7.1

TM 92-74 SY, "Procedural Guide to Aircrew Anthropometric Accommodation Assessment," (DRAFT) by Scott A. Price, Systems Engineering Test Directorate, Naval Warfare Center - Aircraft Division, Patuxent River NAS, MD, 20670, 13 October 1992.

Reviewed by: Kenneth W. Kennedy, Ph.D.

Consultant in Engineering Anthropometry
1420 Meadow Lane
Yellow Springs, OH 45387

The most puzzling characteristic of this document is that the body of the report does not contain as much information regarding technique as does Appendix I, "Quick Reference/Summary of Procedures." For that reason, the review of procedures is divided into three parts, TEXT, QUICK REF, and COMMENT; for information taken from the body of the report, from "Quick Reference/Summary of Procedures," and commentary regarding the appropriateness and usefulness of the procedures.

While this report is quite well written and informative, it does not show signs of having the benefit of broad experience: there are no nuances of procedure or recommendations that reveal themselves to be the results of experience in the aircraft cockpit, even though the author indicates that these procedures are the result of research and field testing experience originally conducted for NAVAIRSYSCOM and the T-45A program. All information could easily have been developed at the desk through reflection and by consulting with other personnel and reports.

The Test Center was tasked by NAVAIRSYSCOM to "develop new procedures for determining the ranges and limitations of anthropometric accommodation in military aircraft" in an operational environment. It is intended to enable the "establishment of Anthropometric Restriction Codes" to reduce the need for "fit checks, guide Student Naval Aviators into appropriate pipelines, determine contractor compliance, identify deficiencies in the crewstation layout of mockups and aircraft undergoing development." It is intended to be a stand alone procedure that can be performed without reference to requirements so that requirements do not "interfere."

NAVAIRSYSCOM no longer endorses the use of most Mil Stds to provide guidance in anthropometric accommodation. However, appendices to this report consist of summaries of Mil Stds 203G (Aircrewstation Controls and Displays: Location, Arrangement and Actuation of, for Fixed Wing Aircraft), 250D (Aircrewstation Controls and Displays for Rotary Wing Aircraft), 850B (Aircrewstation Vision Requirements for Military

Aircraft, 1333B (Aircrewstation Geometry for Military Aircraft), 1472D (Human Engineering Design Criteria for Military Systems, Equipment and Facilities) Mil-H-46855B (Human Engineering Requirements for Military Systems, Equipment and Facilities), Mil-C-81774A (Control Panel, Aircraft, General Requirements for). Data forms are also contained in Appendices.

Subject selection criteria is expressed in terms of percentiles, i.e., 5th and 95th percentile Naval Aviators. Crew members are considered optimum subjects. Recommends looking for close matches to desired anthropometric dimensions, although the values for these dimensions are not specified. Extremes should be sought, i.e., short/thin, short/heavy, tall/thin and tall/heavy - a minimum of four subjects. If time permits, another small and large subject should be added. If one or two more are allowable, they should represent the middle range of the population. Subjects in excess of eight should be spread throughout the range. Although Sitting Shoulder Height is recognized, almost as an afterthought, as second only to Functional Arm Reach to the understanding of reach capability, individuals on the high side for Sitting Shoulder Height, relative to their Sitting Eye Height, are not acknowledged as most appropriate subjects.

The report indicates that current methods of measurement differ from those used in the "outdated" Anthropometric Survey of Naval Aviators - 1964, as well as those used by other military services, contractors, and foreign studies. It is not reported how or why they differ nor is there a specific reference to an alternative source. If techniques and data differ, percent accommodation should be very difficult or impossible to acquire.

Anthropometric dimensions considered important consist of the following:

Sex
Age
Race
Stature
Weight
Sitting Height
Sitting Eye Height
Sitting Acromial Height
Boot Size

Functional Arm Reach
Hand
Functional Leg Length
Buttock-Knee Length
Sitting Knee Height
Bideltoid Breadth
Sitting Hip Breadth
Thigh Circumference
Lower Thigh Circumference

Blocking to a maximum of one inch is proposed for use in the measurement of overhead clearance, external and internal fields of view, functional arm reach, functional leg reach, leg clearance, and ejection clearance — in other words, all of them. The author proposes the use of Space Vector, a 3-D point location device to track relocation of body landmarks as a result of blocking. Primary areas for blocking are under boot and buttocks and behind lower back. Boot and butt blocks that are shaped to fit (the boot or the pedals?) are proposed. The author expresses caution in adjusting seat to simulate large and smaller body dimensions.

Proposes locating NSRP and SRPs for full up, full down, full forward, and full aft with regard to other aircraft hard points "to allow comparison against cockpit/crewstation design/specifications, aircraft configuration changes, and future AAAA test sessions." SRPs are, therefore, interpreted as hard points, which appears to go against previous USN policy. NSRP is determined from contractor diagrams and descriptions. USAF experience, when considering NSRP and SRPs as hard points has been less than satisfactory.

Proposes detailed statistical analysis "if sufficient number of subjects and data points are available." Cites use of Minitab, SAS, SPSS, STATA, and Systat for large amounts of data. Proposing these high powered statistical packages seems like overkill to me.

OVERHEAD CLEARANCE

TEXT: Clearance above and to the sides of the head are measured.

QUICK REF: Clearance evaluation includes tilting the head left and right to increase over-the-nose and over-the-side external fields of view: twisting the torso, neck, and head around for aft field of view.

Measurements performed at multiple seat positions and with blocking.

COMMENT: These procedures suffer from indecision with regard to purpose. Are they for determining if a given subject is accommodated in a cockpit or to measure the maximum Sitting Height that can be accommodated? Measurement is made at different seat adjustments so one is led to believe that maximum accommodation is sought. However, since the inclusion of the amount of additional downward seat adjustment is never considered in such determinations, there is some uncertainty. But why measure in different seat positions, beginning with, i.e., full down?

There are no specific instructions to measure parallel to ejection rails or seat adjustment line.

I question the usefulness of blocking when measuring Overhead Clearance.

EXTERNAL FIELD OF VIEW

TEXT: Proposes to measure vertical limits of lines-of-sight straight ahead (zero azimuth) and at selected, although not specified here, angles left (port) and right (starboard). Uses an "optical protractor" to attain selected azimuths. Field of View Evaluation Apparatus (FOVEA), which is controlled remotely, provides detailed azimuth and elevation "maps" of external field of view from DEP or alternative eye positions.

QUICK REF: Begin with seat full down and, as appropriate, aft. Consider various head positions for external field of view, flight demands, and use of controls. For example, head in Frankfort Plane, tilted to left and right, and bending body to left and/or right for over-the-side external view and take external field of view elevation measurements at selected azimuths.

Azimuths include straight ahead (0 degrees), 20-30 degrees right and left, over-the-side right and left, aft right and left.

Repeat measurements with blocking and at predefined seat positions.

COMMENT: Many of the same comments regarding Overhead Clearance apply here as well, especially those having to do with purpose and blocking. There are no recommendations regarding the "predefined" seat positions that are called out or defining the location of the eyes in alternative head positions.

INTERNAL FIELD OF VIEW

TEXT: Includes visual access to HUD - the sight bundle or "porthole." NAVSYSCOM appears to have developed the capability to define "Instantaneous Field of View, Total Field of View, and Biocular Instantaneous Field of View" using a photographic process. Obstructions to vision are also diagrammed. See paragraph 109.

QUICK REF: Drawings of the display panels are shaded to define areas of obstruction. Begin with seat full down. Use different head positions and tilts representative of aircrew needs, flight demands, access to HUD, and use of crewstation controls. Same head, neck and torso movements are allowed as for External Field of View. Note each instrument, display, and control, the percentage of its useful surface area obstructed, etc. 3-D coordinates of eye are determined during fore and aft motion of the head to access the full display offered by the HUD. Repeat with blocking and seat positions.

COMMENT: Same as for External Field of View.

FUNCTIONAL ARM REACH

TEXT: Acknowledges importance of Thumb-Tip (Functional) Reach and Sitting Shoulder Height. Dimensions of secondary concern are Downward Vertical Reach, Upward Vertical Reach, Bideltoid Diameter, Shoulder Elbow Length, and Hand Length. Since this is a general procedures document, i.e., including application to helicopters and larger flight decks, it acknowledges that overhead controls favor higher shoulders. Also acknowledges that controls to the right of the centerline of the main instrument panel may have to, on occasion, be reached by the left hand. The attempt is made to derive the percent of total excursion of controls with large ranges of motion, i.e., throttle and control stick,

possible with "X" value for Thumb-Tip Reach - also that full excursion of such controls may never be used. There may be a point beyond which there is not additional effect. How this is determined is not discussed.

When measuring miss distances, a measurement is made from the interface point on the control to the appropriate interface point on the hand. They also attempt to measure surplus reach distances, although in most cases we have found this to be difficult to impossible since the hand would typically have to be pushed through the plane of the instrument panel. In an apparent contradiction to these instructions, the author proposes that "Surplus distances, as well as miss distances, are measured from a specified area on the forearm . . ." — a reference band about five inches above the wrist. He also proposes the alternative of premeasuring the distances from the "reference band" on the forearm to the interface points on the hand. I get the impression that the latter procedure is used only when there is surplus reach capability. Does not appear to really use the reach subject as a "tool" for calculating Equivalent Thumb—Tip Reaches.

Reach is evaluated using three undefined seat positions.

QUICK REF: Functional reach testing determines the degree to which a person can properly, efficiently, and comfortably reach and actuate a hand control. Acknowledges worst case combination of small Thumb-Tip Reach and relatively large Sitting Shoulder Height.

The author proposes using drawings of the instrument panels to "make notes and shade in obstructed areas." The initial seat position is full down. Zones 1, 2 and 3 measurements are made as described in Mil Std 1333. Miss distances are measured between the interface points on the hand and control. Surplus reaches are measured from the reference band around the lower forearm - apparently as USAF does it.

Additional seat positions and blocking are used.

COMMENT: We found that measuring to the actual interface point on the hand in the cockpit when reaching toward a control was physically difficult, subject to paralax error, and uncertain as to accuracy of palpation. The latter is especially true with regard to the grip and hook. The author appears to propose USAF techniques only when measuring excess reach capability.

There is no discussion of data analysis so whether or not the author proposes to calculate a minimum Thumb-Tip Reach to access a given control is uncertain. Even though Mil Std 1333 definition of reach Zone 3 is included in the discussion, a technique for measuring it is not.

FUNCTIONAL LEG LENGTH

TEXT: Anthropometric dimensions include Functional Leg Length, Buttock-Knee Length, Sitting Knee Height, and Boot Size.

Does not describe foot-boot contact with pedals, although miss distances are measured from the pedal to the center of the heel. Seems to confuse purpose of measuring pedal access with acceptability of subject and the minimum length of leg that can operate pedals. Appears not to be most concerned with the latter.

QUICK REF: Although acknowledges that leg reach is usually a concern for smaller subjects, the proposed starting seat position is full down and aft and pedal carriage full aft. Miss distances are measured from the "underside" of the boot (footwear) to the interface point on the foot control. Reference is made to "surplus" distances, but I am uncertain if this term applies to the subject having additional reach capability or if the pedal can be pushed farther forward.

Procedures are repeated at "additional," but undefined seat positions and with blocking.

COMMENT: Some uncertainty regarding purpose of measuring. Is it to evaluate a specific subjects accommodation, or to measure minimum population accommodation? How "predetermined" seat positions are established is not described.

LEG CLEARANCE

TEXT: Procedures pretty much parallel those of USAF, except that optimum seat and rudder carriage positions are only conditions under which clearance with cockpit structure is observed and measured. Blocking for Butt-Knee and Knee Height is proposed, but would appear to be used only in the subject's chosen seat/rudder positions.

QUICK REF: Primary body dimensions are "functional leg length, buttock-leg length, sitting knee height, boot size, thigh circumference, and lower thigh circumference." Measurements are taken with carriage initially at full aft position, then at increments along its range of motion - and repeated with blocking.

COMMENT: A difference with USAF procedures in that the carriage is adjusted to positions not chosen (or appropriate) for the subject. Data, therefore are gathered at carriage adjust positions inappropriate for the subjects body size, real or obtained through blocking. Buttock-Knee Length is not acknowledged as important in leg clearance. Again, "appropriate" seat positions are proposed without further discussion of "why."

THIGH GAP

TEXT: Thigh Gap measurements are made for comparison with injury records "to determine if thigh gap may be excessive." Also considered a measure of general sitting comfort.

Dimension is measured from hard seat pan edge to underside of the thigh "perpendicular to the femur." Seat and pedals are adjusted "to provide comfortable access to full pedal actuation." Measurements are taken "throughout full pedal motion," i.e., neutral, full forward, and full brake rotation at full forward pedal. The "fleshiness" of the highs before bone contact apparently is somehow considered. Uncertainties "are partially countered by using same set of subjects on all aircraft to be compared." This [of course] "minimizes anomalies between subjects." Thigh gap is measured for informational and comparison purposes only.

QUICK REF: Important body dimensions include "functional leg length, buttock-knee length, sitting knee height, thigh circumference, and lower thigh circumference."

COMMENT: None.

EJECTION CLEARANCES

TEXT: Recommends seat pulls.

QUICK REF: Proposes seat pulls from more than one "predefined seat position" and with blocking.

COMMENT: Does not discuss the uncertain and loose relationships between these static measurements and the dynamics of an actual ejection. I cannot perceive the advantage of taking measurements while pulling the seat up the rails versus USAF procedures. I question the value of using blocks,* presumably behind the lower back, to simulate the effect of increased Buttock-Knee Length. No discussion of shoulder and elbow clearances.

* NOTE: On all occasions in which blocking is proposed to simulate larger body dimensions, and there are many, there is no discussion of observing the ranges of values for Buttock-Knee Length or Sitting Knee Height.

TASK 8 ...shall perform statistical analyses and comparison of a sample of 500 USAF fliers, 500 Navy fliers, and 9,000 Army soldiers...to determine if the three services can share large anthropometric data pools...

This task was inactive during this reporting period.

...shall develop statistical techniques for the summarization of three-dimensional shape data which is being gathered on the human body...The eventual goal of this research is to be able to describe and summarize the variability in the shape of the human body, and create summarized (or composite) body forms.

This task was inactive during this reporting period.

...shall develop a graphical design package to facilitate the use of 3-D data collected during the survey...including an "anthropometric clothing pattern production" tool...a "fit checking" tool...and a "customized fit" tool...

This task was inactive during this reporting period.

...shall investigate methods for determining the relationship between dexterity performance and hand and wrist size, shape, and kinematics...

Work under this task was not initiated.

TASK 12 ...shall use existing software, the on-line CARD Database, and AAMRL human mass distribution and volume data...in the solution of specific applied design problems as required by the Air Force...

Evaluations of Commercial Hardware and Software

CARD Laboratory Hardware

During this last reporting period the CARD laboratory relocated. Prior to the move, data on the Silicon Graphics workstations were backed up. Transceivers were obtained which allowed for the connection of the Silicon Graphics computers to the ethernet network. Personal computers were also connected to allow for access to the network by laboratory personnel.

A problem with the ethernet dropping out was identified and called into Silicon Graphics. Support of this call within the laboratory has been turned over to Lou Storey, LTSI.

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	В	Measurements	2
	С	Repeatability Study Exit Questionnaire Measurers/Markers	2
	D	Repeatability Study Exit Questionnaire Subjects	2
	E	Repeatability Study Exit Questionnaire Recorders	2
	F	Univariate Statistics	4
	G	Finished Measurements of Coveralls EAFFS and 66/P	4
	Н	Data Forms	4
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APPENDIX A FUNCTION/GOALS MATRIX

The purpose of the attached Function/Goals Matrix is to cross reference the goals of the Lab with the functions that support the accomplishment of those goals. Goals are documented in the CARD Lab Mission and Goals Hierarchy, while functions are documented in the CARD Lab Enterprise Model.

The following points are important for understanding the Matrix.

- When looking at the Matrix, goals are listed along the left side of the page while functions are listed along the top.
- The matrix represents support for goal/sub-goal accomplishment by the lowest functional level from which that support comes. Although not shown on the Matrix, goal support "bubbles up" through the hierarchy of goals and functions.
- The evaluation behind the check marks is admittedly subjective. This set of check marks is our assessment of functions which have <u>historically</u> supported or <u>currently</u> do support the accomplishment of the goals.
- A check mark in a given Matrix cell does not imply any level of strength
 of support. It only indicates that the function does, to some degree,
 support goal accomplishment. For many goals, significantly increased
 support is required to accomplish the goal and thereby improve Lab
 performance. It is very difficult for us to assess the strength of support for
 goal accomplishment, given that time horizons were not attached to the
 goals and that measures have not been developed to monitor progress
 toward goal accomplishment.

The following steps can be followed to improve the overall operation of the Lab by accomplishing the goals:

- Prioritize the goals and identify those most vital to the success of the Lab.
- Establish a time horizon for the accomplishment of each goal. For example:

short term — under 1 year medium term — 1 to 3 years long term — over 3 years.

- Assign responsibility for each Lab functional area and set of goals.
- The individual(s) responsible for each Lab functional area should assume ownership for the accomplishment of the goals supported by the functions in that area.

- The goal owner(s) should develop a plan to accomplish the goal over the established time horizon.
- Develop a mechanism to measure and monitor goal accomplishment.
 Such a mechanism provides the goal owner, and other interested parties, with the capability to determine what progress has been made toward the accomplishment of a given goal. The mechanism, typically one or more measurable items for each sub-goal, is designed to answer the question: "How can we tell when this goal is achieved?"
- Publish periodic memoranda reporting progress toward goal accomplishment.

We will document our observations concerning the Lab goals and the current support provided for goal accomplishment in the Project Final Report.

	Ouestion e Appros	ypothesiz	rototype pproach	Test Test Method	Acquire Data	Analyzo li Data n	11.1.4 Pub 1.1.5 Hish/Prose Establish nt Results Standards	Establish Standards	Serve on Working	Assist With Req.	articpate Evaluate in Brieffn Proposals		Serve f	fy Opport	Educato Users	Advertise
		1							Groups		.	-	Witness	- -	Dosigners	
1 Exnand Denth of Data Pool	/	7	>	7	7	7	>	>	>				7			
1.2 Expand Breadth of Data Pool	7	>	7	>	>	>	7	7	7				7			
13 Maintain Data Currency					7	7	>									
2.1.1 Improve Fit Ouantification	>	>	>	>		>			>						\	
2.1.2 Develop New Fit Methods	>	>	>	>		>									>	
2.1.3 Define Fit Procedures							>	>	>	>					>	
2.2.1 Improve Data Accuracy	7	>	>	7	>				>							
2.2.2 Increase Acquistion Speed	>	>	>	>	>				>							
2.3.1 Improve Shape Methods	>	>	>	>					>							
2.3.2 Develop Auto Landmarking	>	>	>	>												
2.3.3 Compare Surface of Objects	>	>														
3.4 Develop Data Use Methods	>	>	>	>					>							
2.4 Develop Finite Element Tools	>	>													6	
2.5 Develop Bio-Mech. Modeling									>							
2.6 Move Towards Virtual Reality																
valuate/Select Methodology																
3.2 Develop Integrated Toolset																
3.3.1 Provide Data Accessibility					>											
3.3.2 Provide Tool Accessibility																
3.3.3 Provide On-Line Help												1				
Provide Mobile Data Entry																
3.3.5 Develop GUI																
3.3.6 Provide Graphical Displays																
3.4 Enhance Information Network								,	Ì							
3.5.1 Develop Data Standards								>	>							
3.5.2 Design Data Representation												+				
3.5.3 Develop Data Reduction									,							
3.6 Keep Current with Technology									7					,		
4.1 Develop Service Strategy								,	>	,	Ĭ,	,	,	>	,	,
4.2.1 Influence Procurement								>)	>	7	7	>	\	7	7
4.2.2 Educate/Train Designers									>	>	>	>	1	7	7	
4.2.3 Educate Lab Personnel									>	,	>	,		ľ	,	ļ
4.2.4 Expand Role in Design									>	>	>	>		>	>	7
4.2.5 Promote Advances							>	>	>		>		7			7
4.3 Raise Awareness of Lab							\		>	7	>	>	>	>	/	7
4.4 Enhance Service Offerings	7	7	7	}	7				>	>	>	>		7	>	
4.5 Enhance User Support									>	>	>	>			>	
4.6 Maintain Global Awareness									>							
5.1 Enhance Staff Skills									>							
5.2 Prioritize Lab Activities																
5.3 Improve Communications																

	3.1 Monit	32.1	2.1 3.2.2 Mo	3.23 3		332	333	3.4	3.5.1	3.52	3.6	4.1		422	4.3 Mana
		Maintain User Base		-	ermine K oquireme nts	Select SW/HW		Develop I.S. Methods	Develop Routines	Develop Data Systems	V2	Manage Lab Budgets		Manage Workload	Sponsor Manage ge Facilii Training Workloades/Equip ment
1.1 Expand Depth of Data Pool												\		>	7
1.2 Expand Breadth of Data Pool												>		/	\
1.3 Maintain Data Currency			i									7		>	7
2.1.1 Improve Fit Quantification		-						>	>			>		>	
2.1.2 Develop New Fit Methods												7	:	>	
2.1.3 Define Fit Procedures		j		-								>		>	
2.2.1 Improve Data Accuracy					7	>	>	\	>	>		7	+ :	/	\
2.2.2 Increase Acquistion Speed					/	>	>	>	>	7		7		>	7
2.3.1 Improve Shape Methods				.			ļ	>	>	7		>		>	
2.3.2 Develop Auto Landmarking								/	>	>	7	>		>	
2.3.3 Compare Surface of Objects								7	7		>	>		>	
2.3.4 Develop Data Use Methods	7						- 	7	>	/		>		>	
2.4 Develop Finite Element Tools							-	7	>			7		>	
2.5 Develop Bio-Mech. Modeling												>	:		
2.6 Move Towards Virtual Reality	7			1								7		ĺ	
3.1 Evaluate/Select Methodology	7				7	7		7				7	\		
3.2 Develop Integrated Toolset	>				>	/				>		\	İ		
3.3.1 Provide Data Accessibility	7	/	7	7	7	7	>		>	7		>		>	
3.3.2 Provide Tool Accessibility	>	/	7	7	>	>	>		>	>		>		>	
3.3.3 Provide On-Line Help									>	>					
3.3.4 Provide Mobile Data Entry	7								7		>	7			
3.3.5 Develop GUI	7				7	7		7	>	\		7		>	
3.5.0 Provide Graphical Displays	7	-							/	7					
3.4 Enhance Information Network	\ \				7	\ \	7		7	7		7		>	
2.2.1 Develop Data Statitudius	۱,		-		\			,	,	,					
3.5.3 Develor Data Reduction	\ \						+	7,	/	7		7		7	
3.6 Keen Current with Technology	\			-	1	1		7	\	\		7	\	:	
4.1 Develop Service Strategy			1	-		>	-					\ز\	<u>}</u>		
4.2.1 Influence Procurement												\		\	
4.2.2 Educate/Train Designers											>	1	-	İ	
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4.2 Enhance User Support			\		7	7	7	7	\	\	\	>		>	
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5.3 Trioritize Lab Activities			_									\		}	>
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APPENDIX B SURVEY RESULTS

This document presents our analysis of the responses to the Questionnaire For Potential Users of the CARD Lab Data and Services. We received thirteen (13) completed survey responses from external organizations, and one from inside the Lab. This level of response was much less than we expected. A more extensive distribution of this Questionnaire would have provided more responses, and correspondingly, a better basis for understanding the requirements of current and prospective Lab customers.

The following external organizations provided responses:

- AL/CFBV (2)
- Sytronics, Inc.
- Bose Corp.
- Systems Research Lab
- Rose Imaging
- ILC Dover, Inc.
- Lockheed Fort Worth Division
- U. S. Army Natick RD&E Center
- Naval Air Warfare Center Warminster (2)
- GEC Marconi Avionics, Ltd.
- ITT

We have attached a copy of the Questionnaire, with the responses tallied and all relevant comments listed. These summarized responses provide insight into respondents' requirements for:

- import and export data formats
- network access
- categories of anthropometric data
- analytic capabilities, and
- other assistance and support.

These responses will prove useful as input to subsequent analysis and design steps for the integrated CARD Lab Data System. For example, the Lab should determine which of the import and export data formats are to be included in the scope of the Data System, thoroughly analyze those formats, and design the Data System to accommodate the formats. Likewise, the responses on the categories of data will be useful in designing data access paths.

Based on our analysis of the summarized responses we have concluded that there is **no impact** on the "First Cut" Enterprise and Conceptual Data Models.

Under separate cover, we have enclosed the original completed survey responses.

Note: Due to overlapping answers, survey responses for a given question can not be accumulated to arrive at the total number of surveys returned. For example, there are more responses for "Principal Occupation" than the number of surveys returned due to one or more respondents categorizing themselves under multiple occupational categories.

— Summarized Responses — QUESTIONNAIRE FOR POTENTIAL USERS OF THE CARD LAB DATA AND SERVICES

			Date:		
Background				M D Y	
Name Organization Organization Address					- - -
Country Phone	()				-
Principal Occupation	(Check appropriate box))			
Applications					
	currently engaged in or h tric and/or 3D surface or				
Design of prosthetic	ctive equipment/clothing netic devices gery ications (<i>list</i>)	8 3 7 1 1	Design of coor Design of wor Computerized Physical hum Automated m Custom manu Other (<i>List</i>)	rkstations d human modeling an modeling anufacturing	8 5 7 7 2 4
Cranial/facial surge		1		olications research	1
				et mounted display et mounted night ggles	1

CARD LAB QUESTIONNAIRE

Page 2

Computer and Communications Capabilities

CASE tool software?

	386/486 personal computers Macintosh personal computers Other personal computers (<i>list</i>) 286 personal computers	14 7 _ 2	VAX mainframe IBM mainframe Cray mainframe Other mainframes (<i>list</i>) Convex	7 2 2 1
	Silicon Graphics workstation Other graphics workstations (<i>list</i>) DEC workstation	- 10 5	Other (list) HP 9000 Server	_ 1
	Sun Sparc	8		
	Apollo Prime	1		
2. [/	Do you generally have access to the for nardware or package(s) used.)	ollowing	? (Check all that apply, and list th	ne
2. [<i>l</i>	nardware or package(s) used.)		? (Check all that apply, and list th	ne
2. [/	Electronic mail network daily?	12 _	? (Check all that apply, and list th	ne
2. [Electronic mail network daily? Graphics workstation(s)?	12 <u> </u>	? (Check all that apply, and list th	ne
2. [/	Electronic mail network daily? Graphics workstation(s)? Mainframe computers as needed?	12 <u>.</u> 14 <u>.</u> 8 <u>.</u>	? (Check all that apply, and list th	<i>ne</i>
2. [Electronic mail network daily? Graphics workstation(s)?	12 <u> </u>	? (Check all that apply, and list th	<i>ne</i>
2. [/	Electronic mail network daily? Graphics workstation(s)? Mainframe computers as needed? Personal computer(s) as needed?	12 - 14 - 8 - 14 -	? (Check all that apply, and list th	<i>ne</i>
2. [/	Electronic mail network daily? Graphics workstation(s)? Mainframe computers as needed? Personal computer(s) as needed? Statistical analysis software?	12 - 14 - 8 - 14 -	? (Check all that apply, and list th	<i>ne</i>
2. [Electronic mail network daily? Graphics workstation(s)? Mainframe computers as needed? Personal computer(s) as needed? Statistical analysis software? Word processing software?	12 - 14 - 8 - 14 - 10 - 14 -	? (Check all that apply, and list th	<i>ne</i>
2. [/	Electronic mail network daily? Graphics workstation(s)? Mainframe computers as needed? Personal computer(s) as needed? Statistical analysis software? Word processing software? Windowing software?	12 - 14 - 8 - 14 - 10 - 14 - 13 -	? (Check all that apply, and list th	<i>ne</i>
2. [Electronic mail network daily? Graphics workstation(s)? Mainframe computers as needed? Personal computer(s) as needed? Statistical analysis software? Word processing software? Windowing software? Spreadsheet software?	12 - 14 - 8 - 14 - 10 - 14 - 13 -	? (Check all that apply, and list th	<i>ne</i>

4

CARD LAB QUESTIONNAIRE Page 3

3.	What database m (Check all that ap	nanag oply a	emen nd list	t technology is av the package(s) ເ	vailab used.)	le for y	our us	se?		
	Relational			13						
	Object oriente	d		4					<u> v</u>	
	Other									
	What software la	ngua(ges ar	e available for us	e at y	our fac	cility?	(Check all th	at app	oly)
	Fortran					uage(s		f) PV-Wave	4	
	C C++			14 11	Pasc		_ <u>5</u> 3	Basic	3	
	Ada			6		embler	3	Turbo Basio		
					<u>Lisp</u> PLI		<u> </u>	Tulbo basic	<u>- </u>	
					<u>FLI</u>		<u> </u>			
4.	What import or eapply)	xport	3D da	ata formats are av	/ailabl	le to yo	our fac	cility? (Check	all tha	at
	lr	nport I	Export	I	Import	Export		lr	nport I	Export
	IGES Cyberware PATRAN	9 3	8 2	QUICKMODEL POSTSCRIPT QUADRAX	1 6	1 6		AS ENGINEER r (<i>List</i>)	3 3	3 3
	.DXF	8	7	AUTOCAD	11	11		RÀ	1	1
	ASCII Point List	6 5	6 6	Color Postscript CADKEY	3	3 1				
	STL (Stereolithography)	O	Voxel View	1	i				
	formatting) ACR-NEMA DICOM	1	1	Unigraphics	2	2				
5.	Do you have acc	ess to	o Inter	net?		1	0-Y	N-3 (1 In F	Progre	ess)
6.	Do you have acc	ess to	o Bitno	et?		1	-Y	N-11		
7.	List other networ	ks to	which		s. al Ethe	ornet	1			
	Bulletin Boards	<u>-</u>		MILN		Z.110t	1			
	Dulletti Dualus	<u>, 1</u>		141(С1	<u> </u>					
8.	Do you have acc	ess t	o a m	odem?		1	2-Y	N-1 (Class	sified)	

8. Do you have access to a modem?

CARD LAB QUESTIONNAIRE

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Anthropometric Data and Analytics

9. Do you have access to any of the following types of anthropometric data? (Check applicable boxes and list outside sources if any)

	Published Tabulated Statistical Tables		lectronic ata	
		In-house Collected	Outside Source	
Traditional anthropometric measurements	14	9	7	
Human-system interface data (e.g., Clothing or helmet fit, cock, accommodation)	9 Dit	4	4	
3-dimensional human body surface data	7	4	5	
3-dimensional human body subsurface data (MRI, CT)	3	2	2	

10. If you have access to equipment for collecting high resolution 3-dimensional surface or subsurface data on the human body, to what type(s) of systems do you have access? (Check all that apply)

Cyberware Echo digitizer Linney laser system	.3	Other surface system (<i>List</i>) Laser design	1
Laser range finder system Cencit scanner	1	3-D sonic digitizer	1
Stereophotometric system with automated system	1	MRI	2
-or-	'	CT scanner Other subsurface system (<i>List</i>)	2
with manual processing LASS	1	(List)	

11. Which of the following types of data would be useful to you? (Check all that apply.)

Traditional anthropometric measurements

Categorized by Population	14
Categorized by Body Region	12
Categorized by Measurement Type	12

CARD LAB QUESTIONNAIRE Page 5

11.	Which of the following types of data wou apply.)	ld be us	seful to you? (Cont'd.) (C	Check all that
	3-dimensional human body surface dat	a		
	Categorized by Population Categorized by Body Region Categorized by Measurement Type	13 14 14		
	3-dimensional human body subsurface	data (N	IRI, CT)	
	Categorized by Population Categorized by Body Region	5 5		
	Human-system interface data			
	Prosthetic devices Other medical devices Clothing Protective equipment Cockpit Other workstations Other (<i>Please describe</i>)	3 6 11 9 6		
	Aids for physically challenged	1	Wheelchairs	1
	Head to helmet fit	1	Beds	1_
	Fit to vision (LOS & facial)	1	Lavatory	
12.	Please check the sections or aspects of to you.	human	body data that are of mo	st interest
	Head	11		
	Hands	6		
	Upper body Lower body	9 5		
	Whole body	9		
	Bio-mechanical/movement Other (<i>Please discuss</i>)	8		
	Ears and contours of head beh	ind ears	1	
				
				

CARD LAB QUESTIONNAIRE Page 6

13.	What analytic capabilities would you want to apanthropometric data covered in previous questions.	oply against the 2 ions? (<i>Check all</i>	?- and 3-dimensional that apply.)
	Linear statistics Multivariate statistics Surface descriptor or algorithms Shape quantification Shape summarization Distance calculations (Curvature, point-to-point, volumes, areas, mass properties) Non-linear calculations 3-dimensional data editing Data segmentation Other (<i>Please describe</i>)	10 9 7 9 7 14 5 7	
	Automated isolation and presentation		1
	Surface area		1
	Volume and center of volume		1
	Center of mass and inertial properties	A	1

CARD LAB QUESTIONNAIRE

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14. Would you prefer to store, access, and process 2- and 3-dimensional anthropometric data at your site on your computers, or have remote access (through a network or a modem) to such data and processing capabilities?

10 Local storage, access, processing 8 Remote access Comments Would like access to raw data 1 2 Download and store locally with quarterly updates 1 Depending on funding and access requirements 1 Remote access eliminates maintenance and update of on-site data base 1 A convenient system of remote access would allow us to download data when necessary It would be useful to hold the analytical 'tools' on site and be able to access various data packages as required (remote access)

15. Please describe the type(s) of help you would need to take greatest advantage of the data and analytic resources available through the Computerized Anthropometric Research and Design (CARD) Lab. Consider both on-line help as well as expertise and advice provided by Lab personnel.

Cross-referenced data	1
Edited data	2
Locating extremes (outliers)	1
On-line help	2
Groupware for research	1
Obtaining data	1
Understand format	2
Database manipulation	2
Validation/verification of data	1
System fit analysis with CARD data	1
Access to fit performance	1
Access to anthro data	1
Cockpit accommodation queries	1
Helmets	1
Caution about use/misuse of data	1
Raw data access	2
Statistical support	1
Tutorial/primer on how to use and the capabilities	3

CARD LAB QUESTIONNAIRE

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15. Please describe the type(s) of help you would need to take greatest advantage of the data and analytic resources available through the Computerized Anthropometric Research and Design (CARD) Lab. Consider both on-line help as well as expertise and advice provided by Lab personnel. (Continued)

A summary manual describing the database setup and its operation	1
Points of contact to answer questions regarding operation and data	1
It is likely that we will need both 'systems' and 'application' advice	1
since the amount of computerized anthropometric analysis	
knowledge we have is very limited	

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APPENDIX C CARD LAB CONCEPTUAL DATA MODEL - "FINAL"

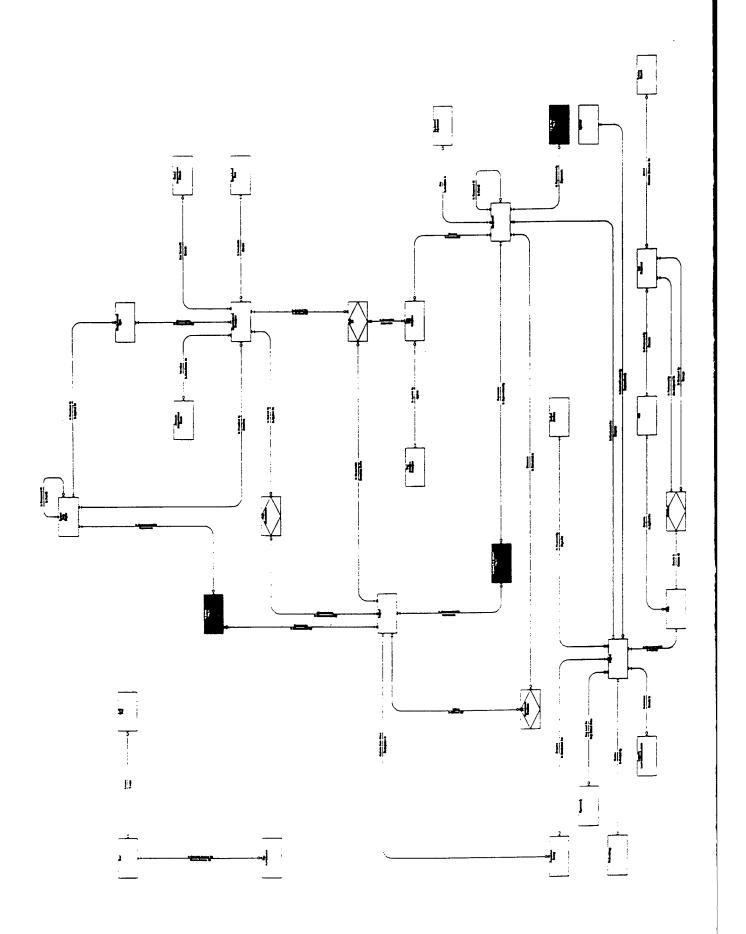
This deliverable includes the three documents that make up the Conceptual Data Model:

- Entity Relationship Diagram
- Entity Report
- Relationship Report.

The following points are important for understanding the Lab's Conceptual Data Model:

- We do not show summarized data in the Model. Instead we show the raw data collected during a study/survey as entities in the Model.
 Determination of what to do with summarized data is best dealt with as a design decision, with the two major alternatives being to store the statistically summarized data as a table or to recalculate the statistical summaries when needed.
- Three dimensional scan images are shown on the Entity Relationship Diagram as black boxes with white text to distinguish them from the tabular collections of data.
- The entities shown on the Entity Relationship Diagram as rectangles with diamonds inside are a special type of entity known as an <u>associative</u> entity. These entities contain data that result from a relationship between two or more other entities. For example, the entity "Raw Measurement" will contain the raw data resulting from taking specific measurements of a specific subject. "Raw Measurement" cannot exist without a "Subject" entity and a "Measurement Descriptor" entity.
- The user-related entities (User, User Authorization, Audit Trail) and corresponding relationships form the conceptual design for a User Database. While these entities provide control over, and tracking of, access and use of the remainder of the integrated CARD Lab data resource, there is no natural relationship between any of these entities and any of the remaining entities. Therefore, these entities are depicted in a "stand-alone" fashion.

ENTITY RELATIONSHIP DIAGRAM



ENTITY REPORT

CARD Lab Entity Report Object Summary Report

07-28-1993 03:25:02 PM CHUCKS card-lab

Entity Type: Alternate Measurement Name

Definition

An alternate name by which a measurement is known and may be accessed.

Comments

Identifier: Alternate Measurement Name

Other Attributes: Measurement Title

Entity Type: Audit Trail

Definition

Tracks the usage and navigational paths followed by the user during a specific session. In essence, this serves as a "script" of everything the user did during the session.

Comments

The user will be given the option of saving a maximum number of audit trail "files" for future use and reference. This number has not yet been determined.

Identifier: Session Date + Session Name

(Note: The user can be prompted for a session name for those sessions he/she wishes to save.)

Entity Type: Budget Account

Definition

A specified amount of budgeted funds, allocated for a specific purpose or against an approved project.

Comments

Identifier: Account Number

Other Attributes: Amount Budgeted, To Date Amount Spent

CARD Lab Entity Report Object Summary Report

Entity Type: Coded Measurement Domain

Definition

The domain of valid values for measurements which are coded.

Comments

Identifier: Measurement Title + Measurement Code

Other Attributes: Measurement Code Value

Entity Type: Equipment

Definition

An item of clothing, personal protective equipment, aircraft, or other equipment of interest in an anthropological study.

Comments

Due to the recursive relationship, this entity encompasses the hierarchy of an equipment family. For example, for an aircraft this entity will capture the following:

Category |

Aircraft

Crewstation

Control Region

Control

Identifier: Equipment Type + Equipment Identifier

Other Attributes: Serial Number, Equipment Description

Entity Type: Equipment Adjustment

Definition

The adjustments available for a given item of equipment. This includes the range of sizes for clothing and personal protective equipment, adjustments available for aircraft seat position, adjustments available for vision systems within a helmet, etc.

Comments

Identifier: Equipment Type + Equipment Identifier + Adjustment Identifier

Other Attributes: Adjustment Increment, Maximum Adjustment, Range of Adjustment

Entity Type: Equipment Image

Definition

A three dimensional image, either surface or subsurface, of a specific item of equipment.

Comments

Identifier: Equipment Type + Equipment Identifier

Other Attributes: Scan Date

Entity Type: Fit Assessment Comment

Definition

A comment made by the subject or the investigator about some aspect of the comfort or fit of a specific item of clothing or personal protective equipment.

Comments

Identifier: Subject Number + Subject Name + Equipment Type + Equipment Identifier

Other Attributes: Subject Comments, Investigator Comments

Entity Type: Human Body Region

Definition

A region of the human body, ranging from the whole body to a more minute section, such as a hand.

Comments

Identifier: Body Region Name

Entity Type: Lab Personnel

Definition

A human resource available to the Lab. May be a Government or a contractor employee.

Comments

Identifier: Personnel Name

Other Attributes: Employer

Entity Type: Lessons Learned/Conclusions

Definition

Text discussion of the lessons learned and conclusions for a specific project.

Comments

Identifier: Conclusion Identifier

Other Attributes: Lessons Learned/Conclusion Text

Entity Type: Measurement Descriptor

Definition

A specific anthropometric measurement to be applied in a study or survey.

Comments

Identifier: Measurement Title

Other Attributes: Measurement Description

Entity Type: Measurement Type

Definition

A means to classify and group anthropometric measurements.

Comments

Identifier: Measurement Type

Other Attributes: Measurement Type Description

Entity Type: Methodology

Definition

The approach and guidelines used to conduct a specific Lab project.

Comments

Identifier: Methodology Name

Entity Type: Opportunity

Definition

A possible new project (study, survey, fit assessment, etc.) which the Lab could undertake for a sponsor.

Comments

Identifier: Opportunity Identifier

Other Attributes: Potential Sponsor, Opportunity Description

Entity Type: Population Survey

Definition

A survey of a specific population group, such as "USAF Flying Personnel 1967".

Comments

Identifier: Population Survey Identifier

Other Attributes: Survey Description, Survey Date

Entity Type: Project

Definition

A fit assessment, population survey, cockpit or crewstation accommodation study, or some other work undertaken for, or on behalf of, a sponsoring organization.

Comments

Identifier: Project Identifier

Other Attributes: Project Description, Start Date, End Date

Entity Type: Raw Fit

Definition

A raw data value for a specific anthropometric measurement taken at a specific point in time for a specific subject to assess the fit or accommodation of a specific item of equipment, given specific trial conditions.

Comments

Identifier: Subject Number + Subject Name + Measurement Title + Equipment Type + Equipment Identifier + Test Trial Number

Other Attributes: Fit Measurement Value

Entity Type: Raw Measurement

Definition

A raw data value for a specific anthropometric measurement taken at a specific point in time for a specific subject.

Comments

Identifier: Subject Number + Subject Name + Measurement Title

Other Identifier: Measurement Value

Entity Type: Skill

Definition

The knowledge, proficiency, or ability required to accomplish a

specific task.

Comments

Identifier: Skill Name

Other Attributes: Skill Description

Entity Type: Specialized Term

Definition

A term used in any aspect of engineering anthropometry for which a

system user may require a definition.

Comments

Identifier: Specialized Term

Other Attributes: Term Description

Entity Type: Sponsor

Definition

The organization for which a Lab project is undertaken. This may be an

organization external to the Lab, or it may be the Lab itself.

Comments

Identifier: Organization

Other: Sponsor Key Contact Name, Address, Phone Number

Entity Type: Subject

Definition

A subject participant in a population survey, fit assessment, cockpit accommodation study, or other type of study.

Comments

Identifier: Subject Number + Subject Name

Other Attributes: Date of Birth, Age at Last Birthday, Place of Birth, Race, Rank, Gender, Branch of Service

Entity Type: Subject Image

Definition

A three dimensional image, either surface or subsurface, of a specific human subject or some body region of a human subject.

Comments

Identifier: Subject Number + Subject Name + Body Region Name

Other Attributes: Scan Date

Entity Type: Subject/Equipment Image

Definition

A three dimensional image, either surface or subsurface, involving a specific human subject and a specific item of equipment. This provides a "picture" of the human-equipment interface.

Comments

Identifier: Subject Number + Subject Name + Equipment Type + Equipment Identifier

Other Attributes: Scan Date

Entity Type: Task

Definition

A discrete unit of work activity. Includes a description of the work to be accomplished and an estimate of the time required to complete the work.

Comments

Identifier: Task Name

Other Attributes: Task Description, Time Required To Perform

Entity Type: Test Trial Condition

Definition

The specific conditions under which a specific measurement is taken. This could include: configuration, temperature, lighting, aircraft seat position, angle of orientation, etc.

Comments

Identifier: Equipment Type + Equipment Identifier + Trial Condition

Name

Other Attributes: Condition Value

Entity Type: Training Course

Definition

Formal training or continuing education intended to impart required knowledge, ability, or skill.

Comments

Identifier: Training Course Name

Entity Type: Trial Condition Descriptor

Definition

Description of a specific condition under which a measurement might be taken in a trial of a study test.

Comments

Identifier: Trial Condition Name

Other Attributes: Trial Condition Description

Entity Type: User

Definition

An individual or organization authorized to access and use CARD Lab data, hardware, and/or software tools.

Comments

Identifier: User Name

Other Attributes: Organization, Phone Number, Address

Entity Type: User Authorization

Definition

The specific access and use capabilities granted to an individual user or organization.

Comments

Identifier: Authorization Level

Other Attributes: Privilege Granted

Entity Type: Workload

Definition

The amount of work, in the form of specific tasks, assigned to a specific Lab "employee" during a given period of time.

Comments

Identifier: Personnel Name + Task Name

Other Attributes: Estimated Time Required, Start Date, End Date

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RELATIONSHIP REPORT

CARD Lab Relationship Report

Object Summary Report

07-28-1993 02:46:40 PM CHUCKS card-lab

Relationship Type: Test Trial Condition. Applies. Trial Condition Descriptor

PROPERTY	VALUE		
To From Name	Is Applied By		
From To Minimum	1		
From To Maximum	1		
To From Minimum	0		
To From Maximum	M		
Last Update	1993/07/28 13:00:5	55 CHUCKS	
Created	1993/07/28 13:00:5	55 CHUCKS	
ASSOCIATION	TYPE	NAME	

Relationship Type: Lab Personnel.Are Assigned To.Workload

PROPERTY	VALUE	
To From Name From To Minimum From To Maximum To From Minimum To From Maximum Last Update Created	Is Performed By 1 M 1 1 1993/05/11 07:29:28 1993/05/10 12:34:37	
ASSOCIATION	TYPE	NAME

Relationship Type: Lab Personnel.Attend.Training Course

PROPERTY	VALUE
To From Name	Provides Education To
From To Minimum	0
From To Maximum	M

To From Minimum 0

To From Maximum M
Last Update 1993/05/11 07:50:40 MARKW
Created 1993/05/10 12:10:47 MARKW

ASSOCIATION TYPE NAME

Relationship Type: Population Survey.Collects Data About.Subject

PROPERTY	VALUE	
To From Name From To Minimum From To Maximum To From Minimum To From Maximum Last Update Created	Participates In 1 M 0 M 1993/07/14 09:42:49 CHC 1993/07/12 08:27:16 CHC	
ASSOCIATION	TYPE	NAME

Relationship Type: User.Creates.Audit Trail

PROPERTY	VALUE	
To From Name From To Minimum From To Maximum To From Minimum To From Maximum Last Update Created	Tracks 0 M 1 1 1993/07/28 1993/07/28	
ASSOCIATION	TYPE	NAME

Relationship Type: Sponsor.Desires/Funds.Project

PROPERTY	VALUE
To From Name From To Minimum From To Maximum To From Minimum To From Maximum Last Update Created	Is Desired/Funded By 0 M 1 M 1993/07/28 13:38:07 CHUCKS 1993/05/10 12:03:24 MARKW
ASSOCIATION	TYPE NAME

Relationship Type: Equipment.Has.Equipment Adjustment

PROPERTY	VALUE
To From Name From To Minimum From To Maximum To From Minimum To From Maximum Last Update Created	Is Available In 0 M 1 1 1993/07/15 14:34:46 CHUCKS 1993/07/14 08:44:40 CHUCKS
ASSOCIATION	TYPE NAME

Relationship Type: Measurement Descriptor. Has Values Of. Coded Measurement Domai

PROPERTY	VALUE
To From Name	Bounds
From To Minimum	0
From To Maximum	M
To From Minimum	1

To From Maximum 1
Last Update 1993/07/14 10:02:56 CHUCKS
Created 1993/07/12 08:42:18 CHUCKS

ASSOCIATION TYPE NAME

Relationship Type: Test Trial Condition.Influences.Raw Fit

PROPERTY	VALUE
To From Name From To Minimum From To Maximum To From Minimum To From Maximum Last Update Created	Is Based On 0 M 1 1 1993/07/28 13:35:21 CHUCKS 1993/07/12 09:39:43 CHUCKS
ASSOCIATION	TYPE NAME

Relationship Type: Measurement Descriptor.Is Also Known As.Alternate Measurement Name

PROPERTY	VALUE	
To From Name From To Minimum From To Maximum To From Minimum To From Maximum Last Update Created	Identifies 0 M 1 1 1 993/07/14 1993/07/12	
ASSOCIATION	TYPE	NAME

Relationship Type: Measurement Descriptor.Is Applied To.Raw Measurement

PROPERTY	VALUE	
To From Name From To Minimum From To Maximum To From Minimum To From Maximum Last Update Created	Is Defined By 0 M 1 1 1993/07/28 13:32:29 1993/07/08 15:53:36	
ASSOCIATION	TYPE	NAME

Relationship Type: Measurement Descriptor.Is Applied To.Raw Fit

PROPERTY	VALUE	
To From Name From To Minimum From To Maximum To From Minimum To From Maximum Last Update Created	Is Defined By 0 M 1 1 1993/07/28 13:33:10 1993/07/12 09:02:10	
ASSOCIATION	TYPE	NAME

Relationship Type: Measurement Type.Is Applied To.Human Body Region

PROPERTY	VALUE
To From Name From To Minimum From To Maximum To From Minimum	Is Described By 1 M

To From Maximum M

Last Update 1993/07/28 13:09:40 CHUCKS Created 1993/07/28 13:09:40 CHUCKS

ASSOCIATION TYPE NAME

Relationship Type: Measurement Descriptor. Is Categorized By. Measurement Type

PROPERTY VALUE

To From Name Categorizes

From To Minimum 1
From To Maximum 1
To From Minimum 1
To From Maximum M

Last Update 1993/07/14 10:02:04 CHUCKS Created 1993/07/12 08:40:19 CHUCKS

ASSOCIATION TYPE NAME

Relationship Type: Subject.Is Characterized By.Raw Measurement

PROPERTY VALUE

To From Name Characterizes

From To Minimum 0
From To Maximum M
To From Minimum 1
To From Maximum 1

Last Update 1993/07/14 09:48:34 CHUCKS Created 1993/07/12 08:21:23 CHUCKS

ASSOCIATION TYPE NAME

Relationship Type: Project.Is Composed Of.Task

PROPERTY	VALUE	
To From Name From To Minimum From To Maximum To From Minimum To From Maximum Last Update Created	Is Part Of 1 M 1 1 1993/05/11 1993/05/10	
ASSOCIATION	TYPE	NAME

Relationship Type: Human Body Region. Is Composed Of. Human Body Region

PROPERTY	VALUE	
To From Name From To Minimum From To Maximum To From Minimum To From Maximum Last Update Created	Is Part Of 0 M 1 1 1993/07/15 14:39:59 1993/05/18 09:16:36	
ASSOCIATION	TYPE	NAME

Relationship Type: Equipment. Is Composed Of. Equipment

PROPERTY	ď	VAI	LUE	
To From	Name	Is	Part	Of
From To	Minimum	0		
From To	Maximum	M		
To From	Minimum	1		

To From Maximum 1

Last Update 1993/07/15 14:40:34 CHUCKS Created 1993/07/12 09:26:11 CHUCKS

ASSOCIATION TYPE NAME

Relationship Type: Project.Is Conducted For.Population Survey

PROPERTY VALUE

To From Name Requires
From To Minimum 0
From To Maximum M
To From Minimum 1
To From Maximum 1
Last Update 1993/07/14 09:14:43 CHUCKS
Created 1993/07/14 08:52:58 CHUCKS

ASSOCIATION TYPE NAME

Relationship Type: Project. Is Conducted For. Equipment

PROPERTY VALUE To From Name Requires From To Minimum From To Maximum M To From Minimum To From Maximum 1 Last Update 1993/07/14 09:10:33 CHUCKS Created 1993/07/14 09:10:33 CHUCKS ASSOCIATION TYPE NAME

Relationship Type: Human Body Region. Is Described By. Measurement Descriptor

PROPERTY	VALUE			
To From Name	Describes			
From To Minimum	0			
From To Maximum	М			
To From Minimum	1			
To From Maximum	1			
Last Update	1993/07/14	09:56:47	CHUCKS	
Created	1993/05/14	11:38:49	CHUCKS	
ASSOCIATION	TYPE		NAME	

Relationship Type: Equipment.Is Discussed In.Fit Assessment Comment

PROPERTY	VALUE	
To From Name From To Minimum From To Maximum To From Minimum To From Maximum Last Update Created	Discusses 0 M 1 1 1993/07/14 1993/07/12	
ASSOCIATION	TYPE	NAME

Relationship Type: Project.Is Financed By.Budget Account

PROPERTY	VALUE
To From Name	Pays For
From To Minimum	1
From To Maximum	М
To From Minimum	0

To From Maximum

M

Last Update Created

1993/07/14 09:16:32 CHUCKS 1993/07/12 12:35:00 CHUCKS

ASSOCIATION

TYPE

NAME

Relationship Type: User.Is Granted Access By.User Authorization

PROPERTY

VALUE

To From Name

Grants Access To

From To Minimum 0
From To Maximum M
To From Minimum 1
To From Maximum 1

Last Update Created 1993/07/14 09:58:10 CHUCKS 1993/07/12 12:29:35 CHUCKS

ASSOCIATION TYPE

NAME

Relationship Type: Project. Is Guided By. Methodology

PROPERTY

VALUE

To From Name

Guides

From To Minimum
From To Maximum
To From Minimum
To From Maximum

Last Update

1993/07/14 09:13:54 CHUCKS

Created

1993/07/12 13:19:45 CHUCKS

ASSOCIATION

TYPE

NAME

Relationship Type: Measurement Descriptor.Is Included In.Specialized Term

PROPERTY	VALUE	
To From Name From To Minimum From To Maximum To From Minimum To From Maximum	Covers 1 1 0 1	
Last Update Created	1993/07/14 1993/07/12	
ASSOCIATION	TYPE	 NAME

Relationship Type: Equipment.Is Included In.Test Trial Condition

PROPERTY	VALUE	
To From Name From To Minimum From To Maximum To From Minimum To From Maximum Last Update	Covers 0 M 1 1 1993/07/28 14:45:09	
Created	1993/07/14 08:41:27	CHUCKS
ASSOCIATION	TYPE	NAME

Relationship Type: Subject.Is Measured In.Raw Fit

PROPERTY	ď	,	VALUE		
To From	Name Minimum	I (Describes	Fit	For
	Maximum	N	1		
To From	Minimum	1			
To From	Maximum	1	-		

Last Update 1993/07/28 14:42:54 CHUCKS Created 1993/07/12 09:07:43 CHUCKS

ASSOCIATION TYPE NAME

Relationship Type: Fit Assessment Comment. Is Offered By. Subject

PROPERTY VALUE To From Name Offers From To Minimum From To Maximum To From Minimum 0 To From Maximum Last Update 1993/07/15 14:33:38 CHUCKS Created 1993/07/12 09:35:43 CHUCKS ASSOCIATION TYPE NAME

Relationship Type: Human Body Region. Is Represented By. Subject Image

PROPERTY VALUE To From Name Represents From To Minimum 0 From To Maximum М To From Minimum 1 To From Maximum Last Update 1993/07/15 14:42:42 CHUCKS 1993/05/14 11:38:15 CHUCKS Created TYPE ASSOCIATION NAME

Relationship Type: Subject.Is Represented By.Subject Image

PROPERTY	VALUE
To From Name From To Minimum From To Maximum To From Minimum To From Maximum Last Update Created	Represents 0 M 1 1 1993/07/15 14:43:37 CHUCKS 1993/07/08 15:47:44 CHUCKS
ASSOCIATION	TYPE NAME

Relationship Type: Subject.Is Represented By.Subject/Equipment Image

PROPERTY	VÄLUE	
To From Name From To Minimum From To Maximum To From Minimum To From Maximum Last Update Created	Represents 0 M 1 1 1993/07/14 09:17:42 1993/07/12 09:30:28	
ASSOCIATION	TYPE	NAME

VALUE

Relationship Type: Equipment.Is Represented By.Subject/Equipment Image

To From	Name	Represents
From To	Minimum	0
From To	Maximum	M
To From	Minimum	1

PROPERTY

To From Maximum

Last Update 1993/07/14 09:18:50 CHUCKS Created 1993/07/12 09:31:12 CHUCKS

ASSOCIATION TYPE NAME

Relationship Type: Equipment. Is Represented By . Equipment Image

PROPERTY VALUE

To From Name Represents

From To Minimum 0
From To Maximum M
To From Minimum 1
To From Maximum 1

Last Update 1993/07/14 09:19:29 CHUCKS Created 1993/07/12 09:33:09 CHUCKS

ASSOCIATION TYPE NAME

VALUE

Relationship Type: Lab Personnel.Manage.Workload

To From Name Is Managed By

From To Minimum 0
From To Maximum M
To From Minimum 1
To From Maximum 1

PROPERTY

Last Update 1993/05/11 07:30:12 MARKW Created 1993/05/11 07:30:12 MARKW

ASSOCIATION TYPE NAME

Relationship Type: Project. May Result From. Opportunity

PROPERTY	VALUE	
To From Name From To Minimum From To Maximum To From Minimum To From Maximum Last Update Created	May Lead To 0 M 0 M 1993/07/14 09:15:27 CHUCKS 1993/07/12 12:40:06 CHUCKS	
ASSOCIATION	TYPE NAME	

Relationship Type: Lab Personnel.Possess.Skill

PROPERTY	VALUE	
To From Name From To Minimum From To Maximum To From Minimum To From Maximum Last Update Created	Is Possessed By 1 M 0 M 1993/07/15 14:44:36 1993/05/10 12:15:53	
ASSOCIATION	TYPE	NAME

Relationship Type: Task.Requires.Skill

PROPERTY	VALUE
To From Name From To Minimum	Is Applied To 1
From To Maximum	М
To From Minimum	0
To From Maximum	M

Last Update 1993/07/28 12:26:02 CHUCKS Created 1993/07/28 12:26:02 CHUCKS

ASSOCIATION TYPE NAME

Relationship Type: Task.Results In.Workload

PROPERTY VALUE

To From Name Consists Of
From To Minimum 1
From To Maximum M
To From Minimum 1
To From Maximum 1
Last Update 1993/07/15 14:46:49 CHUCKS
Created 1993/05/10 12:33:46 MARKW

TYPE

Relationship Type: Project.Results In.Lessons Learned/Conclusions

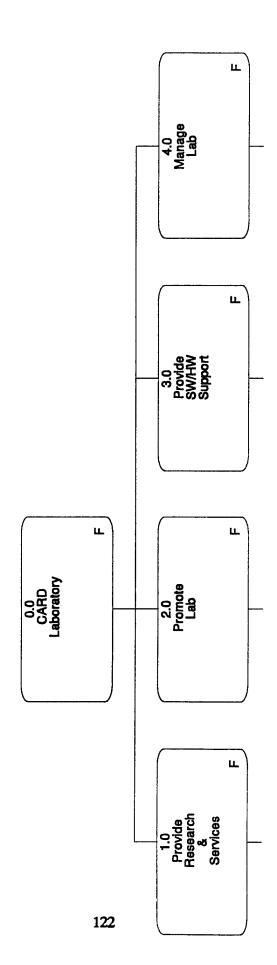
NAME

PROPERTY VALUE To From Name Summarize From To Minimum From To Maximum M To From Minimum To From Maximum Last Update 1993/07/28 12:31:25 CHUCKS Created 1993/07/28 12:31:25 CHUCKS ASSOCIATION TYPE NAME

ASSOCIATION

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APPENDIX D CARD LAB ENTERPRISE MODEL - "FINAL"



CARD Lab Enterprise Model Object Summary Report

07-06-1993 10:29:28 AM CHUCKS card-lab

Function: 0.0 CARD Laboratory

Definition

The Computerized Anthropometric Research and Design (CARD) Laboratory captures, analyzes, and provides information on human body size and shape, and the interface of the human body with equipment/systems, to evaluate and improve the design of clothing, personal protective equipment, and cockpits and other workstations.

Function: 1.0 Provide Research & Services

Definition

Conduct research to advance the state of the art of anthropometry and to answer specific questions posed by, or in support of, other organizations, and provide anthropometric consulting services to other organizations.

Comments

The CARD Lab conducts research to advance methods for defining and representing the size, shape (summarization and characterization), strength, dexterity, and functional characteristics of humans for use in the design of clothing, personal protective equipment, and workstations.

Research studies may be focused on different parts of the human body (for example, head, hands, total body, etc.) or on the human-system interface.

Research may be conducted for a specific sponsor or may be conducted as part of the research program of a member of the Lab staff.

Function: 2.0 Promote Lab

Definition

Promote the use of Lab research capabilities and data, as well as other anthropometric consulting services, and the benefits of using those services and data, by identifying opportunities for the application of

CARD Lab Enterprise Model Object Summary Report

Lab capabilities, educating engineers and designers in the use of Lab data and services, participating on working groups, and advertising.

Function: 3.0 Provide SW/HW Support

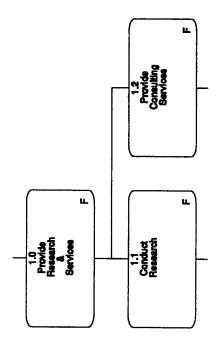
Definition

Provide computer software and hardware support for the CARD Lab by monitoring trends and advances in technology, administering existing systems and databases, acquiring new software and hardware, developing methods, turning those methods into automated tools and systems, and providing training in tool and system use.

Function: 4.0 Manage Lab

Definition

Manage the overall operation of the CARD Lab, including budgets and funding, facilities and equipment, and personnel.



CARD Lab Enterprise Model
Object Summary Report
07-06-1993 09:22:30 AM CHUCKS card-lab

Function: 1.0 Provide Research & Services

Definition

Conduct research to advance the state of the art of anthropometry and to answer specific questions posed by, or in support of, other organizations, and provide anthropometric consulting services to other organizations.

Comments

The CARD Lab conducts research to advance methods for defining and representing the size, shape (summarization and characterization), strength, dexterity, and functional characteristics of humans for use in the design of clothing, personal protective equipment, and workstations.

Research studies may be focused on different parts of the human body (for example, head, hands, total body, etc.) or on the human-system interface.

Research may be conducted for a specific sponsor or may be conducted as part of the research program of a member of the Lab staff.

Function: 1.1 Conduct Research

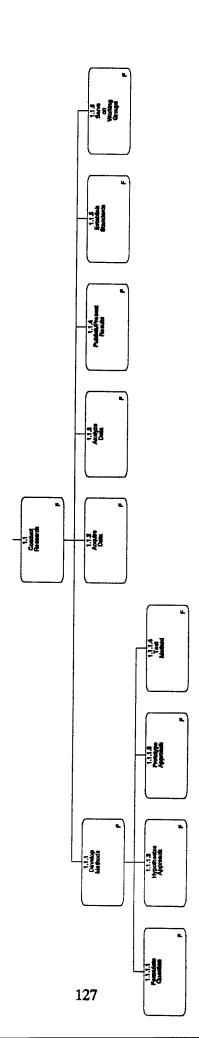
Definition

Advance the state of the art of engineering anthropometry by conducting research to develop or refine anthropometric techniques and methods, introducing new technologies into the discipline, delivering papers and presentations, and serving on working groups.

Function: 1.2 Provide Consulting Services

Definition

Provide anthropometric consulting services to Lab customers and funding agencies by participating in the procurement process and serving as an expert witness.



CARD Lab Enterprise Model Object Summary Report

07-19-1993 08:25:33 AM CHUCKS card-lab

Function: 1.1 Conduct Research

Definition

Advance the state of the art of engineering anthropometry by conducting research to develop or refine anthropometric techniques and methods, introducing new technologies into the discipline, delivering papers and presentations, and serving on working groups.

Function: 1.1.1 Develop Methods

Definition

Develop new methods and techniques for assessing the fit (or accommodation) of clothing, personal protective equipment, cockpits, aircraft crewstations, and other work stations to the human body, or collecting anthropometric data. This involves formulating the research question, hypothesizing an approach to answer the question, prototyping and testing the approach.

Function: 1.1.1.1 Formulate Question

Definition

Formulate the research question necessary to satisfy the need of a Lab customer and to guide a research investigation. This research question may be documented in the form of a research proposal.

Function: 1.1.1.2 Hypothesize Approach

Definition

Design the research approach (method) necessary to answer the research question, plan the tests required to evaluate the approach, and document any applicable research protocols.

Function: 1.1.1.3 Prototype Approach

Definition

Develop prototypes of any required forms, equipment, etc. necessary to execute the research approach.

CARD Lab Enterprise Model Object Summary Report

Function: 1.1.1.4 Test Method

Definition

Execute the test plan for the new method to evaluate the overall reliability, repeatability, and consistency of the new method and to compare the quality of measurements acquired through the use of traditional anthropometry with those acquired through the use of the new method. Modify the approach based on the results of the test.

Function: 1.1.2 Acquire Data

Definition

Acquire data on the human body, as well as other objects, and the fit/accommodation of clothing, personal protective equipment, cockpits, and aircraft crewstations.

Comments

Advancing anthropometry will involve collecting new data about:

- * 3-dimensional surface and subsurface
- * tissue properties
- * strength and dexterity
- * bio-mechanics and movement
- * human-equipment interface

Function: 1.1.3 Analyze Data

Definition

Conduct analyses on the data necessary to answer the research questions. This may involve extracting data from population samples, manipulating 3-dimensional images, and/or running statistical or mathematical procedures against the data.

Function: 1.1.4 Publish/Present Results

Definition

Document and publish the research results in technical reports or through a briefing to inform the research sponsor of the results and

CARD Lab Enterprise Model Object Summary Report

for subsequent use by Lab personnel and other organizations.

Function: 1.1.5 Establish Standards

Definition

Establish and publish standards and/or handbooks to codify the new methods for the acquisition, storage, analysis, and exchange of anthropometric data on the human body and/or the human-equipment interface. These standards may be general in nature or application specific (fit or accommodation assessment, anthropometry, etc.).

Function: 1.1.6 Serve on Working Groups

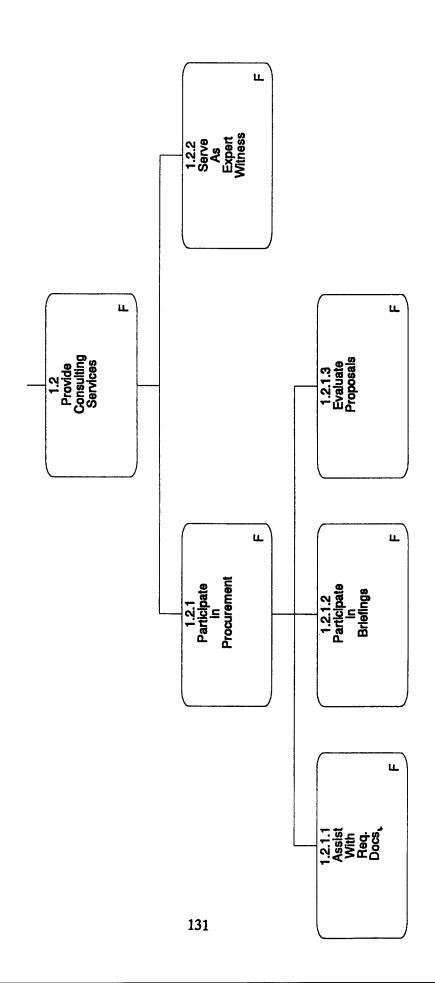
Definition

Serve on national and international working groups, committees, and professional societies as a means of furthering engineering anthropometry, as a forum for information exchange for advanced methods and techniques, and as a means of promoting the CARD Lab.

Comments

Lab staff currently serve on the following working groups, committees, and professional societies:

- * Electronic Imaging of the Human Body
- * Working Group on Night Visions Systems
- * Tri-Service Working Group for Bio-Mechanics
- * Advisory Group for Aerospace Research and Development (AGARD)
- * Air Standardization Coordinating Committee (ASCC)
- * Defense Advisory Committee on Women in Services
- * Human Factors Society
- * Aerospace Medical Association
- * SAFE



CARD Lab Enterprise Model

Object Summary Report

07-06-1993 09:04:00 AM CHUCKS card-lab

Function: 1.2 Provide Consulting Services

Definition

Provide anthropometric consulting services to Lab customers and funding agencies by participating in the procurement process and serving as an expert witness.

Function: 1.2.1 Participate in Procurement

Definition

Participate in the process of procuring clothing, protective equipment, and aircraft by providing expertise in sound anthropometric practices and data, and commenting on designs and proposals based on that expertise.

Function: 1.2.1.1 Assist With Req. Docs.

Definition

Provide assistance to SPOs and other acquiring agencies with the preparation of requirements documents, including requests for proposal, for clothing, personal protective equipment, and aircraft. Such assistance is aimed at incorporating sound anthropometric practices and data into the acquisition process.

Function: 1.2.1.2 Participate in Briefings

Definition

Provide expertise in engineering anthropometry during briefings with manufacturers to discuss the design of clothing, personal protective equipment, and aircraft.

Function: 1.2.1.3 Evaluate Proposals

Definition

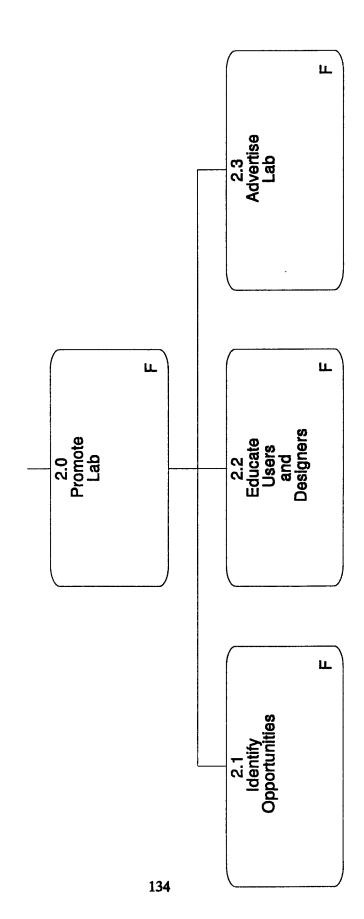
Evaluate proposals from manufacturers of clothing, personal protective equipment, and aircraft based on the criteria of sound engineering anthropometry and data.

CARD Lab Enterprise Model Object Summary Report

Function: 1.2.2 Serve As Expert Witness

Definition

Serve as an expert witness in engineering anthropometry, giving testimony and advice to Senate, Pentagon, and other Governmental committees.



CARD Lab Enterprise Model

Object Summary Report

07-19-1993 08:17:33 AM CHUCKS card-lab

Function: 2.0 Promote Lab

Definition

Promote the use of Lab research capabilities and data, as well as other anthropometric consulting services, and the benefits of using those services and data, by identifying opportunities for the application of Lab capabilities, educating engineers and designers in the use of Lab data and services, participating on working groups, and advertising.

Function: 2.1 Identify Opportunities

Definition

Search for and identify opportunities where the Lab's data and/or services could be applied to the design of an object so that the comfort, fit, safety, and performance of the object are improved.

Function: 2.2 Educate Users and Designers

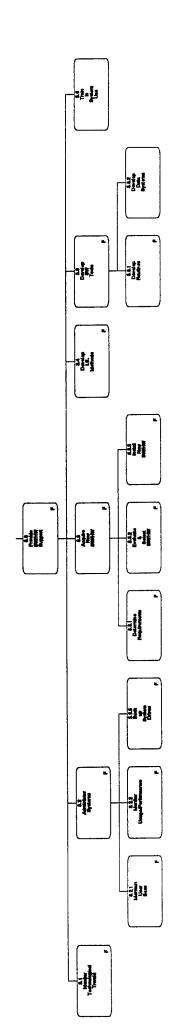
Definition

Educate engineers, designers, representatives from acquiring agencies, and other interested parties on the role and value of engineering anthropometry and the access and use of Lab data and services.

Function: 2.3 Advertise Lab

Definition

Promote the capabilities of the CARD Lab through print advertising, video presentations, and public affairs publications, and by giving tours of the Lab facilities.



CARD Lab Enterprise Model

Object Summary Report

07-07-1993 08:26:07 AM CHUCKS card-lab

Function: 3.0 Provide SW/HW Support

Definition

Provide computer software and hardware support for the CARD Lab by monitoring trends and advances in technology, administering existing systems and databases, acquiring new software and hardware, developing methods, turning those methods into automated tools and systems, and providing training in tool and system use.

Function: 3.1 Monitor Technological Trends

Definition

Monitor trends and advances in computer software and hardware technologies and software development methodologies to stay abreast of developments which might benefit the Lab.

Function: 3.2 Administer Systems

Definition

Administer existing computer software and hardware systems by maintaining user authorization and privileges, monitoring usage and performance, backing up databases, and in general managing the configuration of the overall system as well as system components, etc.

Function: 3.2.1 Maintain User Base

Definition

Maintain a database of Lab system users, including user addresses, security authorization, and access and use privileges for users within and outside the Lab.

Function: 3.2.2 Monitor Usage/Performance

Definition

Monitor the usage and performance of all system components -- hardware (computers, printers, etc.), application software, databases, network,

CARD Lab Enterprise Model Object Summary Report

etc.

Function: 3.2.3 Back up System Drives

Definition

Back up all system disk drives on a regularly scheduled basis to ensure that databases and other software components can be recovered in the event of a system failure.

Function: 3.3 Acquire New SW/HW

Definition

Acquire new software and/or hardware by determining the requirements for software or hardware, evaluating commercial offerings against those requirements and selecting those best satisfying the requirements, and installing the software and/or hardware.

Function: 3.3.1 Determine Requirements

Definition

Determine the requirements for software or hardware to be acquired.

Function: 3.3.2 Evaluate & Select SW/HW

Definition

Evaluate software and/or hardware offerings and select those which best satisfy the Lab requirements.

Function: 3.3.3 Install New SW/HW

Definition

Install new software and/or hardware.

Function: 3.4 Develop I.S. Methods

Definition

Develop methods and techniques to guide the development and application

CARD Lab Enterprise Model Object Summary Report

of information systems technologies in support of the Lab. This includes methods and standards for developing information systems, storing data and images in computer files, accessing the data and images, and presenting them for and performing visualization, manipulation, and analysis.

Comments

These methods might be used for modeling surface and subsurface data, merging surface and subsurface data into a consolidated image, and modeling bio-mechanical and movement data. These methods are turned into software applications in function 3.5.

Function: 3.5 Develop SW Tools

Definition

Provide software tools to support Lab operations by custom development of stand-alone routines as well as more comprehensive data systems.

Function: 3.5.1 Develop Routines

Definition

Develop stand-alone routines or modules to satisfy ad hoc requests or meet one-time or short-term needs for software support. Routines are frequently developed to support specific research efforts.

This function includes both new development and enhancement or modification of existing routines.

Program code is developed in a modular fashion to allow additional capabilities to be incorporated later.

Comments

Routines might support any of the following:

- * automated landmarking
- * display of an axis system for 3D head data
- * visualization and manipulation of 3D images
- * data reduction
- * data exchange formats (between the CARD Lab Data

CARD Lab Enterprise Model Object Summary Report

System and other systems, such as CAD and modeling, etc.)

* automated identification of colored points found on scanned objects.

Function: 3.5.2 Develop Data Systems

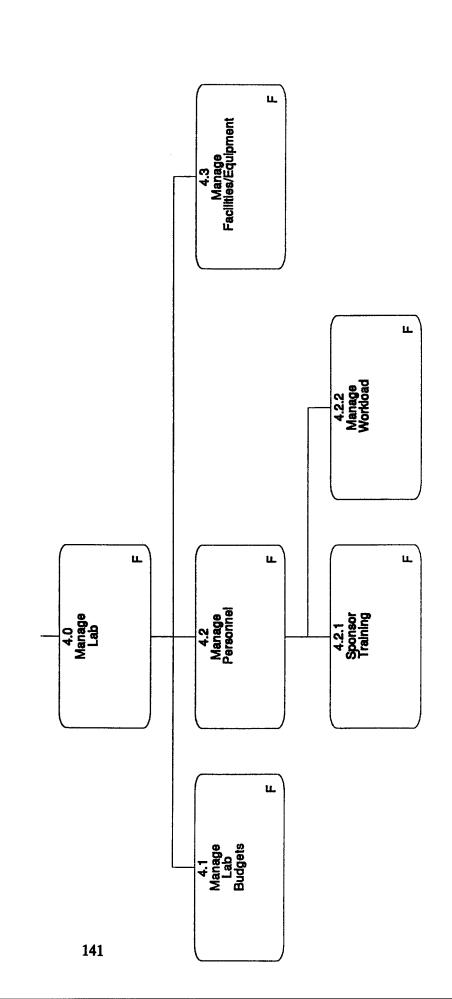
Definition

Develop complete data systems, including 2- and 3-dimensional databases, user interface, and programs, to meet multiple use or on-going needs for software support. This includes both new development and enhancement or modification of existing systems.

Function: 3.6 Train in System Use

Definition

Train Lab personnel, 3rd party systems developers, and other system users in the capabilities, access, and use of software. Provide on-going support for the use of Lab data and hardware/software tools.



CARD Lab Enterprise Model

Object Summary Report

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Function: 4.0 Manage Lab

Definition

Manage the overall operation of the CARD Lab, including budgets and funding, facilities and equipment, and personnel.

Function: 4.1 Manage Lab Budgets

Definition

Prepare budgets for the Lab, attract funding and sponsors for Lab projects, and manage contracts and expenditures against the budget.

Function: 4.2 Manage Personnel

Definition

Ensure that the personnel with appropriate training and skills are available to accomplish the projects and studies undertaken by the Lab, and manage the workload assigned to staff.

Function: 4.2.1 Sponsor Training

Definition

Sponsor training for Lab personnel, to help personnel stay current with technology, methods, and techniques.

Function: 4.2.2 Manage Workload

Definition

Manage the workload assigned to Lab personnel and coordinate project and study priorities across the Lab.

Function: 4.3 Manage Facilities/Equipment

Definition

Manage the facilities allocated to the Lab and the equipment owned by the Lab. This includes assigning workspace, arranging needed modifications and maintenance to lighting or layout, coordinating moves when necessary, etc.

APPENDIX E DATABASE DESCRIPTION

RIM COCKPIT DATABASE SCHEMA

YES

KEY

RELATION : AIRCRAFT

LAST MOD : 93/03/04 READ PASSWORD : NONE MODIFY PASSWORD : NONE SCHEMA : CACCOM

KEY TYPE LENGTH NAME

ANUM INT 1 INT 1 CATNUM

TEXT 8 CHARACTERS ANAME

CURRENT NUMBER OF ROWS = 5

TYPE

NAME

RELATION : AIRDESC

LAST MOD: 93/03/04 READ PASSWORD: NONE

MODIFY PASSWORD : NONE SCHEMA : CACCOM

LENGTH

YES 1 INT

ANUM TEXT VARIABLE ADESC

CURRENT NUMBER OF ROWS =

RELATION : CATNAME

LAST MOD : 93/03/04 READ PASSWORD : NONE MODIFY PASSWORD : NONE SCHEMA : CACCOM

LENGTH KEY TYPE NAME

CATNUM INT

10 CHARACTERS TEXT CATNAME

CURRENT NUMBER OF ROWS =

RELATION : CREWSTA

LAST MOD : 93/03/04 READ PASSWORD : NONE MODIFY PASSWORD : NONE SCHEMA : CACCOM

LENGTH NAME TYPE

YES CREWSTAN INT 10 CHARACTERS CREWSTA TEXT

CURRENT NUMBER OF ROWS =

RELATION : AIRCREW

LAST MOD: 93/03/04 READ PASSWORD: NONE SCHEMA: CACCOM MODIFY PASSWORD: NONE SCHEMA : CACCOM

LENGTH KEY TYPE NAME YES 1 ANUM INT CREWSTAN YES INT 1

CURRENT NUMBER OF ROWS =

RELATION : AIRREG

LAST MOD : 93/03/04 READ PASSWORD : NONE SCHEMA : CACCOM MODIFY PASSWORD : NONE

LENGTH KEY TYPE NAME YES INT ANUM 1 REGNUM INT

RELATION : CONTROL LAST MOD: 93/03/04 READ PASSWORD: NONE SCHEMA : CACCOM MODIFY PASSWORD : NONE NAME TYPE LENGTH KEY CONTNUM INT 1 YES CONTNAME TEXT 60 CHARACTERS CURRENT NUMBER OF ROWS = 281 RELATION : CREWCONT LAST MOD : 93/03/04 READ PASSWORD : NONE SCHEMA : CACCOM MODIFY PASSWORD : NONE NAME TYPE LENGTH KEY ANUM INT 1 YES CREWSTAN INT 1 YES CONTNUM INT YES CURRENT NUMBER OF ROWS = 407 RELATION : SEATADJ LAST MOD : 93/03/04 READ PASSWORD : NONE SCHEMA : CACCOM MODIFY PASSWORD : NONE NAME TYPE LENGTH KEY ANUM INT 1 YES ADJDIR TEXT 1 CHARACTERS ADJINC REAL 1 MAXADJ REAL 1 CURRENT NUMBER OF ROWS = RELATION : REACH LAST MOD : 93/03/04 READ PASSWORD : NONE SCHEMA : CACCOM MODIFY PASSWORD : NONE NAME TYPE LENGTH KEY ANUM INT YES REGNUM INT 1 CREWSTAN INT 1 YES CONTHAND TEXT 1 CHARACTERS YES CONTNUM INT 1 YES CONTTYPE TEXT 1 CHARACTERS MEASURED TEXT 1 CHARACTERS Z2FACTOR REAL 1 SHSCOEF REAL 1 CONSTANT REAL CURRENT NUMBER OF ROWS = 474 RELATION : RCHNOTE LAST MOD : 93/03/04 READ PASSWORD : NONE SCHEMA : CACCOM MODIFY PASSWORD : NONE NAME TYPE LENGTH KEY ANUM INT 1 YES REGNUM

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1 CHARACTERS

YES

YES

INT

INT

TEXT

CREWSTAN

CONTHAND

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	RELATION :							
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CURREN	T NUMBER OF ROW	'S = 6						
	RELATION :	CREWVIEW						
LAST MOD : SCHEMA :	93/03/04 CACCOM	READ PASSWORD MODIFY PASSWOR	: NONE D : NONE					
NAME	TYPE	LENGTH	KEY					
ANUM	INT INT	1	YES					
	INT INT	1 1	YES YES					
VIEWNUM	INT	1	125					
CURRE	NT NUMBER OF ROW	<i>IS</i> = 31						
	RELATION :	VISNOTE	1701777					
LAST MOD : SCHEMA :	CACCOM	READ PASSWORD MODIFY PASSWOR	: NONE					
NAME	TYPE	LENGTH	KEY					
ANUM	INT	1	YES					
VIEWNUM	INT	1	YES					
HEADPOSN CREWSTAN		1 1	YES YES					
	INT	1	120					
CURRENT NUMBER OF ROWS = 16								
	RELATION :	CI DOTTOLE						
LAST MOD :		READ PASSWORD	: NONE					
SCHEMA :	CACCOM	MODIFY PASSWOR	ED : NONE					
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SCHEMA :	CACCOM	MODIFY PASSWOR	RD : NONE					
NAME	TYPE	LENGTH	KEY					
ANUM	INT	1	YES					
CREWSTAN		1	YES					
TITLENUM		1	YES					
FMTTYPE	INT	1						

RELATION : TYPETWO LAST MOD : 93/03/04 READ PASSWORD : NONE SCHEMA : CACCOM MODIFY PASSWORD : NONE NAME TYPE LENGTH KEY ANUM INT YES TITLENUM INT 1 YES CREWSTAN INT YES LINEMNUM INT 1 LINEMVAL REAL 1 MNUM INT 1 LOWVAL REAL 1 LOWCLR REAL UPVAL REAL UPCLR REAL DEGSUBT REAL CURRENT NUMBER OF ROWS = RELATION : CLRNOTE LAST MOD : 93/03/04 READ PASSWORD : NONE SCHEMA : CACCOM MODIFY PASSWORD : NONE NAME TYPE LENGTH KEY ANUM INT YES TITLENUM INT 1 YES **CREWSTAN** INT 1 YES CNOTENUM INT CURRENT NUMBER OF ROWS = 10 RELATION : MNAME LAST MOD : 93/03/04 READ PASSWORD : NONE SCHEMA : CACCOM MODIFY PASSWORD : NONE NAME TYPE LENGTH KEY MNUM INT MNAME TEXT 35 CHARACTERS CURRENT NUMBER OF ROWS = RELATION : LINEMNAM LAST MOD : 93/03/04 READ PASSWORD : NONE SCHEMA : CACCOM MODIFY PASSWORD : NONE NAME TYPE LENGTH KEY LINEMNUM INT LINEMNAM TEXT 35 CHARACTERS CURRENT NUMBER OF ROWS = 1 RELATION : REGION LAST MOD : 93/03/04 READ PASSWORD : NONE SCHEMA : CACCOM MODIFY PASSWORD : NONE NAME TYPE LENGTH KEY REGNUM INT 1 REGION 30 CHARACTERS TEXT

RELATION : VNOTE

LAST MOD: 93/03/04 READ PASSWORD: NONE SCHEMA : CACCOM MODIFY PASSWORD : NONE

LENGTH

1

KEY

VNOTENUM INT

TYPE

NAME

120 CHARACTERS VNOTE TEXT

CURRENT NUMBER OF ROWS =

RELATION : CNOTE

LAST MOD: 93/03/04 READ PASSWORD: NONE SCHEMA : CACCOM MODIFY PASSWORD : NONE

NAME TYPE KEY LENGTH

CNOTENUM INT 1

TEXT 120 CHARACTERS CNOTE

CURRENT NUMBER OF ROWS =

RELATION : RNOTE

LAST MOD : 93/03/04 READ PASSWORD : NONE SCHEMA : CACCOM MODIFY PASSWORD : NONE

LENGTH NAME TYPE KEY

RNOTENUM INT

TEXT 120 CHARACTERS RNOTE

CURRENT NUMBER OF ROWS = 0

RELATION : VISION

LAST MOD : 93/03/04 READ PASSWORD : NONE SCHEMA : CACCOM MODIFY PASSWORD : NONE

NAME TYPE LENGTH KEY ANUM INT YES VIEWNUM INT 1 YES HEADPOSN INT 1 YES CREWSTAN INT YES MINEHT REAL REAL MINVDEG REAL MAXEHT MAXVDEG REAL ABVGLARE REAL GLAREHT REAL BLWGLARE REAL

CURRENT NUMBER OF ROWS = 60

RELATION : CREWREG

LAST MOD : 93/03/04 READ PASSWORD : NONE SCHEMA : CACCOM MODIFY PASSWORD : NONE

NAME TYPE LENGTH KEY ANUM INT 1 YES CREWSTAN INT 1 YES REGNUM INT

RELATION : VISADJ

LAST MOD : SCHEMA :	93/03/04 CACCOM	READ PASSWORD : MODIFY PASSWORD	NONE : NONE
NAME	TYPE	LENGTH	KEY
ANUM VIEWNUM HEADPOSN CREWSTAN ADJDEG	INT INT INT INT REAL	1 1 1 1	YES YES YES YES

CURRENT NUMBER OF ROWS = 16

RELATION . TYPEONE

LAST MOD :	03/03/04		
	93/03/04	READ PASSWORD :	NONE
SCHEMA :	CACCOM	MODIFY PASSWORD	: NONE
NAME	TYPE	LENGTH	KEY
ANUM	INT	1	YES
TITLENUM	INT	1	YES
CREWSTAN	INT	ī	YES
SEATPOS	INT	ī	120
MNUM	INT	ī	
MVAL	REAL	1	
CLRCHNG	REAL	1	

RELATION: AIRCRAFT RELATION: AIRDESC RELATION: CATNAME RELATION: CREWSTA RELATION: AIRCREW RELATION: AIRREG ANAMB CATNAME FIGHTER CARGO TRAINER CREWSTA CREWSTAN lept Right Porward Apt CATNUM REGNUM ADESC CREWSTAN ANUM CATNUM ANUM ANUN ANUM

RELATION: CONTROL

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CONTNUM CONTNAME

100 AC-FUSES-LOWERNOST-RT

130 AC-FUSES-LOWERNOST-RT

145 ADF-CONTEL-TR-2

146 ADF-CONTEL-TR-2

157 ADI-LT

202 ARRIAL-REPUBL-LTS

310 ALLERON-TRIM-LOWER

311 AIRS-DANTEL-RASTER-KNOB

312 AILERON-TRIM-LOWER

313 AIR-CONTEL-RASTER-KNOB

314 AIRS-DANCH-KNOS-LT

315 AIR-CONTEL-RASTER-KNOB

316 AIR-REPUBL-CON-CLO

317 AIRS-CONTEL-RASTER-ROG-RT

318 AIR-CONTEL-RASTER-ROG-RT

319 AIR-REPUBL-OFN-CLO

311 AIRSPD-HACH-IND

312 AILERER-ADJUSTMENT-RNOB

412 AILTIMETER-ADJUSTMENT-RNOB

414 AITIMETER-ABI-IND-SEEW-TOGG-RT

415 ALTIMETER-SEE-ENOB

416 ALTIMETER-SEE-ENOB

416 ALTIMETER-SEE-ENOB

416 ALTIMETER-SEE-ENOB

417 ALTIMETER-SEE-ENOB

418 ALTIMETER-SEE-ENOB

419 ANTIMETER-SEE-ENOB

410 ALTIMETER-SEE-ENOB

411 ALTIMETER-SEE-ENOB

412 ALTIMETER-SEE-ENOB

414 ALTIMETER-SEE-ENOB

415 ANTIMENNA-SEE-UHB

515 ANTI-COLITISION-BRACON-LTS-SWTCH

515 ANTI-COLITISION-BRACON-LTS-SWTCH

516 ANTI-COLITISION-BRACON-LTS-SWTCH
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CONTRL-STICK-GRIP-LT-COCKPIT-PULL-PWD-LT CONTRL-STICK-GRIP-LT-COCKPIT-NEUTRAL CONTRL-STICK-NEUTRAL CONTRL-STICK-GRIP-RT-COCKPIT-FULL-FWD-LT CONTRL-STICK-GRIP-RT-COCKPIT-NBUTRAL CIRCUIT-BREAKER-PANEL-ARC-164 CIRCUIT-BREAKER-PANEL-CAUTION-WARNING COCKPIT-AIR-TEMP-CONTRL-RHEOSTAT COCKPIT-AIR-TEMP-CONTRL-SWTCH COMM-ANTENNA-SWTCH DC-CIRCUIT-BREAKERS-LOWERMOST-RT DC-CIRCUIT-BREAKERS-UPPERMOST-RT CABIN-PRESSURE-SWICH-RAM-DUMP CO-PILOT-NAV-SEL-PN-SEL-NORM CO-PILOT-SIDE-CONSOLE-LTS CIRCUIT-BREAKER-PANEL-XMTR-1 COMMAND-AND-NAV-O'RIDE-SWTCH COMPASS-SWTCH COORDINATED-TURN-THUMB-WHEEL CABIN-AIR-OV-HT-ANNUNCIATOR DIGITAL-CLOCK-TIME-SWTCH-RT DISP-DIM-PANKL-AIR-DATA-RT DISP-DIMMING-SWTCH-RADI-LT BRAKE-PRESSURE-NORM-EMERG CANOPY-DR-CLUTCH-T-HANDLE AOA - INDEXER - LIGHTS - DIMMER CRS-OFF-VOR-LOC-L-NAV-LT CRS-OFF-VOR-LOC-L-NAV-RT CANOPY-JETTISON-T-HANDLE CONTRL-STICK-FULL-FWD-LT CONTRL-YOKE-PULL-PWD-LT CONTRL-YOKK-FULL-FWD-RT CLIMB-DIVE-PULL-TO-CAGE CABIN-TEMP-CONTRL-KNOB CONTRL-YOKE-NEUTRAL-LT DOWNLOCK-O'RIDE-BUTTON CONTRL-YOKE-NEUTRAL-RT CARGO-DOORS-ALL-DOORS CANOPY-LOCKING-LEVER CABIN-AIR-TEMP-SNTCH COMM-PANEL-NAV-2-RT COMM-PANEL-UHF-LT BOOST-PUMP-LT-SWTCH BOOST-PUMP-RT-SWTCH CANOPY - DEPOG-KNOB CHUTE-REL-REL-OFF COCKPIT-AIR-LEVER BDHI-SBT-INDX-LT CABIN-CONTROLLER CABIN-DUMP CLOCK-SET-BUTTON CHUTE-REL-EMERG CROSSFEED-SWTCH AUTO-PILOT-TURN AUX-GBAR-CONTRL CLOCK-PUSH-HARD BRAKE-T-HANDLE BAILOUT-ALARM BATTERY-SWTCH BDHI-VOR-2-LT CAGING-SWTCH DEFOG-LEVER CONTRL-GRIP COURSE-SEL BOT-2-ARM DIS/LTS 3065 3301 3884 1439 2040 2100 2157 2665 3282 3615 2160 2280 2411 2663 2917 1967 2971 1998 3025 3339 3430 1490 9651 598 588 9091 1610 9501 3061 3062 576 580 1554 559 571 596 1595 1597 600 601 609 611 001

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HRADING-IND-CUTOUT-E-FAST-SLAVE-SWICH
HORIZ-STAB-DE-ICE-BACKUP-MAN-NORM
HSI-COURSE-SEIT-RNOB
HSI-COURSE-SEIT-RNOB-LT
HSI-COURSE-SEIT-RNOB-RI
HSI-COURSE-SEIT-RNOB-RI
            RPIS-NAV-COMM-PANBLS-LOWER-LT-SCREW
RPIS-NAV-COMM-PANBLS-LOWER-RT-SCREW
BRIS-NAV-COMM-PANBLS-UPPERR-LT-SCREW
BRIS-NAV-COMM-PANBLS-UPPERR-RT-SCREW
LT-EJECTION-SEAT-HAND-GRIPS
RT-EJECTION-SEAT-HAND-GRIPS
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RT-FUEL-X-PEED-L-TANK-NORM-R-TANK
FUEL-X-PEED-L-TANK-NORM-R-TANK
FUEL-X-PEED-L-TANK-NORM-R-TANK
FUEL-SYSTEM-SWTCH
FWD-CIRCUIT-BRIK-PANEL-F-H-INST
GRAR-AUDIBLE-SILENCE-SWTCH
GRAR-UP-WARNING
LT-GENERATOR-SWTCH
RT-GENERATOR-SWTCH
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HSI-PULL-TO-CAGE
HYD-LEVEL-LO-ANNUNCIATOR
HYDRAULIC-PRESS-SWTCH-REL-NORM
IFF-IDENT
                                                                                                                                EMERG-CABIN-DEPRESS-T-HANDLE
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FUEL-SHUTOFF-SWICH-L
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PIRE-EXTINGUISH-T-HANDLE-4
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ILS-CONTRL-PANEL-POWER
                                                                                                                                                                                                                                                              engine - Fire-Detect-Swich
Engine - Fire-Test-4
Engine - Start-Botton-L
Engine - Start-Botton-L
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LT-IGNITION-SWICH
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buerg-press-le-togg
buerg-stores-jettison
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FUEL-GAGING-SEL-SWICH
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head-up-disp-filter
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DOWNLOCK-REL

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press-to-test-swich-for-light-in-lt-purl-shutopp-t-handle
press-to-test-swich-for-light-in-rt-purl-shutopp-t-handle
primary-plight-instrs-lts-rhegstat-apt
                                                                                                                                                                                                                                                                                                                                                                         LIGHTING-CONTRL-PANEL-COCKPIT-FLOOD-KNOB
LIGHTING-CONTRL-PANEL-WARNING-TEST-SWTCH
LO-FILTER-BYPASS-ANNUNCIATOR
LOBING-SWTCE
                                                                                                                                                                                                                                                                                                             LANDING-GEAR-WARNING-LIGHT-SIL-BUTTON
                                                                                                                                                                                                                                                                                                                            Landing-grap-warning-light-test-bwtch
                                                                                                                                                                                        Landing-Obar-Emerg-O'ride-Swych-Ly
Landing-Obar-Emerg-O'ride-Swych-Ry
Landing-Obar-Emerg-Y-Handle
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      OXY-8BL-SWTCH-NORM-OXY-MASK-LT

OXY-SUPP-LEVER-LT

OXY-SUPP-LEVER-LT

OXY-SUPP-OM-OYP-MASK-RT

OXY-SUPP-OM-OYP-RT

OXY-SUPP-LEVER-RT

OXY-SUPP-LY-SWTCH-100%-NORM

OXY-SUPP-LY-SWTCH-100%-NORM-TEST

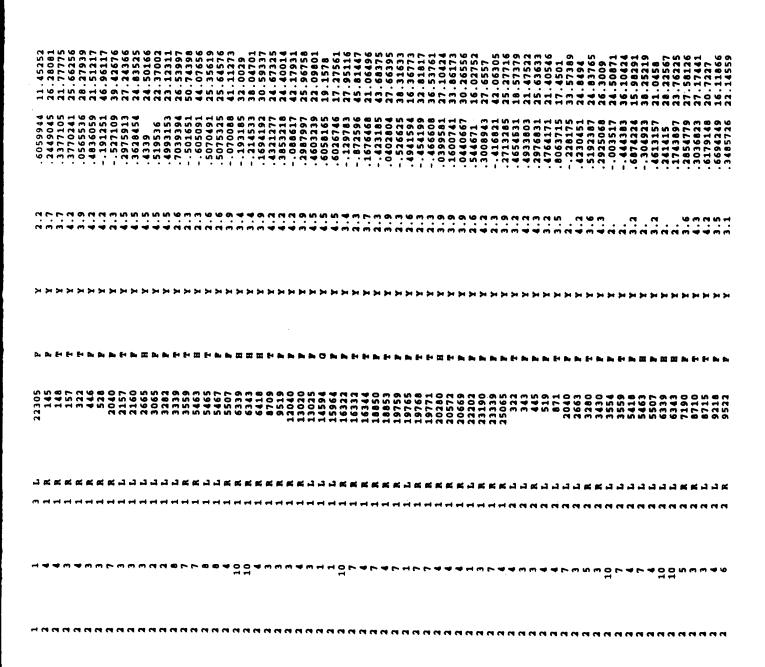
OXY-SUPP-LY-SWTCH-100%-NORM
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Pilot-side-console-lts
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NAV-MODE-SWTCH-TACAN
                                                                        INTERCOM-SWTCH-INTER
INTERCOM-SWTCH-NAV
INVERTER-SWTCH-
JET-PUEL-START-3
LANDING-6-TAXI-LTS-SWTCH
LANDING-GEAR-ALT-REL-HANDLE
LANDING-GEAR-DOWNLOCK-REL
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        OXY-REG-FLOW-ENERG-NORM-LT
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        MASTER-GENERATOR-L-GEN
MENU-DISP-AVIONICS-STATUS
                                                                                                                                                                                                                                                                                                                                                                                                                                         MACE - INCREASE - TODO
MACE - KNOTS - SLEW - LEVER - LT
MAIN - PWR - BATT
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INBRTIA-REBL-LOCK-LEVER
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         MASTER-CAUTION-RESET-LT
MASTER-CAUTION-RESET-RT
                                                                                                                                                                                                                                          LAND ING-GEAR-HANDLE
LAND ING-GEAR-HANDLE-LT
LAND ING-GEAR-HANDLE-RT
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                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         OXY-DILUTER-LEVER-LT
OXY-DILUTER-LEVER-RT
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          Master-Caution-Light
                                                                                                                                                                                                                                                                                                                                                             LE-BNGINE-FIRE-PUSH
                            INTERCOM-SWTCH-COMM
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         MANUAL-PITCH-O'RIDE
                                                                                                                                                                                                                                                                                             LANDING-GRAR-LEVER
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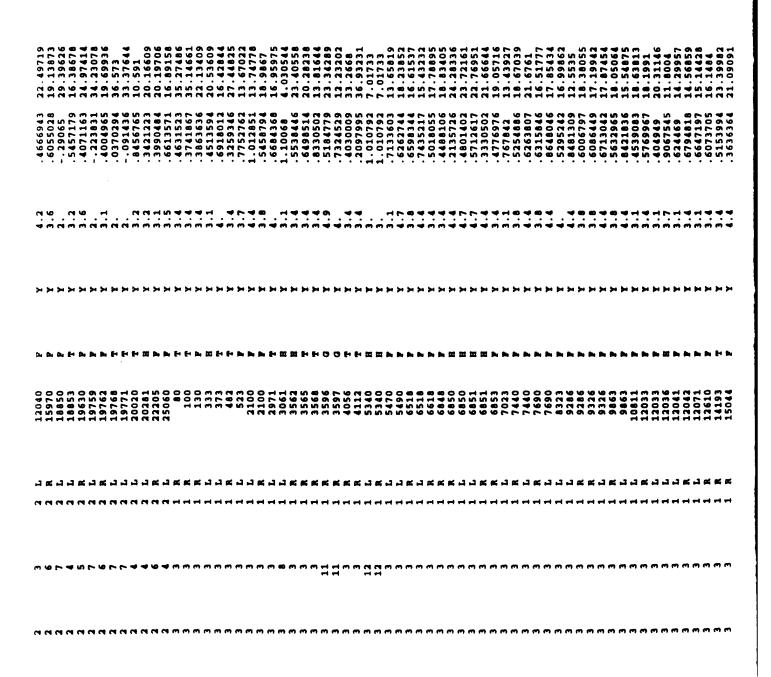
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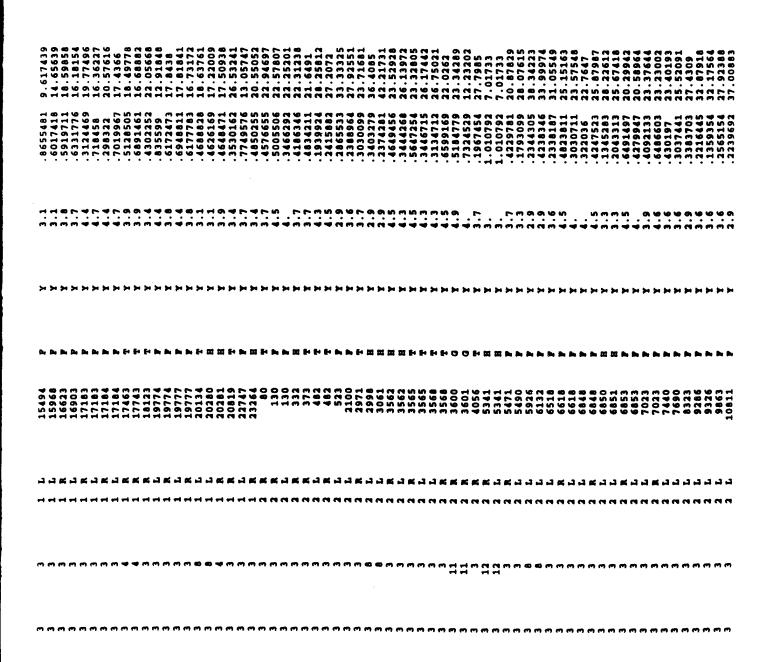
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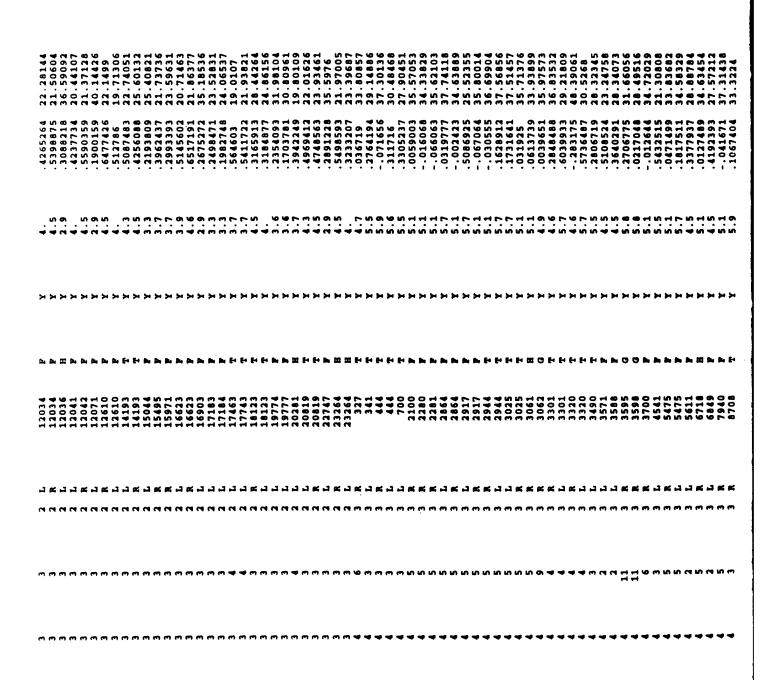
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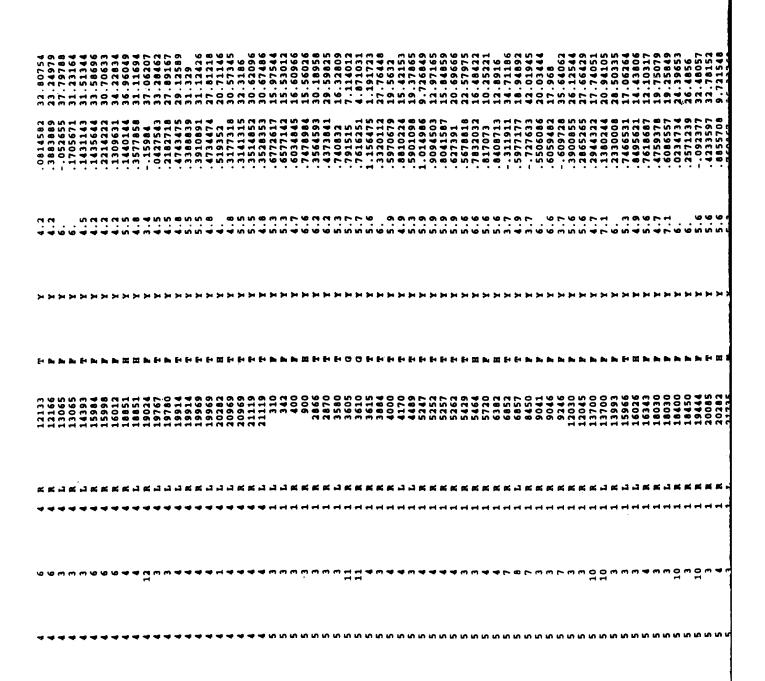








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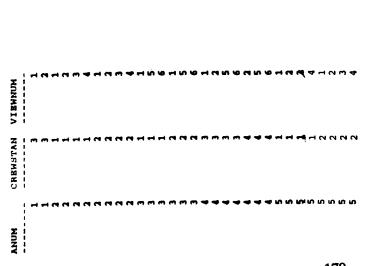
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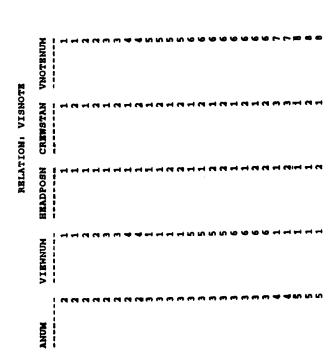
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RELATION: MNAME

KNAMB BUTTOCK-KNEE-LENGTH LEGO-LENGTH
---------------------------------------------

RELATION: LINEMNAM

LINBMNAM		KNEE-HEIGHT-SITTING
LINEMAGE	1 1 1 1	529

RELATION: REGION

REGION		LEFT-SIDE-PANEL	LEPT-AUXILIARY-PANEL	HAIN-INSTRUMENT-PANEL	CHNTHR-PEDROTAL	RIGHT-AUXILIARY-PANBL	RIGHT-SIDE-PANEL	Overhead-Control-Panel	LEPT-BULKHEAD	Richt-Bulkhrad	OLARE-BHIELD	CONTROL-STICK	BEAT
REGNUM	1 1 1 1 1 1	-	~	m	◀	10	•	7	-	•	10	11	2

VNOTE

VNOTBNUM

Moving seat full aft loses 2 degrees in each position.

Moving seat aft loses 3.5 degrees in each position.

Moving seat aft loses 2.6 degrees in each position.

Moving seat aft loses 11 degrees in each position.

Narthe seat goes down they see more.

As the seat goes down they see more.

Add 1 degree per inch from 30 inches to 36 inches: Add 2 degrees per bata available for forward positions only.

## RELATION: CNOTE

CNOTE

CNOTENUM

These values allow 1.5 inches for the HGU-55/P and 1 inch space over Thigh held perpendicular to ejection rail.
Clearance space overhead for mobility is 1 inch.
Data is available for full forward positions only.
Data is available for full aft positions only.

# RELATION: RNOTE

RNOTE RNOTENDM

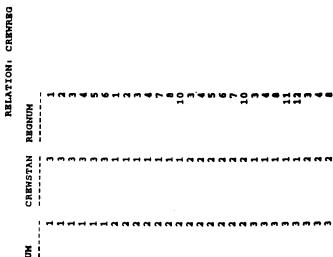
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ABVGLARE

	BLWGLARE		-2.89	-2		0.7.		-		-1.		-			. T.	-1.5	4				-1.9	-1.5	۲.		6875	6175	6875	6875	-2 1976		0/01.7	-2.1875	-2.1075	-2.1075	-2.1875
	GLARBHT		76.	26.			. 92	29.			78.	29.	36			25.	25.	25				. 52	25.	25.	25.	25.	25.	25	25.				25.	25.	25.
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-	MAXVDEG		-31.14	-32.	-32.			-23.	-22		. 97-	-76.	-30.5	30.5		- 24.5	-32.5	-37.5	-37.5	7 61-		n .		20.	-10.	-10.	-20.	-20.	-1.75	-1.75	36		6/ .5-	-13.75	-13.75
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RELATION: VISION	CREWSTAN		•	-	~	<b>(</b>	•	4	~	-	•	•	-	~	-	•	•	<b>-</b>	~		~	-		•	<b>-</b>	٠.	~ (	PQ •	-	~		~	•	• •	•
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2.4 /1" OFF SEATADJ -2.89 /EYE-HT-SIT

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-2.1875	-2.1875				-1.2	٥.	-1.2		-1.6		-1.6	0	-1.6		-1.6	-3.	-2	-3.	-3.	-2.	-2.	-3.	-3.	-3.	-2.	-5.	-3.	-1.8	-1.0	-1.0	-1.8
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### INFORMIX CPLOAD.COM

```
FILE "aircraft.load" DELIMITER ":" 3 ;
INSERT INTO aircraft:
FILE "catname.load" DELIMITER ":" 2;
INSERT INTO catname:
FILE "crewsta.load" DELIMITER ":" 2;
INSERT INTO crewsta;
FILE "aircrew.load" DELIMITER ":" 2;
INSERT INTO aircrew:
FILE "airreg.load" DELIMITER ": " 2;
INSERT INTO airreg;
FILE "control.load" DELIMITER ":" 2;
INSERT INTO control;
FILE "crewcont.load" DELIMITER ":" 3 ;
INSERT INTO crewcont:
FILE "seatadj.load" DELIMITER ":" 4;
INSERT INTO seatadj;
FILE "reach.load" DELIMITER ":" 10 ;
INSERT INTO reach:
FILE "view.load" DELIMITER ":" 2;
INSERT INTO view;
FILE "crewview.load" DELIMITER ":" 3 ;
INSERT INTO crewview;
FILE "visnote.load" DELIMITER ":" 5;
INSERT INTO visnote;
FILE "clrtitle.load" DELIMITER ":" 3 ;
INSERT INTO cirtitle;
FILE "crewtitl.load" DELIMITER ":" 4 ;
INSERT INTO crewtitl;
FILE "typetwo.load" DELIMITER ":" 11;
INSERT INTO typetwo;
FILE "clrnote.load" DELIMITER ":" 4;
INSERT INTO clrnote;
FILE "mname.load" DELIMITER ":" 2;
INSERT INTO mname:
FILE "linemnam.load" DELIMITER ":" 2 ;
INSERT INTO linemnam;
FILE "region.load" DELIMITER ": " 2;
INSERT INTO region;
FILE "vnote.load" DELIMITER ":" 2;
INSERT INTO vnote;
FILE "cnote.load" DELIMITER ":" 2;
INSERT INTO cnote;
FILE "vision.load" DELIMITER ":" 11;
INSERT INTO vision;
```

```
FILE "crewreg.load" DELIMITER ":" 3;
INSERT INTO crewreg;

FILE "visadj.load" DELIMITER ":" 5;
INSERT INTO visadj;

FILE "typeone.load" DELIMITER ":" 7;
INSERT INTO typeone;
```

### INFORMIX COCKPIT DATABASE SCHEMA

```
create table "card".crewcont
    anum smallint not null,
   .crewstan smallint not null,
    contnum smallint not null
revoke all on "card".crewcont from "public";
{ TABLE "card".seatad; row size = 23 number of columns = 4 index size = 0 }
{ unload file name = seatadj108.unl number of rows = 7 }
create table "card".seatadj
    anum smallint not null,
    adjdir char(1),
    adjinc decimal(16),
    maxadj decimal(16)
revoke all on "card".seatadj from "public";
{ TABLE "card".reach row size = 41 number of columns = 10 index size = 0 }
{ unload file name = reach__110.unl number of rows = 474 }
create table "card".reach
    anum smallint not null,
    regnum smallint not null,
    crewstan smallint not null,
    conthand char(1) not null,
    contnum smallint not null,
    conttype char(1),
    measured char(1),
    z2factor decimal(16).
    shscoef decimal(16),
    constant decimal(16)
revoke all on "card".reach from "public";
{ TABLE "card".rchnote row size = 11 number of columns = 6 index size = 0 }
{ unload file name = rchnotell1.unl number of rows = 0 }
create table "card".rchnote
    anum smallint not null,
    regnum smallint not null,
    crewstan smallint not null,
    conthand char(1) not null,
    contnum smallint not null,
    rnotenum smallint not null
  );
revoke all on "card".rchnote from "public";
{ TABLE "card".view row size = 62 number of columns = 2 index size = 0 }
{ unload file name = view 112.unl number of rows = 6 }
create table "card".view
    viewnum smallint not null,
    view char (60) not null
revoke all on "card".view from "public";
{ TABLE "card".crewview row size = 6 number of columns = 3 index size = 0 }
{ unload file name = crewviel13.unl number of rows = 31 }
```

```
create table "card".crewview
    anum smallint not null,
    crewstan smallint not null,
    viewnum smallint
revoke all on "card".crewview from "public";
{ TABLE "card".visnote row size = 10 number of columns = 5 index size = 0 }
{ unload file name = visnotel14.unl number of rows = 16 }
create table "card".visnote
    anum smallint not null,
    viewnum smallint not null,
    headposn smallint not null,
    crewstan smallint not null,
    vnotenum smallint
  );
revoke all on "card".visnote from "public";
{ TABLE "card".clrtitle row size = 63 number of columns = 3 index size = 0 }
{ unload file name = clrtitl115.unl number of rows = 5 }
create table "card".clrtitle
    titlenum smallint not null,
    title char(60),
    min char(1)
revoke all on "card".clrtitle from "public";
{ TABLE "card".crewtitl row size = 8 number of columns = 4 index size = 0 }
{ unload file name = crewtit116.unl number of rows = 32 }
create table "card".crewtitl
    anum smallint not null,
    crewstan smallint not null,
    titlenum smallint not null,
    fmttype smallint
  );
revoke all on "card".crewtitl from "public";
{ TABLE "card".typetwo row size = 70 number of columns = 11 index size = 0 }
{ unload file name = typetwoll7.unl number of rows = 2 }
create table "card".typetwo
  (
    anum smallint not null,
    titlenum smallint not null,
    crewstan smallint not null,
    linemnum smallint,
    linemval decimal(16),
    mnum smallint,
    lowval decimal(16),
    lowclr decimal(16),
    upval decimal(16),
    upclr decimal(16),
    degsubt decimal(16)
revoke all on "card".typetwo from "public";
{ TABLE "card".clrnote row size = 8 number of columns = 4 index size = 0 }
{ unload file name = clrnotell8.unl number of rows = 10 }
```

```
create table "card".clrnote
     anum smallint not null,
     titlenum smallint not null,
     crewstan smallint not null,
     cnotenum smallint
   );
 revoke all on "card".clrnote from "public";
 { TABLE "card".mname row size = 37 number of columns = 2 index size = 0 }
 { unload file name = mname 119.unl number of rows = 4 }
 create table "card".mname
     mnum smallint not null,
     mname char (35)
revoke all on "card".mname from "public";
 { TABLE "card".linemnam row size = 37 number of columns = 2 index size = 0 }
 { unload file name = linemna120.unl number of rows = 1 }
create table "card".linemnam
    linemnum smallint not null,
    linemnam char (35)
revoke all on "card".linemnam from "public";
{ TABLE "card".region row size = 32 number of columns = 2 index size = 0 }
{ unload file name = region_121.unl number of rows = 12 }
create table "card".region
    regnum smallint not null,
    region char (30)
revoke all on "card".region from "public";
{ TABLE "card".vnote row size = 122 number of columns = 2 index size = 0 }
{ unload file name = vnote__122.unl number of rows = 1 }
create table "card".vnote
    vnotenum smallint not null,
    vnote char (120)
  );
revoke all on "card".vnote from "public";
{ TABLE "card".cnote row size = 122 number of columns = 2 index size = 0 }
{ unload file name = cnote__123.unl number of rows = 5 }
create table "card".cnote
    cnotenum smallint not null,
    cnote char (120)
  );
revoke all on "card".cnote from "public";
{ TABLE "card".rnote row size = 122 number of columns = 2 index size = 0 }
{ unload file name = rnote__124.unl number of rows = 0 }
create table "card".rnote
    rnotenum smallint not null,
                                     181
    rnote char (120)
```

```
revoke all on "card".rnote from "public";
{ TABLE "card".vision row size = 78 number of columns = 11 index size = 0 }
{ unload file name = vision 125.unl number of rows = 60 }
create table "card".vision
   anum smallint not null,
   viewnum smallint not null,
   headposn smallint not null,
   crewstan smallint not null,
   mineht decimal(16),
   minvdeg decimal (16),
   maxeht decimal(16),
   maxvdeg decimal (16),
   abvglare decimal(16),
    glareht decimal(16),
   blwglare decimal(16)
  );
revoke all on "card".vision from "public";
{ TABLE "card".crewreg row size = 6 number of columns = 3 index size = 0 }
{ unload file name = crewreg126.unl number of rows = 58 }
create table "card".crewreg
  (
    anum smallint not null,
    crewstan smallint not null,
    regnum smallint
  );
revoke all on "card".crewreg from "public";
{ TABLE "card".visadj row size = 18 number of columns = 5 index size = 0 }
{ unload file name = visadj_127.unl number of rows = 16 }
create table "card".visadj
    anum smallint not null,
    viewnum smallint not null,
    headposn smallint not null,
    crewstan smallint not null,
    adjdeg decimal(16)
revoke all on "card".visadj from "public";
{ TABLE "card".typeone row size = 30 number of columns = 7 index size = 0 }
{ unload file name = typeone128.unl number of rows = 58 }
create table "card".typeone
    anum smallint not null,
    titlenum smallint not null,
    crewstan smallint not null,
    seatpos smallint not null,
    mnum smallint,
    mval decimal(16),
    clrchng decimal(16)
  );
revoke all on "card".typeone from "public";
{ TABLE "card".aircraft row size = 12 number of columns = 3 index size = 0 }
{ unload file name = aircraf129.unl number of rows = 5 }
create table "card".aircraft
                                      182
```

```
anum smallint not null,
     catnum smallint,
     aname char(8)
 revoke all on "card".aircraft from "public";
 grant select on "card".airdesc to "public" as "card";
 grant update on "card".airdesc to "public" as "card";
 grant insert on "card".airdesc to "public" as "card";
 grant delete on "card".airdesc to "public" as "card";
 grant index on "card".airdesc to "public" as "card";
 grant select on "card".catname to "public" as "card";
 grant update on "card".catname to "public" as "card";
 grant insert on "card".catname to "public" as "card";
 grant delete on "card".catname to "public" as "card";
 grant index on "card".catname to "public" as "card";
 grant select on "card".crewsta to "public" as "card";
 grant update on "card".crewsta to "public" as "card";
 grant insert on "card".crewsta to "public" as "card";
 grant delete on "card".crewsta to "public" as "card";
 grant index on "card".crewsta to "public" as "card";
 grant select on "card".aircrew to "public" as "card";
 grant update on "card".aircrew to "public" as "card";
grant insert on "card".aircrew to "public" as "card";
grant delete on "card".aircrew to "public" as "card";
grant index on "card".aircrew to "public" as "card";
 grant select on "card".airreg to "public" as "card";
grant update on "card".airreg to "public" as "card";
grant insert on "card".airreg to "public" as "card";
grant delete on "card".airreg to "public" as "card";
grant index on "card".airreg to "public" as "card";
grant select on "card".control to "public" as "card";
grant update on "card".control to "public" as "card";
grant insert on "card".control to "public" as "card";
grant delete on "card".control to "public" as "card";
grant index on "card".control to "public" as "card";
grant select on "card".crewcont to "public" as "card";
grant update on "card".crewcont to "public" as "card";
grant insert on "card".crewcont to "public" as "card";
grant delete on "card".crewcont to "public" as "card";
grant index on "card".crewcont to "public" as "card";
grant select on "card".seatadj to "public" as "card";
grant update on "card".seatadj to "public" as "card";
grant insert on "card".seatadj to "public" as "card";
grant delete on "card".seatadj to "public" as "card";
grant index on "card".seatadj to "public" as "card";
grant select on "card".visnote to "public" as "card";
grant update on "card".visnote to "public" as "card";
grant insert on "card".visnote to "public" as "card";
grant delete on "card".visnote to "public" as "card";
grant index on "card".visnote to "public" as "card";
grant select on "card".reach to "public" as "card";
grant update on "card".reach to "public" as "card";
grant insert on "card".reach to "public" as "card";
grant delete on "card".reach to "public" as "card";
grant index on "card".reach to "public" as "card";
grant select on "card".rchnote to "public" as "card";
grant update on "card".rchnote to "public" as "card";
grant insert on "card".rchnote to "public" as "card";
grant delete on "card".rchnote to "public" as "card";
grant index on "card".rchnote to "public" as "card";
grant select on "card".view to "public" as "card";
grant update on "card".view to "public" as "card";
grant insert on "card".view to "public" as "card";
```

```
grant delete on "card".view to "public" as "card";
grant index on "card".view to "public" as "card";
grant select on "card".crewview to "public" as "card";
grant update on "card".crewview to "public" as "card";
grant insert on "card".crewview to "public" as "card";
grant delete on "card".crewview to "public" as "card";
grant index on "card".crewview to "public" as "card";
grant select on "card".clrtitle to "public" as "card";
grant update on "card".clrtitle to "public" as "card";
grant insert on "card".clrtitle to "public" as "card";
grant delete on "card".clrtitle to "public" as "card";
grant index on "card".clrtitle to "public" as "card";
grant select on "card".crewtitl to "public" as "card";
grant update on "card".crewtitl to "public" as "card";
grant insert on "card".crewtitl to "public" as "card";
grant delete on "card".crewtitl to "public" as "card";
grant index on "card".crewtitl to "public" as "card";
grant select on "card".typetwo to "public" as "card";
grant update on "card".typetwo to "public" as "card";
grant insert on "card".typetwo to "public" as "card";
grant delete on "card".typetwo to "public" as "card";
grant index on "card".typetwo to "public" as "card";
grant select on "card".clrnote to "public" as "card";
grant update on "card".clrnote to "public" as "card";
grant insert on "card".clrnote to "public" as "card";
grant delete on "card".clrnote to "public" as "card";
grant index on "card".clrnote to "public" as "card";
grant select on "card".mname to "public" as "card";
grant update on "card".mname to "public" as "card";
grant insert on "card".mname to "public" as "card";
grant delete on "card".mname to "public" as "card";
grant index on "card".mname to "public" as "card";
grant select on "card".linemnam to "public" as "card";
grant update on "card".linemnam to "public" as "card";
grant insert on "card".linemnam to "public" as "card";
grant delete on "card".linemnam to "public" as "card";
grant index on "card".linemnam to "public" as "card";
grant select on "card".region to "public" as "card";
grant update on "card".region to "public" as "card";
grant insert on "card".region to "public" as "card";
grant delete on "card".region to "public" as "card";
grant index on "card".region to "public" as "card";
grant select on "card".vnote to "public" as "card";
grant update on "card".vnote to "public" as "card";
grant insert on "card".vnote to "public" as "card";
grant delete on "card".vnote to "public" as "card";
grant index on "card".vnote to "public" as "card";
grant select on "card".cnote to "public" as "card";
grant update on "card".cnote to "public" as "card";
grant insert on "card".cnote to "public" as "card";
grant delete on "card".cnote to "public" as "card";
grant index on "card".cnote to "public" as "card";
grant select on "card".rnote to "public" as "card";
grant update on "card".rnote to "public" as "card";
grant insert on "card".rnote to "public" as "card";
grant delete on "card".rnote to "public" as "card";
grant index on "card".rnote to "public" as "card";
grant select on "card".vision to "public" as "card";
grant update on "card".vision to "public" as "card";
grant insert on "card".vision to "public" as "card";
grant delete on "card".vision to "public" as "card";
grant index on "card".vision to "public" as "card";
grant select on "card".crewreg to "public" as "card";
grant update on "card".crewreg to "public" as "card";
grant insert on "card".crewreg to "public" as "card";
grant delete on "card".crewreg to "public" as "card";
```

```
grant index on "card".crewreg to "public" as "card";
grant select on "card".visadj to "public" as "card";
grant update on "card".visadj to "public" as "card";
grant insert on "card".visadj to "public" as "card";
grant delete on "card".visadj to "public" as "card";
grant index on "card".visadj to "public" as "card";
grant select on "card".typeone to "public" as "card";
grant update on "card".typeone to "public" as "card";
grant insert on "card".typeone to "public" as "card";
grant delete on "card".typeone to "public" as "card";
grant index on "card".typeone to "public" as "card";
grant select on "card".aircraft to "public" as "card";
grant update on "card".aircraft to "public" as "card";
grant insert on "card".aircraft to "public" as "card";
grant delete on "card".aircraft to "public" as "card";
grant index on "card".aircraft to "public" as "card";
```

### INFORMIX DATABASE INTERFACE ROUTINES

```
#define MAX_AIRCRAFT 500
#define MAX_CATEGORIES 25
#define MAX_CLEARANCE_TYPES 10
#define MAX_CONTROLS 200
#define MAX_CREWSTATIONS 50
#define MAX_REGIONS 50
typedef struct _aircraft_category
       int catNumber[MAX_CATEGORIES];
       char *catName[MAX_CATEGORIES];
}AircraftCategory;
typedef struct _console_region
       int regionNumber[MAX_REGIONS];
       char *regionName[MAX_REGIONS];
)ConsoleRegion;
typedef struct _clearance_type
        int clearNumber[MAX_CLEARANCE_TYPES];
       char *clearMinimum[MAX_CLEARANCE_TYPES];
       char *clearTitle[MAX_CLEARANCE_TYPES];
)ClearanceType;
typedef struct _vertical_seat_position_data
                                                     /* 0 = no
                                                                  1 = yes
            seatAdjustsVertical[MAX_AIRCRAFT];
        int
                                                     /* 0 = notch 2 = inches */ ◆
        int vertSeatUnits[MAX_AIRCRAFT];
            vertSeatNumberOfIncrements[MAX_AIRCRAFT];
        float vertSeatTotalAdj[MAX_AIRCRAFT];
        float vertSeatMaxAdj[MAX_AIRCRAFT];
        float vertSeatAdjIncrements[MAX_AIRCRAFT];
}VerticalSeatData;
typedef struct _horizontal_seat_position_data
                                                     /* 0 = no 1 = yes
            seatAdjustsHorizontal[MAX_AIRCRAFT];
                                                     /* 0 = notch 1 = inches */
        int horzSeatUnits[MAX_AIRCRAFT];
        int horzSeatNumberOfIncrements(MAX_AIRCRAFT);
        float horzSeatTotalAdj[MAX_AIRCRAFT];
        float horzSeatMaxAdj[MAX_AIRCRAFT];
              horzSeatAdjIncrements[MAX_AIRCRAFT];
        float
}HorizontalSeatData;
typedef struct _console_controls
        int aircraftControl[MAX_AIRCRAFT] [MAX_CREWSTATIONS] [MAX_CONTROLS];
        int numberControlsThisAircraft[MAX_AIRCRAFT][MAX_CREWSTATIONS];
}ConsoleControls;
```

```
#include <stdio.h>
#include <string.h>
#include "aircraft.h"
EXEC SQL include sqlca;
EXEC SQL include sqlda;
AircraftCategory Category;
ConsoleRegion Console;
ClearanceType ClearType;
VerticalSeatData VertSeat;
HorizontalSeatData HorzSeat;
ConsoleControls Controls;
/* Declare the host variables for database queries */
EXEC SQL BEGIN DECLARE SECTION;
short i;
short ind, ind2;
                                 /* indexes from the database */
short field;
short desc_Count;
char *query_String;
char tempname [60];
EXEC SQL END DECLARE SECTION;
main()
{
/* Open the cockpit database */
        EXEC SQL database cockpit;
        getAircraftCategory();
        getConsoleRegion();
        getClearanceType();
        getSeatData();
        getConsoleControls();
void getAircraftCategory()
        register i;
/* Set up the query to the database */
        query_String = "select * from catname";
/* Define the descriptor for database access */
        EXEC SQL prepare qid from $query_String;
        EXEC SQL declare query_Cursor cursor for qid;
        EXEC SQL allocate descriptor 'queryDesc';
        EXEC SQL open query_Cursor;
        EXEC SQL describe qid using sql descriptor 'queryDesc';
        EXEC SQL get descriptor 'queryDesc' $desc_Count = count;
        for (i=1; i<= desc_Count; i++)</pre>
                prsqlda(i);
        for (;;)
                EXEC SQL fetch query_Cursor using sql descriptor 'queryDesc';
```

```
if (sqlca.sqlcode != 0) break;
                for (field = 1; field<= desc_Count; field++)</pre>
                switch(field)
                               /* catnum: category number */
                case 1:
                        EXEC SQL get descriptor 'queryDesc' value $field
                                 $ind = data;
                        Category.catNumber[ind] = ind;
                        printf("catnum: %d ",Category.catNumber[ind]);
                        break;
                                 /* catname: category name */
                case 2:
                        EXEC SQL get descriptor 'queryDesc' value $field
                                 $tempname = data;
                        Category.catName[ind] = tempname;
                        printf(" %s\n", Category.catName[ind]);
                        break:
                }
                }
        }
        EXEC SQL close query Cursor;
}
void getConsoleRegion()
        register i;
/* Set up the query to the database */
        query_String = "select * from region";
/* Define the descriptor for database access */
        EXEC SQL prepare qidl from $query String;
        EXEC SQL declare query Cursor1 cursor for qid1;
        EXEC SQL allocate descriptor 'queryDesc';
        EXEC SQL open query_Cursorl;
        EXEC SQL describe qidl using sql descriptor 'queryDesc';
        EXEC SQL get descriptor 'queryDesc' $desc_Count = count;
        for (i=1; i<= desc Count; i++)
                prsqlda(i);
        for (;;)
                EXEC SQL fetch query_Cursorl using sql descriptor 'queryDesc';
                if (sqlca.sqlcode != 0) break;
                for (field = 1; field<= desc_Count; field++)</pre>
                switch (field)
                                 /* regnum: region number */
                case 1:
                        EXEC SQL get descriptor 'queryDesc' value $field
                                 $ind = data;
                        Console.regionNumber[ind] = ind;
```

```
printf("regnum: %d ",Console.regionNumber[ind]);
                        break;
                case 2:
                                 /* catname: category name */
                        EXEC SQL get descriptor 'queryDesc' value $field
                                 $tempname = data;
                        Console.regionName[ind] = tempname;
                        printf(" %s\n", Console.regionName[ind]);
                        break;
                }
                }
        }
        EXEC SQL close query Cursor;
}
void getClearanceType()
        register i;
/* Set up the query to the database */
       query_String = "select * from clrtitle";
/* Define the descriptor for database access */
        EXEC SQL prepare qid2 from $query_String;
        EXEC SQL declare query_Cursor2 cursor for qid2;
        EXEC SQL allocate descriptor 'queryDesc';
        EXEC SQL open query Cursor2;
        EXEC SQL describe qid2 using sql descriptor 'queryDesc';
        EXEC SQL get descriptor 'queryDesc' $desc_Count = count;
        for (i=1; i<= desc_Count; i++)
                prsqlda(i);
        for (;;)
                EXEC SQL fetch query_Cursor2 using sql descriptor 'queryDesc';
                if (sqlca.sqlcode != 0) break;
                for (field = 1; field<= desc Count; field++)</pre>
                switch (field)
                ł
                case 1:
                                /* titlenum: clearance title number */
                        EXEC SQL get descriptor 'queryDesc' value $field
                                $ind = data;
                        ClearType.clearNumber[ind] = ind;
                        printf("clearNumber: %d ",ClearType.clearNumber[ind]);
                        break:
                case 2:
                                /* title: clearance title */
                        EXEC SQL get descriptor 'queryDesc' value $field
                                $tempname = data;
                        ClearType.clearTitle[ind] = tempname;
                        printf(" %s",ClearType.clearTitle[ind]);
                        break;
                case 3:
                                /* min: clearance minimum? y/n */
```

```
EXEC SQL close query Cursor;
}
void getSeatData()
        register i;
       EXEC SQL BEGIN DECLARE SECTION;
        char seatDir[2]; /* seat adj direction, v=vertical, h=horizontal */
        short adjType; /* seat adj type, 0=notches, 1=inches */
        short anum;
                         /* aircraft id number */
        float adjInc;
                         /* distance between each seat increment in inches */
        float maxAdj;
                         /* total seat travel in inches */
       EXEC SQL END DECLARE SECTION:
/* Set up the query to the database */
        query String = "select * from seatadj";
/* Define the descriptor for database access */
       EXEC SQL prepare qid3 from $query String;
       EXEC SQL declare query_Cursor3 cursor for qid3;
       EXEC SQL allocate descriptor 'queryDesc';
       EXEC SQL open query Cursor3;
       EXEC SQL describe qid3 using sql descriptor 'queryDesc';
       EXEC SQL get descriptor 'queryDesc' $desc_Count = count;
       for (i=1; i<= desc Count; i++)
                prsqlda(i);
       for (;;)
                EXEC SQL fetch query Cursor3 using sql descriptor 'queryDesc';
                if (sqlca.sqlcode != 0) break;
                for (field = 1; field <= desc Count; field ++)</pre>
                switch (field)
                case 1:
                               /* anum: aircraft number */
                        EXEC SQL get descriptor 'queryDesc' value $field
                                $anum = data;
                        break:
                                     190
                case 2:
```

EXEC SQL get descriptor 'queryDesc' value \$field

printf(" %s\n",ClearType.clearMinimum[ind]);

\$tempname = data;

break;

ClearType.clearMinimum[ind] = tempname;

```
EXEC SQL get descriptor 'queryDesc' value $field
                                 $seatDir = data;
                         break;
                 case 3:
                                 /* adjInc: adj increment */
                         EXEC SQL get descriptor 'queryDesc' value $field
                                 $adjInc = data;
                         break;
                 case 4:
                                 /* maxAdj: adj increment */
                         EXEC SQL get descriptor 'queryDesc' value $field
                                 $maxAdj = data;
                         break;
                 case 5:
                                 /* adjType: type of adj */
                         EXEC SQL get descriptor 'queryDesc' value $field
                                 $adjType = data;
                         break;
                 }
                 }
/* set the vertical/horizontal flags for each aircraft, figure out the
   number of notches */
                if (strcmp(seatDir, "V") == 0)
                         VertSeat.seatAdjustsVertical[anum] = 1;
                         VertSeat.vertSeatUnits[anum] = adjType;
                         VertSeat.vertSeatTotalAdj[anum] = maxAdj;
                         VertSeat.vertSeatAdjIncrements[anum] = adjInc;
                         VertSeat.vertSeatNumberOfIncrements[anum] = maxAdj/adjInc;
                 }
                else
                         VertSeat.seatAdjustsVertical[anum] = 0;
                 }
                if (strcmp(seatDir,"H") == 0)
                         HorzSeat.seatAdjustsHorizontal(anum) = 1;
                         HorzSeat.horzSeatUnits[anum] = adjType;
                         HorzSeat.horzSeatTotalAdj(anum) = maxAdj;
                         HorzSeat.horzSeatAdjIncrements(anum) = adjInc;
                         HorzSeat.horzSeatNumberOfIncrements(anum) = maxAdj/adjInc;
                }
                else
                {
                        HorzSeat.seatAdjustsHorizontal[anum] = 0;
                }
if (VertSeat.seatAdjustsVertical[anum])
printf("\n Seat adjustment data for %d \n",anum);
printf("seatAdjustsVertical: %d \n", VertSeat.seatAdjustsVertical[anum]);
printf("vertSeatUnits: %d\n", VertSeat.vertSeatUnits[anum]);
printf("vertSeatTotalAdj: %f\n", VertSeat.vertSeatTotalAdj[anum]);
printf("vertSeatAdjIncrements: %f\n", VertSeat.vertSeatAdjIncrements[anum]);
printf("vertSeatNumberOfIncrements: %d\n", VertSeat.vertSeatNumberOfIncrements[anum]
}
if (HorzSeat.seatAdjustsHorizontal[anum])
```

```
printf("\n Seat adjustment data for %d \n", anum);
printf("seatAdjustsHorizontal: %d \n", HorzSeat.seatAdjustsHorizontal[anum]);
printf("horzSeatUnits: %d\n", HorzSeat.horzSeatUnits[anum]);
printf("horzSeatTotalAdj: %f\n", HorzSeat.horzSeatTotalAdj[anum]);
printf("horzSeatAdjIncrements: %f\n", HorzSeat.horzSeatAdjIncrements[anum]);
printf("horzSeatNumberOfIncrements: %d\n", HorzSeat.horzSeatNumberOfIncrements[anum]
        }
        EXEC SQL close query Cursor3;
}
void getConsoleControls()
register i, j;
EXEC SQL BEGIN DECLARE SECTION;
short control number;
int
      ind3;
EXEC SQL END DECLARE SECTION;
/* Set up the query to the database */
        query_String = "select * from crewcont";
/* Define the descriptor for database access */
        EXEC SQL prepare qid4 from $query String;
        EXEC SQL declare query_Cursor4 cursor for qid4;
        EXEC SQL allocate descriptor 'queryDesc';
        EXEC SQL open query_Cursor4;
        EXEC SQL describe qid4 using sql descriptor 'queryDesc';
        EXEC SQL get descriptor 'queryDesc' $desc Count = count;
        for (i=1; i<= desc Count; i++)
                prsqlda(i);
        for (;;)
                EXEC SQL fetch query Cursor4 using sql descriptor 'queryDesc';
                if (sqlca.sqlcode != 0) break;
                for (field = 1; field<= desc Count; field++)</pre>
                switch (field)
                case 1:
                                 /* anum: aircraft number */
                        EXEC SQL get descriptor 'queryDesc' value $field
                                 $ind = data;
                        break:
                case 2:
                                 /* crewstan: crewstation number */
                        EXEC SQL get descriptor 'queryDesc' value $field
                                 $ind2 = data;
                        break;
                                       192
```

```
case 3:
                                 /* contnum: control number */
                         EXEC SQL get descriptor / queryDesc' value $field
                                 $control number = data;
                         break:
                 }
                 }
                ++Controls.numberOfControls[ind][ind2];
                ind3 = Controls.numberOfControls[ind][ind2];
                Controls.aircraftControl[ind][ind2][ind3] = control number;
                printf("anum: %d crew: %d control: %d\n",ind,ind2,
                        Controls.aircraftControl[ind][ind2][ind3]);
        }
                for (i=1;i<=3;i++)
                   for (j=1; j<=2; j++)
                        printf("# of controls: [ %d ] [ %d ] = %d\n",i,j,
                }
        EXEC SQL close query_Cursor4;
}
prsqlda(index)
EXEC SQL BEGIN DECLARE SECTION;
parameter int index;
EXEC SQL END DECLARE SECTION;
{
EXEC SQL BEGIN DECLARE SECTION;
        int type;
        int len;
        char name [40];
EXEC SQL END DECLARE SECTION;
        EXEC SQL get descriptor 'queryDesc' value $index $type = type,
                $len = length, $name = name;
        printf (" Column %d: type = %d:, len = %d, name = %s\n",
                index, type, len, name); */
}
```

```
#include <stdio.h>
#include <string.h>
#include "aircraft.h"
#include "typedefs.h"
#include "constants.h"
FitData indata;
VerticalSeatData VertSeat;
HorizontalSeatData HorzSeat;
compute_F16_SeatAdj()
float maxSitHtFulldown[4] = \{40.5, 39.5, 38.5, 37.5\};
float maxSitHtFullup[4] = \{36.2, 35.2, 34.2, 33.2\};
float sittingHeightRange;
/* initially the seat position is set at full-down */
/******this variable set for testing **********/
        VertSeat.vertSeatNumberOfIncrements[F 16 A] = 50;
        indata.vertSeatPosition = 0;
        sittingHeightRange = (maxSitHtFulldown[indata.clearanceOverhead-1] -
                             maxSitHtFullup[indata.clearanceOverhead-1]) /
                             VertSeat.vertSeatNumberOfIncrements[F 16 A];
/* Determine the seat position. If the sitting height is less than the
   minimum at the clearance value requested, the subject sits at fullup.
   If the sitting height is greater than the maximum at the clearance value
   requested, the subject sits at fulldown. Otherwise calculate where the
   seat should be positioned. */
        if ( indata.sittingHeight <=</pre>
                        maxSitHtFullup[indata.clearanceOverhead-1])
                indata.vertSeatPosition =
                                VertSeat.vertSeatNumberOfIncrements[F_16_A];
        else if (indata.sittingHeight >=
                                maxSitHtFulldown[indata.clearanceOverhead-1])
                indata.vertSeatPosition = 0;
        else
                indata.vertSeatPosition =
                        (maxSitHtFulldown[indata.clearanceOverhead-1] -
                        indata.sittingHeight) / sittingHeightRange;
}
compute_T37_SeatAdj()
float maxSitHtFulldown = 40.0;
float seatAdj;
/* initially the seat position is set at full-down */
       indata.vertSeatPosition = 0;
       VertSeat.vertSeatAdjIncrements[T 37 B] = .625;
       VertSeat.vertSeatNumberOfIncrements[T 37 B] = 8;
       seatAdj = ( ( maxSitHtFulldown -
                (indata.clearanceOverhead - 1) ) - indata.sittingHeight) /
                VertSeat.vertSeatAdjIncrements[T_37_B];
```

```
/* Determine the seat position. If the sitting height is less than the
  minimum at the clearance value requested, the subject sits at fullup.
   If the sitting height is greater than the maximum at the clearance value
   requested, the subject sits at fulldown. Otherwise calculate where the
   seat should be positioned. */
        if ( seatAdj >= VertSeat.vertSeatNumberOfIncrements[T_37_B] )
              indata.vertSeatPosition =
                        VertSeat.vertSeatNumberOfIncrements[T 37 B];
        else if ( seatAdj <= 0 )</pre>
              indata.vertSeatPosition = 0;
        else
              indata.vertSeatPosition = seatAdj + .5;
}
compute TlA SeatAdj()
float maxSitHtFulldown = 42.6;
float seatAdj;
/* initially the seat position is set at full-down, full-forward */
        indata.vertSeatPosition = 0;
        indata.horzSeatPosition = 0;
        VertSeat.vertSeatAdjIncrements[T 1 A] = .75;
        VertSeat.vertSeatNumberOfIncrements[T_1_A] = 6;
        seatAdj = ( ( maxSitHtFulldown -
                (indata.clearanceOverhead - 1) ) - indata.sittingHeight) /
                VertSeat.vertSeatAdjIncrements[T 1 A];
/* Determine the seat position. If the sitting height is less than the
   minimum at the clearance value requested, the subject sits at fullup.
   If the sitting height is greater than the maximum at the clearance value
   requested, the subject sits at fulldown. Otherwise calculate where the
   seat should be positioned. */
        if ( seatAdj >= VertSeat.vertSeatNumberOfIncrements[T_1_A] )
              indata.vertSeatPosition =
                        VertSeat.vertSeatNumberOfIncrements[T 1 A];
        else if ( seatAdj <= 0 )</pre>
              indata.vertSeatPosition = 0;
        else
              indata.vertSeatPosition = seatAdj + .5;
compute T38A_SeatAdj()
float maxSitHtFulldown[2] = {45.0,39.5};
float maxDown:
float clearanceFactor = 1.11;
float seatAdj;
/* initially the seat position is set at full-down, full-forward */
```

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```
indata.vertSeatPosition = 0;
        VertSeat.vertSeatTotalAdj[T 38 A] = 5.0;
        VertSeat.vertSeatNumberOfIncrements[T 38 A] = 50;
        if (indata.selectedCrewStations[1] == CREW_FORWARD)
                maxDown = maxSitHtFulldown[0];
        else if (indata.selectedCrewStations[1] == CREW_AFT)
                maxDown = maxSitHtFulldown[1];
        seatAdj = ( maxDown - indata.sittingHeight) /
                  ( indata.clearanceOverhead * clearanceFactor);
/* Determine the seat position. If the sitting height is less than the
   minimum at the clearance value requested, the subject sits at fullup.
   If the sitting height is greater than the maximum at the clearance value
   requested, the subject sits at fulldown. Otherwise calculate where the
   seat should be positioned. */
        if ( seatAdj >= VertSeat.vertSeatTotalAdj[T 38_A] )
              indata.vertSeatPosition =
                        VertSeat.vertSeatNumberOfIncrements[T_38_A];
        else if ( seatAdj <= 0 )</pre>
              indata.vertSeatPosition = 0;
        else
              indata.vertSeatPosition = seatAdj *10;
}
```

```
#include <stdio.h>
#include <string.h>
#include "aircraft.h"
#include "typedefs.h"
#include "constants.h"
EXEC SQL include sqlca;
EXEC SQL include sqlda;
FitData indata;
VerticalSeatData VertSeat;
HorizontalSeatData HorzSeat:
/* Declare the host variables for database queries */
EXEC SQL BEGIN DECLARE SECTION;
short i;
short ind, ind2;
                                 /* indexes from the database */
short field;
short desc Count;
char *crewview Query;
char *view Query;
char *vision_Query;
char *visnote_Query;
char *vnote Query;
char tempname[60];
EXEC SQL END DECLARE SECTION;
main()
{
/* Open the cockpit database */
        EXEC SQL database cockpit;
}
void calculate vision()
EXEC SQL BEGIN DECLARE SECTION;
short aircraftNumber, crewNumber, headPosition;
short viewNumber, headPositionCnt;
short viewNoteNumber[2];
char view[60];
char vnote1[120], vnote2[120];
EXEC SQL END DECLARE SECTION;
float slope,intercept;
                                /* slope and intercept of line */
float adjvis,degvis[2];
                                 /* degrees of vision */
                                 /* c-141 */
float adjdeg;
float minimumEyeHt[2];
                                 /* minimum eyeht */
                                 /* maximum eyeht */
float maximumEyeHt[2];
                                /* minimum degree of vision */
float minimumVisionDeg[2];
                                /* maximum degree of vision */
float maximumVisionDeg[2];
float aboveGlare[2]
                                 /* degree change above glare shield */
float glareHeight[2]
                                /* glare shield height */
                                /* degree change below glare shield */
float belowGlare[2]
                                 /* maximum eyeht for range data */
float rangeMaxEyeHt[2];
```

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```
/* minimum eyeht for range data */
float rangeMinEyeHt[2];
                                /* minimum degree of vision for eyeht */
float minEyeHtDeg[2][2];
                                /* maximum degree of vision for eyeht */
float maxEyeHtDeg[2][2];
/* only perform vision calculations when subject eye-ht-sitting is available */
if ( eyeHeightSitting >= 0.0)
/* Set up the query to the database */
        crewview Query = "select * from crewview where anum =
        indata.selectedAircraft[1] and crewstan =
        indata.selectedCrewStations[1]";
/* Define the descriptor for database access */
        EXEC SQL prepare gid from $crewview Query;
        EXEC SQL declare query_Cursor cursor for qid;
        EXEC SQL allocate descriptor 'queryDesc';
       EXEC SQL open query_Cursor;
        EXEC SQL describe qid using sql descriptor 'queryDesc';
       EXEC SQL get descriptor 'queryDesc' $desc Count = count;
        for (i=1; i<= desc Count; i++)
                prsqlda(i);
        for (;;)
           EXEC SQL fetch query_Cursor using sql descriptor 'queryDesc';
           if (sqlca.sqlcode != 0) break;
           for (field = 1; field<= desc Count; field++)</pre>
                switch(field)
                                /* anum: aircraft number */
                case 1:
                EXEC SQL get descriptor 'queryDesc' value $field
                                $aircraftNumber = data;
                printf("anum: %d ",aircraftNumber);
                break:
                case 2:
                                /* crewstan: crewstation number */
                EXEC SQL get descriptor 'queryDesc' value $field
                                $crewNumber = data;
                printf("crewstan: %d\n", crewNumber);
                break;
                                /* viewnum: view number */
                case 3:
                EXEC SQL get descriptor 'queryDesc' value $field
                                $viewNumber = data;
                printf("viewNumber: %d\n", viewNumber);
                break;
           }
/* Set up the query to the database */
        view Query = "select * from view where viewnum = viewNumber";
```

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```
/* Define the descriptor for database access */
        EXEC SQL prepare qid1 from $view Query;
        EXEC SQL declare query Cursor1 cursor for qid1;
        EXEC SQL allocate descriptor 'queryDesc';
        EXEC SQL open query Cursorl;
        EXEC SQL describe qidl using sql descriptor 'queryDesc';
        EXEC SQL get descriptor 'queryDesc' $desc Count = count;
        for (i=1; i<= desc Count; i++)
                prsqlda(i);
        for (;;)
           EXEC SQL fetch query_Cursor using sql descriptor 'queryDesc';
           if (sqlca.sqlcode != 0) break;
           for (field = 1; field<= desc Count; field++)</pre>
                switch (field)
                case 1:
                                 /* viewnum: view number */
                printf("viewNumber: %d ", viewNumber);
                break;
                                /* view: view title */
                case 2:
                EXEC SQL get descriptor 'queryDesc' value $field
                                 $view = data;
                printf("viewTitle: %s\n", view);
                break;
                }
           }
/* Set up the query to the database */
        vision Query = "select * from vision where anum =
        indata.selectedAircraft[1] and crewstan =
        indata.selectedCrewStations[1] and viewnum = viewNumber";
/* Define the descriptor for database access */
        EXEC SQL prepare qid3 from $vision Query;
        EXEC SQL declare query_Cursor3 cursor for qid3;
        EXEC SQL allocate descriptor 'queryDesc';
        EXEC SQL open query Cursor3;
        EXEC SQL describe qid3 using sql descriptor 'queryDesc';
        EXEC SQL get descriptor 'queryDesc' $desc Count = count;
        for (i=1; i<= desc_Count; i++)
                prsqlda(i);
        for (;;)
           EXEC SQL fetch query Cursor using sql descriptor 'queryDesc';
           if (sqlca.sqlcode != 0) break;
```

```
for (field = 1; field<= desc Count; field++)</pre>
        switch(field)
        {
                      /* anum: aircraft number */
        case 1:
        EXEC SQL get descriptor 'queryDesc' value $field
                        $aircraftNumber = data;
        printf("anum: %d ",aircraftNumber);
        break;
        case 2:
                        /* crewstan: crewstation number */
        EXEC SQL get descriptor 'queryDesc' value $field
                        $crewNumber = data;
        printf("crewstan: %d\n", crewNumber);
       break;
        case 3:
                       /* viewnum: view number */
        EXEC SQL get descriptor 'queryDesc' value $field
                        $viewNumber = data;
       printf("viewNumber: %d\n", viewNumber);
       break;
        }
   }
}
      /* for (;;) */
 /* for (;;) */
}
```

### APPENDIX F GUI SOURCE FILES

buildmenu.c

```
/**********************************
   BuildMenu.c
   Used to build popup, option, pulldown and pullright menus.
   Menus are defined by declaring an array of MenuItem structures
*****************************
#include <Xm/RowColumn.h>
/* #include <Xm/CascadeB.h>*/
#include <Xm/CascadeBG.h>
#include <Xm/ToggleB.h>
#include <Xm/ToggleBG.h>
#include <Xm/PushB.h>
#include <Xm/PushBG.h>
#include "typedefs.h"
#include "constants.h"
extern void SetWidgetColorScheme();
 /**************************
    Build popup, option and pulldown menus, depending on the
    menu_type. It may be XmMENU_PULLDOWN, XmMENU_OPTION, or
    XmMENU POPUP. Pulldowns return the CascadeButton that pops up
   the menu. Popups return the menu. Option menus are created,
   but the RowColumn that acts as the option "area" is returned
   unmanaged. (The user must manage it.) Pulldown menus are
    built from cascade buttons, so this function also builds
   pullright menus. The function also adds the right callback for *
   PushButton or ToggleButton menu items.
 ****************************
 Widget BuildMenu(parent, menu_type, menu_title, menu_mnemonic, items)
 Widget parent;
 int menu_type;
 char *menu_title, menu_mnemonic;
 MenuItem *items;
 {
     Widget menu, cascade, widget;
     int i;
     XmString str;
     if (menu_type == XmMENU PULLDOWN || menu type == XmMENU OPTION)
     {
         menu = XmCreatePulldownMenu(parent, " pulldown", NULL, 0);
     else if (menu type == XmMENU POPUP)
         menu = XmCreatePopupMenu(parent, " popup", NULL, 0);
     else
     {
         XtWarning("Invalid menu type passed to BuildMenu()");
         return NULL;
     SetWidgetColorScheme(menu, dialogSectionTitleColor);
     /* Pulldown menus require a cascade button to be made */
     if (menu_type == XmMENU PULLDOWN)
     {
         str = XmStringCreateSimple(menu title);
         cascade = XtVaCreateManagedWidget (menu title,
                      xmCascadeButtonGadgetClass, parent,
                      XmNsubMenuId,
                                                menu,
                      XmNlabelString,
                                                str,
                      XmNmnemonic,
                                                menu mnemonic,
                      NULL);
                                  203
         XmStringFree(str);
```

```
else if (menu type == XmMENU_OPTION)
    /* Option menus are a special case, but not hard to handle */
    Arg args[2];
    str = XmStringCreateSimple(menu title);
    XtSetArg(args[0], XmNsubMenuId, menu);
    XtSetArg(args[1], XmNlabelString, str);
    /*
     * This really isn't a cascade, but this is the widget handle
     * we're going to return at the end of the function.
    cascade = XmCreateOptionMenu(parent, menu_title, args, 2);
    XmStringFree(str);
}
/* Now add the menu items */
for (i = 0; items[i].label != NULL; i++)
    /*
        If subitems exist, create the pull-right menu by calling
     * this function recursively Since the function returns a
       cascade button, the widget returned is used.
     */
     if (items[i].subitems)
         if (menu type == XmMENU OPTION)
             XtWarning ("you can't have submenus from option menu items");
             continue;
         }
         else
              widget = BuildMenu(menu, XmMENU_PULLDOWN, items[i].label,
                                  items[i].mnemonic, items[i].subitems);
         }
     else
         widget = XtVaCreateManagedWidget(items[i].label,
                                           *items[i].class,
                                           menu, NULL);
     /*
      * Whether the item is a real item or a cascade button with a
      * menu, it can still have a mnemonic.
      */
     if (items[i].mnemonic)
         XtVaSetValues(widget, XmNmnemonic, items[i].mnemonic, NULL);
     /*
      * any item can have an accelerator, except cascade menus. But,
      * we dont warry about that; we know better in our declarations.
      */
     if (items[i].accelerator)
     {
         str = XmStringCreateSimple(items[i].accel_text);
         XtVaSetValues(widget,
                                           items[i].accelerator,
                       XmNaccelerator,
                       XmNacceleratorText, str,
                       NULL);
         XmStringFree(str);
     if (items[i].callback)
         XtAddCallback(widget,
                (items[i].class == &xmToggleButtonWidgetClass | |
                 items[i].class == &xmToggleButtonGadgetClass)?
                      XmNvalueChangedCallback : /* ToggleButton class */
```

popupclearancemenu.c

```
#include <Xm/DialogS.h>
#include <Xm/PushBG.h>
#include <Xm/PushB.h>
#include <Xm/RowColumn.h>
#include "menus.h"
#include "constants.h"
extern void SetWidgetColorScheme();
extern Widget BuildMenu();
extern int buttonPressX, buttonPressY;
Widget dataSelectionDialog;
Widget popUpClearanceSelection(widgetId)
Widget widgetId;
    Widget dsRowCol, menuWidget;
    Dimension x, y;
    dsRowCol = XtVaCreateWidget("deRowCol",
                                 xmRowColumnWidgetClass,
                                 XtParent (widgetId),
                                 NULL);
    XtManageChild(dsRowCol);
   menuWidget = BuildMenu(dsRowCol,
                           XmMENU POPUP,
                            "Data",
                           NULL,
                           overheadClearanceMenu);
    SetWidgetColorScheme(menuWidget, dialogSectionTitleColor);
   XtVaSetValues(menuWidget, XmNx, buttonPressX, NULL);
   XtVaSetValues (menuWidget, XmNy, buttonPressY, NULL);
   XtManageChild(menuWidget);
    return(dsRowCol);
}
```

setwidgetcolorscheme.c

```
#include <Xm/Xm.h>
SetWidgetColorScheme(widget, aColor)
Widget widget;
char aColor[];
{
    Colormap cmap;
    XColor color, unused;
    Pixel bg color, top shadow, bottom shadow, fg, fg_ret, select_color;
    /* Get the colormap */
    XtVaGetValues(widget, XmNcolormap, &cmap, NULL);
    /* Convert the color "aColor" to a pixel value
        from the given colormap */
    XAllocNamedColor(XtDisplay(widget), cmap, aColor, &color, &unused);
    bg_color = color.pixel;
    /* Let Motif calculate the new colors base on that one color */
    XmGetColors(XtScreen(widget), cmap, bg color, &fg ret, &top shadow,
                  &bottom_shadow, &select_color);
    /* Set the colors accordingly */
    XtVaSetValues (widget,
                    XmNbackground, bg_color,
XmNtopShadowColor, top_shadow,
XmNbottomShadowColor, bottom_shadow,
                    XmNselectColor, select_color,
XmNarmColor, select_color,
                    XmNborderColor, fg ret,
                    NULL);
}
```

dataentry.c

```
#include <Xm/DialogS.h>
#include <Xm/PushBG.h>
#include <Xm/PushB.h>
#include <Xm/LabelG.h>
#include <Xm/PanedW.h>
#include <Xm/Form.h>
#include <Xm/RowColumn.h>
#include <Xm/ToggleBG.h>
#include <Xm/Text.h>
#include <Xm/TextF.h>
#include <Xm/Frame.h>
#include <stdlib.h>
#include "typedefs.h"
#include "constants.h"
#include "dataentry.h"
XtCallbackProc ComputeButtonAction();
XtCallbackProc ExitDataEntry();
XtCallbackProc DataButtonAction();
XtCallbackProc ReadSeatPositionValue();
XtCallbackProc ReadMeasurementValue();
void CrewStationValue();
void AircraftSelection();
void UpdateCrewStationWidgets();
extern Widget popUpDataSelection();
extern Widget popUpClearanceSelection();
int nbrCrewStations = 0;
extern MenuItem dataMenu;
Widget deShell, crewStationWidgets[MAX CREW STATIONS PER AIRCRAFT],
               measurementWidget[MAX MEASUREMENTS_TAKEN],
               aircraftWidgets[MAX AIRCRAFT],
               seatPositionWidget[MAX SEAT ADJ DIRECTIONS],
               dataSelectionDialog, csToggleRowCol, csFrame;
FitData analysisData;
      pictureId;
long
extern void updateXY();
void popupDataEntryWindow(widgetId, client data, call data)
Widget widgetId;
caddr t client data;
caddr_t call_data;
   Widget fillInForm, aGadget, fieldRowCol,
          deForm, acRowCol, csRowCol, fieldForm,
          acToggleRowCol, deRowCol, actRowCol,
          spRowCol, actionForm, computeButton,
          buttonForm, dataButton, exitButton, actionFrame, aFrame;
   XtWidgetGeometry geom;
   char debuf[2];
   int rowy = 12, colx = 2, yspace = 35, i = 0, j, k = 0;
    /**********************************
                          Create dialog shell
     *************************
   deShell = XtVaCreateManagedWidget("deShell",
                 xmDialogShellWidgetClass,
                                            XtParent(widgetId),
                 XmNtitle,
                                             "Individual Body Type Fit Analysis",
```

```
XmMdeleteResponse,
                                       XmDESTROY,
              XmNmaxHeight,
                                       500,
                                       900,
              XmNmaxWidth,
              XmNminHeight,
                                       500,
              XmNminWidth,
                                        900.
                                        Ο,
              XmNx.
              XmNy,
                                        Ο,
              NULL);
 deRowCol = XtVaCreateWidget("deRowCol",
              xmRowColumnWidgetClass, deShell,
              NULL);
 deForm = XtVaCreateManagedWidget("deForm",
              xmFormWidgetClass, deRowCol,
              XmNfractionBase,
                                        100,
              NULL);
 SetWidgetColorScheme(deForm, dialogBGColor);
 aFrame = XtVaCreateManagedWidget("aFrame",
              xmFrameWidgetClass,
                                        deForm,
              XmNtopAttachment,
                                        XMATTACH POSITION,
              XmNtopPosition,
              XmNleftAttachment,
                                        XMATTACH POSITION,
                                       5,
XmATTACH_POSITION,
              XmNleftPosition,
              XmNrightAttachment,
              XmNrightPosition,
                                       95,
              NULL);
 fillInForm = XtVaCreateManagedWidget("fillInForm",
              xmFormWidgetClass, aFrame,
              XmNfractionBase,
                                        100,
              NULL);
SetWidgetColorScheme(fillInForm, dialogSectionBGColor);
aGadget = XtVaCreateManagedWidget("Individual Measurement Data:",
              xmLabelWidgetClass, fillInForm,
             XmNtopAttachment,
                                    XmATTACH_POSITION, 0,
              XmNtopPosition,
              XmNleftAttachment,
                                      XmATTACH POSITION,
              XmNleftPosition,
              NULL);
SetWidgetColorScheme(aGadget, dialogSectionTitleColor);
/*********************
       Create Individual Measurement Data entry area
for (j=0; j<XtNumber(deLabels); j++)</pre>
{
    fieldForm = XtVaCreateWidget("deRowColumn",
          xmFormWidgetClass, fillInForm,
                                XMATTACH_POSITION, rowy,
XMATTACH_POSITION, colx,
XMATTACH_POSITION, colx+46,
          XmNtopAttachment,
          XmNtopPosition,
          XmNleftAttachment,
          XmNleftPosition,
          XmNrightAttachment,
          XmNrightPosition,
          NULL);
```

SetWidgetColorScheme(fieldForm, dialogSectionBGColor);

```
XtVaCreateManagedWidget(deLabels[j],
          xmLabelGadgetClass,
                                    fieldForm,
          XmNtopAttachment,
                                     XMATTACH POSITION,
          XmNtopPosition,
          XmNleftAttachment,
                                     XMATTACH POSITION,
          XmNleftPosition,
                                     1,
          NULL);
    measurementWidget[j] = XtVaCreateManagedWidget(debuf,
          xmTextFieldWidgetClass,
                                          fieldForm,
          XmNcolumns,
                                     4,
                                     4,
          XmNmaxLength,
          XmNtopAttachment,
                                     XMATTACH POSITION,
          XmNtopPosition,
          XmNleftAttachment,
                                     XMATTACH POSITION,
          XmNleftPosition,
                                     70,
          NULL);
    SetWidgetColorScheme(measurementWidget[j], "wheat");
    XtAddCallback(measurementWidget[j], XmNactivateCallback,
                 ReadMeasurementValue, j);
   XtVaCreateManagedWidget("in.",
          xmLabelGadgetClass,
                                     fieldForm,
          XmNtopAttachment,
                                     XMATTACH POSITION,
          XmNtopPosition,
          XmNleftAttachment,
                                     XMATTACH POSITION,
          XmNleftPosition,
                                     91,
         NULL);
   XtManageChild(fieldForm);
    if (j%2)
        rowy = rowy + yspace;
        colx = 2;
    }
    else
       colx = 52;
/************************
                Create Aircraft Selection area
 ************************************
aFrame = XtVaCreateManagedWidget("aFrame",
             xmFrameWidgetClass,
                                         deForm,
             XmNtopAttachment,
                                         XMATTACH POSITION,
                                         50,
             XmNtopPosition,
             XmNbottomAttachment,
                                         XMATTACH POSITION,
              XmNbottomPosition,
                                         91,
             XmNleftAttachment,
                                         XMATTACH POSITION,
                                         5,
             XmNleftPosition,
             XmNrightAttachment,
                                         XMATTACH POSITION,
             XmNrightPosition,
                                         30,
             NULL);
acRowCol = XtVaCreateWidget("acRowCol",
              xmRowColumnWidgetClass,
                                         aFrame,
              XmNisAligned,
                                         True,
             XmNentryAlignment,
                                         XMALIGNMENT BEGINNING,
             XmNorientation,
                                         XmVERTICAL,
              XmNnumColumns,
                                         1,
             NULL);
```

}

```
SetWidgetColorScheme(acRowCol, dialogSectionBGColor);
aGadget = XtVaCreateManagedWidget("Aircraft:",
             xmLabelWidgetClass,
                                        acRowCol,
             NULL);
SetWidgetColorScheme(aGadget, dialogSectionTitleColor);
XtManageChild(acRowCol);
acToggleRowCol = XtVaCreateWidget("acRowCol",
             xmRowColumnWidgetClass,
                                        acRowCol,
             XmNisAligned,
                                        True,
                                        XMALIGNMENT BEGINNING,
             XmNentryAlignment,
             XmNorientation,
                                       XmVERTICAL,
             XmNnumColumns,
                                      True,
             XmNradioAlwaysOne,
             XmNradioBehavior,
                                        True,
             NULL);
SetWidgetColorScheme(acToggleRowCol, dialogSectionBGColor);
for (i=0; i<XtNumber(aircraft); i++)</pre>
   aircraftWidgets[i] = XtVaCreateManagedWidget(aircraft[i].name,
                        xmToggleButtonGadgetClass, acToggleRowCol,
                       NULL);
   XtAddCallback(aircraftWidgets[i], XmNvalueChangedCallback,
                 AircraftSelection, i);
}
XtManageChild(acToggleRowCol);
/********************
               Create Crewstation Selection area
 ******************
csFrame = XtVaCreateManagedWidget("aFrame",
             xmFrameWidgetClass,
                                  deForm,
             XmNtopAttachment,
                                        XMATTACH POSITION,
             XmNtopPosition,
                                        50,
                                        XMATTACH POSITION,
             XmNbottomAttachment,
             XmNbottomPosition,
                                        91,
             XmNleftAttachment,
                                        XMATTACH POSITION,
             XmNleftPosition,
                                        35,
                                        XMATTACH POSITION,
             XmNrightAttachment,
             XmNrightPosition,
                                        55,
             NULL);
csRowCol = XtVaCreateWidget("csRowCol",
             xmRowColumnWidgetClass,
                                        csFrame,
                                        XmVERTICAL,
             XmNorientation,
             XmNnumColumns,
             NULL);
SetWidgetColorScheme(csRowCol, dialogSectionBGColor);
aGadget = XtVaCreateManagedWidget("Crewstation:",
             xmLabelWidgetClass, csRowCol,
             NULL);
SetWidgetColorScheme(aGadget, dialogSectionTitleColor);
csToggleRowCol = XtVaCreateWidget("csRowCol",
                                        csRowCol,
             xmRowColumnWidgetClass,
                                        XmVERTICAL,
             XmNorientation,
```

1,

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XmNnumColumns,

```
XmNradioAlwaysOne,
                                       True,
              XmNradioBehavior,
                                       True,
              NULL);
 SetWidgetColorScheme(csToggleRowCol, dialogSectionBGColor);
 XtManageChild(csRowCol);
 Create Seat Position data area
  *********************************
 aFrame = XtVaCreateManagedWidget("aFrame",
              xmFrameWidgetClass, deForm,
              XmNtopAttachment,
                                        XMATTACH POSITION,
              XmNtopPosition,
                                        50,
                                     XmATTACH_POSITION,
60,
XmATTACH_POSITION,
              XmNleftAttachment,
              XmNleftPosition,
              XmNrightAttachment,
              XmNrightPosition,
                                       95,
              NULL);
 spRowCol = XtVaCreateWidget("spRowCol",
              xmRowColumnWidgetClass,
                                        aFrame,
              XmNorientation,
                                        XmVERTICAL,
              XmNnumColumns,
              NULL):
 SetWidgetColorScheme(spRowCol, dialogSectionBGColor);
 aGadget = XtVaCreateManagedWidget("Seat Position:",
              xmLabelWidgetClass, spRowCol,
              XmNtopAttachment,
                                       XMATTACH POSITION,
              XmNtopPosition,
              XmNleftAttachment,
                                      XmATTACH POSITION,
              XmNleftPosition,
              NULL);
SetWidgetColorScheme(aGadget, dialogSectionTitleColor);
rowy = 25;
for (j=0; j<XtNumber(seatPositions); j++)</pre>
{
    fieldForm = XtVaCreateWidget("deRowColumn",
          xmFormWidgetClass,
                                    spRowCol,
          NULL):
    SetWidgetColorScheme(fieldForm, dialogSectionBGColor);
    XtVaCreateManagedWidget(seatPositions[j],
          xmLabelGadgetClass, fieldForm,
          XmNtopAttachment,
                                   XmATTACH_POSITION,
          XmNtopPosition,
                                   1,
          XmNleftAttachment,
                                   XMATTACH POSITION,
          XmNleftPosition,
                                    1,
          NULL);
    seatPositionWidget[j] = XtVaCreateManagedWidget(debuf,
          xmTextFieldWidgetClass,
                                    fieldForm,
          XmNcolumns,
                                    4,
          XmNmaxLength,
                                    4,
          XmNtopAttachment,
                                    XMATTACH POSITION,
          XmNtopPosition,
          XmNleftAttachment,
                                    XmATTACH_POSITION,
          XmNleftPosition,
                                    77,
```

```
NULL);
    XtAddCallback(seatPositionWidget[j], XmNactivateCallback,
                  ReadSeatPositionValue, j);
    SetWidgetColorScheme(seatPositionWidget[j], dialogFillInFieldColor);
    XtManageChild(fieldForm);
    rowy = rowy + yspace+5;
}
fieldForm = XtVaCreateWidget("deRowColumn",
          xmFormWidgetClass,
                                     spRowCol,
          NULL);
SetWidgetColorScheme(fieldForm, dialogSectionBGColor);
computeButton = XtVaCreateManagedWidget("ComputeButton",
             xmPushButtonWidgetClass, fieldForm,
                                     XmStringCreateSimple("Compute"),
             XmNlabelString,
             XmNtopAttachment,
                                         XMATTACH POSITION,
             XmNtopPosition,
                                         XMATTACH POSITION,
             XmNleftAttachment,
             XmNleftPosition,
                                         35,
             NULL);
SetWidgetColorScheme(computeButton, dialogSectionTitleColor);
XtAddEventHandler(computeButton, ButtonPressMask, FALSE, updateXY, NULL);
XtAddCallback(computeButton, XmNactivateCallback, ComputeButtonAction, NULL);
XtManageChild(fieldForm);
XtManageChild(spRowCol);
/************************
      Create the action button area at the bottom of the
      window, and put in a Data and an Exit button.
actionForm = XtVaCreateWidget("dataButtonRowCol",
                                      deForm,
               xmFormWidgetClass,
               XmNtopAttachment,
                                           XMATTACH POSITION,
               XmNtopPosition,
                                           92,
              XmNbottomAttachment,
                                          XMATTACH POSITION,
              XmNbottomPosition,
                                          99,
               XmNleftAttachment,
                                           XMATTACH POSITION,
               XmNleftPosition,
                                           30,
               XmNrightAttachment,
                                           XMATTACH POSITION,
               XmNrightPosition,
                                           70,
               NULL);
SetWidgetColorScheme(actionForm, dialogBGColor);
XtManageChild(actionForm);
actRowCol = XtVaCreateWidget("actRowCol",
              xmRowColumnWidgetClass,
                                          actionForm,
              XmNtopAttachment,
                                          XMATTACH POSITION,
              XmNtopPosition,
              XmNleftAttachment,
                                           XMATTACH POSITION,
              XmNleftPosition,
              XmNrightAttachment,
                                            XMATTACH POSITION,
              XmNrightPosition,
                                            100,
                                          XmHORIZONTAL,
              XmNorientation,
              XmNnumColumns,
                                          2,
                                          200,
              XmNspacing,
              NULL);
```

XtManageChild(actRowCol);

```
SetWidgetColorScheme(actRowCol, dialogBGColor);
   dataButton = XtVaCreateManagedWidget("DataButton",
                xmPushButtonWidgetClass, actRowCol,
                XmNlabelString,
                                       XmStringCreateSimple("Data"),
                NULL);
   SetWidgetColorScheme(dataButton, dialogSectionTitleColor);
   XtAddCallback(dataButton, XmNactivateCallback, DataButtonAction, NULL);
   XtAddEventHandler(dataButton, ButtonPressMask, FALSE, updateXY, NULL);
   exitButton = XtVaCreateManagedWidget("ExitButton",
                xmPushButtonWidgetClass, actRowCol,
                XmNlabelString,
                                       XmStringCreateSimple("Exit"),
                NULL);
   SetWidgetColorScheme(exitButton, dialogSectionTitleColor);
   XtAddCallback(exitButton, XmNactivateCallback, ExitDataEntry, NULL);
   XtManageChild(deRowCol);
}
XtCallbackProc ComputeButtonAction(widget_id, client data, call data)
Widget widget_id;
caddr t client data;
caddr t call data;
  if (dataSelectionDialog != NULL)
       XtUnmanageChild(dataSelectionDialog);
  popUpClearanceSelection(widget id);
/********************
    The Data button was clicked, so pop up the data
    selection dialog for selecting the type of data to
    receive a report for.
 ******************
XtCallbackProc DataButtonAction(widget_id, client data, call data)
Widget widget id;
caddr t client data;
caddr_t call_data;
{
  if (dataSelectionDialog != NULL)
       XtUnmanageChild(dataSelectionDialog);
  dataSelectionDialog = popUpDataSelection(widget id);
/********************
     Display the crew stations for the selected aircraft
             *****************
void RedisplayCrewStations()
   int i = 0;
   while (crewStations[i].idCode)
       crewStationWidgets[i] = XtVaCreateManagedWidget(crewStations[i].name,
                 xmToggleButtonGadgetClass, csToggleRowCol,
```

```
NULL);
       XtAddCallback(crewStationWidgets[i], XmNvalueChangedCallback,
                   CrewStationValue, i);
       i++;
   XtManageChild(csToggleRowCol);
}
/********************
     Update Crewstation selection on the data entry screen *
     to reflect those crewstations found on the aircraft
     that has been selected
 *******************
void UpdateCrewStationWidgets(selectedAircraftIdCode)
int selectedAircraftIdCode;
{
   int i;
   int index = 0;
   /***** Query Database here for Aircraft Profile ******/
   for (i=0; i<nbrcrewStations; i++)</pre>
       XtUnmanageChild(crewStationWidgets[i]);
   XtUnmanageChild(csToggleRowCol);
   /*******************
      Reset the available crewStations array in preparation
      to reflect the crew stations available for the selected *
       aircraft.
    ********************
   nbrCrewStations = 0;
   for (i=0; i<MAX CREW STATIONS PER AIRCRAFT; i++)
       strcpy(crewStations[i].name, " ");
       crewStations[i].idCode = 0;
   }
   /****** Fill in updated crewstation info from Database ******/
   switch(selectedAircraftIdCode+1)
   {
       case F 16 A:
          strcpy(crewStations[0].name, "Forward");
          crewStations[0].idCode = CREW FORWARD;
          nbrCrewStations = 1;
          break;
       case C 141 A :
          strcpy(crewStations[0].name, "Left");
          crewStations[0].idCode = CREW LEFT;
          strcpy(crewStations[1].name,"Right");
          crewStations[1].idCode = CREW RIGHT;
          nbrCrewStations = 2;
```

break;

```
case T 37 B:
           strcpy(crewStations[0].name, "Left");
           crewStations[0].idCode = CREW_LEFT;
           strcpy(crewStations[1].name, "Right");
           crewStations[1].idCode = CREW RIGHT;
           nbrCrewStations = 2;
           break;
       case T 38 A:
           strcpy(crewStations[0].name, "Forward");
           crewStations[0].idCode = CREW FORWARD;
           strcpy(crewStations[1].name, "Aft");
           crewStations[1].idCode = CREW_AFT;
           nbrCrewStations = 2;
           break;
       case T_1_A :
           strcpy(crewStations[0].name, "Left");
           crewStations[0].idCode = CREW LEFT;
           strcpy(crewStations[1].name, "Right");
           crewStations[1].idCode = CREW RIGHT;
           nbrCrewStations = 2;
           break;
       default:
           break;
   };
   RedisplayCrewStations();
}
void AircraftSelection(widget id, which, state)
Widget widget id;
int which;
XmToggleButtonCallbackStruct *state;
{
   if (state->set)
       /********************
           Update crewstation selection widget on data
           entry screen.
        ****************
       UpdateCrewStationWidgets(which);
   }
}
void CrewStationValue(widget id, which, state)
Widget widget_id;
int which;
XmToggleButtonCallbackStruct *state;
{
    if (state->set)
      analysisData.selectedCrewStations[1] = crewStations[which].idCode;
}
```

```
XtCallbackProc ReadSeatPositionValue(widget_id, client_data, call data)
Widget widget id;
int client data;
int call data;
{
    float fieldValue;
    fieldValue = (float) atof(XmTextFieldGetString(widget id));
    switch (client_data)
    {
       case 0:
           analysisData.vertSeatPosition = fieldValue;
       case 1:
           analysisData.horzSeatPosition = fieldValue;
    }
}
XtCallbackProc ReadMeasurementValue(widget id, client data, call data)
Widget widget id;
int client data;
int call data;
{
    float fieldValue;
    fieldValue = (float) atof(XmTextFieldGetString(widget id));
    switch (client_data)
       case 0 :
           analysisData.thumbTipReach = fieldValue;
           break;
           analysisData.buttockKneeLength = fieldValue;
           break;
       case 2:
           analysisData.shoulderHeight = fieldValue;
           break;
       case 3:
           analysisData.sittingHeight = fieldValue;
           break;
       case 4:
           analysisData.kneeHeightSitting = fieldValue;
           break;
       case 5:
           analysisData.eyeHeightSitting = fieldValue;
           break;
}
void updateAnalysisData()
{
    int j;
    for (j=0; j<XtNumber(deLabels); j++)</pre>
        ReadMeasurementValue(measurementWidget[j], j, NULL);
```

```
for (j=0; j<XtNumber(seatPositions); j++)</pre>
        ReadSeatPositionValue(seatPositionWidget[j], j, NULL);
}
void printAnalysisData()
    printf("Thumb Tip Reach:
                                  %3.1f\n",analysisData.thumbTipReach);
    printf("Buttock-Knee Length: %3.1f\n",analysisData.buttockKneeLength);
    printf("Shoulder Height:
                                  %3.1f\n",analysisData.shoulderHeight);
    printf("Sitting Height:
                                  %3.1f\n",analysisData.sittingHeight);
    printf("Knee Height Sitting: %3.1f\n",analysisData.kneeHeightSitting);
    printf("Eye Height Sitting:
                                  %3.1f\n",analysisData.eyeHeightSitting);
    printf("Vertical Position:
                                  %3.1f\n",analysisData.vertSeatPosition);
    printf("Horizontal Position: %3.1f\n",analysisData.horzSeatPosition);
    printf("selectedAircraft:
                                  %d\n", analysisData.selectedAircraft[1]);
    printf("selectedCrewStations:%d\n",analysisData.selectedCrewStations[1]);
    printf("clearanceOverhead:%d\n",analysisData.clearanceOverhead);
XtCallbackProc ExitDataEntry(widget_id, client_data, call_data)
Widget widget_id;
caddr t client data;
caddr_t call_data;
{
   updateAnalysisData();
  printAnalysisData();
   XtDestroyWidget(deShell);
}
```

popupdataselection.c

```
#include <Xm/DialogS.h>
#include <Xm/PushBG.h>
#include <Xm/PushB.h>
#include <Xm/RowColumn.h>
#include "menus.h"
#include "constants.h"
extern void SetWidgetColorScheme();
extern Widget BuildMenu();
extern int buttonPressX, buttonPressY;
Widget dataSelectionDialog;
Widget popUpDataSelection(widgetId)
Widget widgetId;
{
    Widget dsRowCol, menuWidget;
    Dimension x, y;
    dsRowCol = XtVaCreateWidget("deRowCol",
                                   xmRowColumnWidgetClass,
                                   XtParent (widgetId),
                                   NULL);
    XtManageChild(dsRowCol);
    menuWidget = BuildMenu(dsRowCol,
                              XmMENU POPUP,
                              "Data",
                              NULL,
                              dataMenu);
    printf("x = %d\n",buttonPressX);
    printf("y = %d\n",buttonPressY);
    SetWidgetColorScheme(menuWidget, dialogSectionTitleColor);
    XtVaSetValues(menuWidget, XmNx, buttonPressX, NULL);
XtVaSetValues(menuWidget, XmNy, buttonPressY, NULL);
    XtManageChild(menuWidget);
    return(dsRowCol);
}
```

displaypicture.c

```
/*
         showimg -
                 Display a color or black and white image on the iris.
                                                                           Simple
         version for demo use. This will only work on machines that support
         RGB mode.
                                  Paul Haeberli - 1988
 */
#include <stdio.h>
#include <gl.h>
#include <device.h>
#include <image.h>
unsigned short rs[8192];
unsigned short gs[8192];
unsigned short bs[8192];
unsigned char rb[8192];
unsigned char gb[8192];
unsigned char bb[8192];
short colorbuff[4096];
IMAGE *image;
int x, y, xsize, ysize, zsize;
int xscreensize;
int yscreensize;
short val;
extern long pictureId;
void DisplayPicture(filename, title)
char *filename;
char *title;
{
    if (pictureId)
        winclose(pictureId);
    xscreensize = getgdesc(GD_XPMAX);
    yscreensize = getgdesc(GD_YPMAX);
    if( (image=iopen(filename, "r")) == NULL )
        printf("displayPicture: cant open input file");
        exit(1);
    xsize = image->xsize;
    ysize = image->ysize;
    zsize = image->zsize;
    prefsize(xsize, ysize);
    pictureId = winopen(title);
    winmove (0,0);
    RGBmode();
    gconfig();
    drawit();
}
drawit()
    ortho2(-0.5, (float)xsize-0.5, -0.5, (float)ysize-0.5);
    for (y=0; y< ysize; y++) {
        if(zsize<3) {</pre>
            getrow(image, rs, y, 0);
            compress(rs,rb,xsize);
            cmov2i(0,y);
            writeRGB(xsize,rb,rb,rb);
        } else {
                                      225
```

```
getrow(image,rs,y,0);
            compress(rs,rb,xsize);
            getrow(image, gs, y, 1);
            compress(gs,gb,xsize);
            getrow(image, bs, y, 2);
            compress(bs,bb,xsize);
            cmov2i(0,y);
            writeRGB(xsize,rb,gb,bb);
        }
    }
}
compress(sptr,bptr,n)
register unsigned short *sptr;
register unsigned char *bptr;
short n;
    while(n--)
        *bptr++ = *sptr++;
}
```

displaytechinfo.c

```
#include <stdio.h>
#include <Xm/PanedW.h>
#include <string.h>
#include "constants.h"
void DisplayTechInfo(widget_id, infoFileId)
Widget widget id;
     infoFileId;
int.
   caddr_t client_data;
   caddr_t call_data;
   char infoFilename[32];
   char *fileData;
   FILE *inputFile;
   long bufptr;
   switch (infoFileId)
       case VISION:
            strcpy(infoFilename, "textdesc/vision.txt");
            break;
       case REACH RUDDER THROW :
            strcpy(infoFilename, "textdesc/reach rt.txt");
            break;
       case REACH ARM REACH INDIVIDUAL CONTROLS :
            strcpy(infoFilename, "textdesc/reach_aric.txt");
            break;
       case REACH ARM REACH ALL MISSED CONTROLS :
            strcpy(infoFilename, "textdesc/reach aramc.txt");
            break;
       case REACH ARM REACH CONTROL REGION LEFT SIDE PANEL :
            strcpy(infoFilename, "textdesc/reach arcrlsp.txt");
            break;
       case REACH ARM REACH CONTROL REGION LEFT AUXILIARY PANEL:
            strcpy(infoFilename, "textdesc/reach_arcrlap.txt");
            break;
       case REACH ARM REACH CONTROL REGION MAIN INSTRUMENT PANEL:
            strcpy(infoFilename, "textdesc/reach_arcrmip.txt");
            break;
       case REACH ARM REACH CONTROL REGION CENTER PEDESTAL :
            strcpy(infoFilename, "textdesc/reach_arcrcp.txt");
            break;
       case REACH ARM REACH CONTROL REGION RIGHT SIDE PANEL :
            strcpy(infoFilename, "textdesc/reach arcrrsp.txt");
            break;
       case REACH ARM REACH CONTROL REGION RIGHT AUXILIARY PANEL:
            strcpy(infoFilename, "textdesc/reach arcrrap.txt");
            break;
       case CLEARANCE OVERHEAD :
            strcpy(infoFilename, "textdesc/clearance oh.txt");
```

```
break;
    case CLEARANCE_SHIN_WITH_INSTRUMENT_PANEL :
         strcpy(infoFilename, "textdesc/clearance_swip.txt");
         break;
    case CLEARANCE_EJECTION WITH GLARE SHIELD :
         strcpy(infoFilename, "textdesc/clearance ewgs.txt");
         break;
    case CLEARANCE_EJECTION_WITH_CANOPY_BOW :
         strcpy(infoFilename, "textdesc/clearance ewcb.txt");
         break;
    default:
         strcpy(infoFilename, "textdesc/invalid.txt");
         break;
}
printf("DisplayTechInfo filename: %s\n",infoFilename);
bufptr = ReadTextFile(infoFilename);
popupInfoWindow(widget_id, client_data, call_data, "Explanation",
                  bufptr);
free (bufptr);
```

generatereport.c

```
#include <stdio.h>
#include <Xm/PanedW.h>

void GenerateReport(widget_id, reportId)

Widget widget_id;
int reportId;

{
    printf("Generate report\n");
    printf("reportId: %d\n", reportId);
}
```

infowindow.c

```
infowindow.c
 */
#include <stdio.h>
#include <Xm/BulletinB.h>
#include <Xm/PanedW.h>
#include <Xm/PushB.h>
#include <Xm/Frame.h>
#include <Xm/Form.h>
#include <Xm/ScrolledW.h>
#include <Xm/Text.h>
#include <Xm/DrawingA.h>
#include <Xm/MessageB.h>
#include <Xm/RowColumn.h>
#include <Xm/DialogS.h>
#include <Xm/PushBG.h>
#include <gl.h>
#include "constants.h"
     INFOX = (XMAXSCREEN / 2);
int
int INFOY = YMAXSCREEN - (int) (YMAXSCREEN/4);
extern long pictureId;
extern Widget GetTopShell();
extern void DestroyShell();
popupInfoWindow(widget_id, client_data, call_data, title,
                textToDisplay)
    Widget widget id;
    caddr_t client_data;
    caddr_t call_data;
    char title[], textToDisplay[];
    Widget w, infoDialog, text_w, pane, form, widget, verticalScrollBar, label;
    Arg args[9];
    XmString xmString;
    extern void activate();
    extern void DestroyShell();
                                                   Set the delete
        Set up a DialogShell as a popup window.
       window protocol response to XmDESTROY to make sure that
       the window goes away appropriately. Otherwise, it's
        XmUNMAP which means it'd be lost forever, since we're not
        storing the widget globally or statically to this function.
     */
    infoDialog = XtVaCreatePopupShell(title,
                                       xmDialogShellWidgetClass,
                                       GetTopShell(widget id),
                                      XmNdeleteResponse,
                                      XmDESTROY,
                                       XmNx, INFOX,
                                      XmNy, INFOY,
                                      NULL);
    SetWidgetColorScheme(infoDialog, dialogBGColor);
        Create a RowColumn to manage the stuff in this dialog
    pane = XtVaCreateWidget("pane",
                             xmRowColumnWidgetClass,
                             infoDialog
```

```
NULL);
   SetWidgetColorScheme(pane, dialogBGColor);
    /*
       Create a RowColumn in the form for Label and Text widgets
    */
   form = XtVaCreateWidget("form",
                            xmFormWidgetClass,
                            pane,
                            NULL);
   SetWidgetColorScheme(form, dialogFillInFieldColor);
       Convert the textual content to be displayed
       into an instance of ScrolledText
     */
   XtSetArg(args[0], XmNscrollVertical, TRUE);
   XtSetArg(args[1], XmNscrollHorizontal, FALSE);
   XtSetArg(args[2], XmNeditMode, FALSE);
   XtSetArg(args[3], XmNeditable, FALSE);
   XtSetArg(args[4], XmNcursorPositionVisible, FALSE);
   XtSetArg(args[5], XmNwordWrap, TRUE);
   XtSetArg(args[6], XmNvalue, textToDisplay);
   XtSetArg(args[7], XmNheight, (int)(YMAXSCREEN/4));
   XtSetArg(args[8], XmNwidth, (int)(XMAXSCREEN/2));
   text w = XmCreateScrolledText(form,
                                  "help text",
                                  args,
                                   9);
     XtGetValues(text_w, XmNverticalScrollBar, &verticalScrollBar, NULL);
/*
   SetWidgetColorScheme(verticalScrollBar, dialogFillInFieldColor);
    SetWidgetColorScheme(text_w, dialogFillInFieldColor);
    XtManageChild(text_w);
    XtManageChild(form);
    /*
       Create another form to use as an action area for the dialog
    form = XtVaCreateWidget("form2", xmFormWidgetClass,
                            pane, XmNfractionBase, 5, NULL);
    SetWidgetColorScheme(form, dialogBGColor);
    /*
     * Create the OK button
     */
    widget = XtVaCreateManagedWidget("Ok",
                                      xmPushButtonWidgetClass, form,
                                      XmNtopAttachment, XmATTACH_FORM,
                                      XmNbottomAttachment, XmATTACH_FORM,
                                      XmNleftAttachment, XmATTACH_POSITION,
                                      XmNleftPosition, 2,
                                      XmNrightAttachment, XmATTACH POSITION,
                                      XmNrightPosition, 3,
                                      NULL);
    SetWidgetColorScheme(widget, dialogSectionTitleColor);
       Add callback routine for the OK button
    XtAddCallback(widget, XmNactivateCallback,
                  DestroyShell, infoDialog);
```

```
XtManageChild(form);
{
    Dimension h;
    XtVaGetValues(widget, XmNheight, &h, NULL);
    XtVaSetValues(form, XmNpaneMaximum, h, XmNpaneMinimum, h, NULL);
}

XtManageChild(pane);

XtPopup(infoDialog, XtGrabNone);
}
```

readtextfile.c

```
#include <stdio.h>
#include <stdlib.h>
#include <sys/stat.h>
#include <malloc.h>
/*
void main()
    char
         *dataptr, *buffer;
    long
          bufsize, i;
    long
          bufptr;
   bufptr = ReadTextFile("textdesc/c141 desc");
   printf("%s",bufptr);
*/
/**********************
   This routine opens the file named "filename", allocates
   enough memory to hold the file's contents, and reads the
   file into that buffer, returning a pointer to the beginning*
   of the data just read in.
 *************************
long ReadTextFile(filename)
char filename[];
   struct stat statb;
   char *buffer;
   long bufptr, len;
   FILE *fp;
   fp = fopen(filename, "r");
   if (fp == NULL)
       printf("unable to open file named: %s\n", filename);
       exit(0);
    }
   stat(filename, &statb);
   len = statb.st_size;
   if (!(buffer = malloc(len)))
       printf("ReadTextFile: Unable to allocate memory for file contents\n");
   else
       bufptr = (long)buffer;
       fread(buffer, 1, len, fp);
       fclose(fp);
       buffer+= NULL;
   }
   return (bufptr);
}
```

reportwindow.c

```
/*
     reportwindow.c
 */
#include <stdio.h>
#include <Xm/BulletinB.h>
#include <Xm/PanedW.h>
#include <Xm/PushB.h>
#include <Xm/Frame.h>
#include <Xm/Form.h>
#include <Xm/ScrolledW.h>
#include <Xm/Text.h>
#include <Xm/DrawingA.h>
#include <Xm/MessageB.h>
#include <Xm/RowColumn.h>
#include <Xm/DialogS.h>
#include <Xm/PushBG.h>
#include "constants.h"
popupReportWindow(widget_id, client_data, call_data, title,
                   textToDisplay)
    Widget widget id;
    caddr t client data;
    caddr_t call_data;
    char title[], textToDisplay[];
{
    Widget w, reportDialog, text_w, rowCol, form, widget, label;
    Arg args[15];
   XmString xmString;
    extern void DestroyDialog();
    extern void PrintReport();
    /*
      Set up a DialogShell as a popup window.
                                                 Set the delete
     * window protocol response to XmDESTROY to make sure that
     * the window goes away appropriately. Otherwise, it's
       XmUNMAP which means it'd be lost forever, since we're not
       storing the widget globally or statically to this function.
     */
   reportDialog = XtVaCreatePopupShell(title,
                                      xmDialogShellWidgetClass,
                                      GetTopShell(widget id),
                                      XmNdeleteResponse,
                                      XmDESTROY,
                                      NULL);
   /*
       Create a PanedWindow to manage the stuff in this dialog
   rowCol = XtVaCreateWidget("rowCol",
                            xmRowColumnWidgetClass,
                            reportDialog,
                            XmNorientation, XmVERTICAL,
                            XmNcolumns,
                            NULL);
   /*
       Create a RowColumn in the form for Label and Text widgets
    */
   form = XtVaCreateWidget("form",
                            xmFormWidgetClass,
                            rowCol,
                            XmNfractionBase, 100,
                                     239
```

```
NULL);
SetWidgetColorScheme(form, dialogBGColor);
    Convert the textual content to be displayed
 *
 *
    into an instance of ScrolledText
 */
XtSetArg(args[0], XmNscrollVertical, TRUE);
XtSetArg(args[1], XmNscrollHorizontal, FALSE);
XtSetArg(args[2], XmNeditMode, FALSE);
XtSetArg(args[3], XmNeditable, FALSE);
XtSetArg(args[4], XmNcursorPositionVisible, FALSE);
XtSetArg(args[5], XmNwordWrap, TRUE);
XtSetArg(args[6], XmNvalue, textToDisplay);
XtSetArg(args[7], XmNrows, 10);
XtSetArg(args[8], XmNcolumns, 60);
XtSetArg(args[9], XmNtopAttachment, XmATTACH_FORM);
XtSetArg(args[10], XmNbottomAttachment, XmATTACH POSITION);
XtSetArg(args[11], XmNbottomPosition, 80);
XtSetArg(args[12], XmNleftAttachment, XmATTACH_FORM);
XtSetArg(args[13], XmNrightAttachment, XmATTACH_FORM);
text w = XmCreateScrolledText(form,
               "text w",
               args,
               14);
XtManageChild(text w);
 * Create the Print button
 */
widget = XtVaCreateManagedWidget("Print",
                xmPushButtonGadgetClass, form,
                                          XmATTACH POSITION,
                XmNtopAttachment,
                                          85,
                XmNtopPosition,
                 XmNbottomAttachment,
                                          XMATTACH FORM,
                                          XMATTACH POSITION,
                 XmNleftAttachment,
                 XmNleftPosition,
                                          XMATTACH POSITION,
                 XmNrightAttachment,
                 XmNrightPosition,
                                          35,
                                          TRUE,
                 XmNshowAsDefault,
                 XmNdefaultButtonShadowThickness, 2,
                 NULL);
   Add callback routine for the Print button
XtAddCallback(widget, XmNactivateCallback,
              PrintReport, reportDialog);
/*
 * Create the Cancel button
 */
widget = XtVaCreateManagedWidget("Cancel",
                 xmPushButtonGadgetClass, form,
                 XmNtopAttachment,
                                          XmATTACH POSITION,
                 XmNtopPosition,
                                          XMATTACH FORM,
                 XmNbottomAttachment,
                                          XMATTACH POSITION,
                 XmNleftAttachment,
                 XmNleftPosition,
                                           65,
                                          XmATTACH POSITION,
                 XmNrightAttachment,
                                           75,
                 XmNrightPosition,
                                          TRUE,
                 XmNshowAsDefault,
```

updateclearanceselection.c

```
#include <Xm/Xm.h>
#include "typedefs.h"

extern FitData analysisData;

void updateClearanceSelection(widget_id, clearanceSelection)

Widget widget_id;
int clearanceSelection;

{
    analysisData.clearanceOverhead = clearanceSelection;
}
```

utils.c

```
#include <Xm/Xm.h>
/**********************
    Utility routines used throughout the program
 *************************************
extern long pictureId;
/*********************
 * Routine called as a callback to destroy the widget
 * contained in the argument "shell"
 *************************************
void DestroyDialog(widget, shell)
Widget widget, shell;
  XtDestroyWidget(shell);
}
/********************
 * Routine to find the top level shell of a widget
 ***********************
Widget GetTopShell(w)
Widget w;
{
   while (w && !XtIsWMShell(w))
     w = XtParent(w);
   return w:
}
/***********************
   Routine called as a callback to destroy the widget
   contained in the argument "shell", as well as an
   associated picture, if the picture is displayed (Id > 0)*
*************************
void DestroyShell(widget, shell)
Widget widget, shell;
  /* If a picture is being displayed, then close it's window */
  if (pictureId)
     winclose (pictureId);
  XtDestroyWidget(shell);
```

dataentry.h

```
/***********************
     Field labels used in data entry window
 char *deLabels[] = { "Thumb Tip Reach:\n(Reach)",
                  "Buttock-Knee Length:\n(Rudder Throw, Shin,\nand Leg Clearance
                  "Shoulder Height:\n(Reach)",
                  "Sitting Height: \n (Overhead Clearance)",
                  "Knee Height Sitting:\n(Rudder Throw)",
                  "Eye Height Sitting:\n(Vision)" };
/**********************
               Crew Station Definitions
   Updated during Aircraft Selection after Database query.
 *************************************
CrewStations crewStations[MAX_CREW_STATIONS_PER_AIRCRAFT] =
{ " ",
                 0},
  {" ",
                 0},
  (" ",
                 0},
  {" ",
                 0},
  {" ",
                 0},
  ξπ π,
                 0},
  {" ",
                 0},
  {11 11,
                 0},
  11 11
                 0},
  {" "
                 0},
  į " ",
                 0},
  į 11 11
                 0},
  { n n
                 0},
  {" "
                 0 } ,
  {" ",
                 0},
  ξ" ",
                 0},
  {" ",
                 0},
  įππ,
                 0},
  {" ",
                 0},
  in n;
                 0} };
char *seatPositions[] = {"Vert. Position:",
                     "Horz. Position: "};
/***********************
* Specific attributes for each aircraft. (Room for expansion) *
 ***********
AvailableAircraft aircraft[] =
{{ "F-16A",
                              /* Aircraft Name */
   F 16 A,
                              /* Aircraft ID Code */
   CREW FORWARD,
                              /* Possible crewstations for this aircraft */
   0,
   0,
   Ο,
   0,
   0,
   0,
   0,
   0,
   Ο,
   0,
   0,
   Ο,
   0,
   Ο,
   Ο,
   Ο,
   0,
   0,
                               247
   0,
```

```
/* Possible seat directions
  VERTICAL,
                                   /* Number of adjustment notches travel from ze:
  0,
  HORIZONTAL,
  0 },
                                  ' /* Aircraft Name */
{ "C-141A",
                                    /* Aircraft ID Code */
  C 141 A,
                                    /* Possible crewstations for this aircraft */
  CREW LEFT,
  CREW RIGHT,
  Ο,
  0,
  0,
   0,
  0,
  0,
   0,
   0,
  Ο,
   0,
   0,
   0,
   0,
  0,
   0,
   0,
   Ο,
   0,
                                   /* Possible seat directions
   VERTICAL,
                                   /* Number of adjustment notches travel from zer
   Ο,
   HORIZONTAL,
   0 },
                                    /* Aircraft Name */
{ "T-37B",
                                   /* Aircraft ID Code */
   T 37 B,
                                    /* Possible crewstations for this aircraft */
   CREW LEFT,
   CREW RIGHT,
   0,
   Ο,
   0,
   0,
   0,
   0,
   0,
   0,
   Ο,
   0,
   0,
   0,
   0,
   0,
                                    /* Possible seat directions
   VERTICAL,
                                    /* Number of adjustment notches travel from zet
   HORIZONTAL,
   0 },
{ "T-38A",
                                    /* Aircraft Name */
                                    /* Aircraft ID Code */
   T_38_A,
                                    /* Possible crewstations for this aircraft */
   CREW FORWARD,
   CREW AFT, .
                                     248
   Ο,
```

0,

```
0,
   0,
   0,
   0,
   0,
   0,
   Ο,
   0,
   0,
   0,
   0,
   0,
   0,
   0,
   0,
   0,
   VERTICAL,
                                         /* Possible seat directions
   0,
                                         /* Number of adjustment notches travel from ze:
   HORIZONTAL,
   0 },
                                        /* Aircraft Name */
/* Aircraft ID Code */
/* Possible crewstations for this aircraft */
{ "T-1A",
   T_1_A,
   CREW_RIGHT,
   CREW_LEFT,
   Ο,
   Ο,
   0,
   0,
   0,
   0,
   0,
   0,
   0,
   Ο,
   0,
   0,
   0,
   0,
   0,
   0,
   0,
   VERTICAL,
                                         /* Possible seat directions
   0,
                                         /* Number of adjustment notches travel from ze:
   HORIZONTAL,
   0 } };
```

menu.h

```
#include "typedefs.h"
extern void F16ASurveyDesc();
extern void C141ASurveyDesc();
extern void T37BSurveyDesc();
extern void T38ASurveyDesc();
extern void TlASurveyDesc();
extern void GenerateReport();
extern void DisplayTechInfo();
extern void updateClearanceSelection();
MenuItem aircraftMenu[] =
  { "F-16A",
                                  /* Item Label
                                                                        */
    &xmPushButtonGadgetClass,
                                  /* PushButton
                                                                        */
    NULL,
                                  /* mnemonic or NULL
                                                                        */
    NULL,
                                  /* Accelerator or NULL
                                                                        */
    NULL,
                                  /* to be converted to compound str
    F16ASurveyDesc,
                                  /* Routine to call
                                                                        */
    Ο,
                                  /* Client data for callback()
                                                                        */
    NULL },
                                  /* Pullright menu items
  { "C-141A",
    &xmPushButtonGadgetClass,
    NULL,
   NULL,
    NULL,
    C141ASurveyDesc,
    Ο,
    NULL },
  { "T-37B",
    &xmPushButtonGadgetClass,
    NULL, NULL,
              NULL,
    T37BSurveyDesc,
    0,
    NULL },
  { "T-38A",
    &xmPushButtonGadgetClass,
    NULL,
    NULL,
    NULL,
    T38ASurveyDesc,
    Ο,
    NULL },
  { "T-1A",
    &xmPushButtonGadgetClass,
    NULL,
    NULL,
    NULL,
    TlaSurveyDesc,
    Ο,
    NULL },
  NULL,
};
MenuItem surveyMenu[] =
  { "Aircraft Survey Descriptions",
    &xmPushButtonGadgetClass,
    NULL,
    NULL,
    NULL,
    Ο,
    aircraftMenu },
                                       251
  NULL,
```

```
};
MenuItem visionMenu[] =
   { "Explanation",
     &xmPushButtonGadgetClass,
     NULL,
     NULL,
     NULL,
     DisplayTechInfo,
     (XtPointer) VISION,
     NULL },
   { "Report",
     &xmPushButtonGadgetClass,
     NULL,
     NULL,
     NULL,
     GenerateReport,
     (XtPointer) VISION,
     NULL },
   NULL,
};
MenuItem reachRudderThrowReportMenu[ ] =
   { "Explanation",
     &xmPushButtonGadgetClass,
     NULL,
     NULL,
     NULL,
     DisplayTechInfo,
     (XtPointer) REACH_RUDDER_THROW,
     NULL },
   { "Report",
     &xmPushButtonGadgetClass,
     NULL,
     NULL,
     NULL,
     GenerateReport,
      (XtPointer) REACH RUDDER_THROW,
   NULL,
MenuItem reachArmReachIndividualControlsReportMenu[] =
   { "Explanation",
     &xmPushButtonGadgetClass,
      'E',
     NULL,
     NULL,
     DisplayTechInfo,
      (XtPointer) REACH_ARM_REACH_INDIVIDUAL_CONTROLS,
     NULL },
    { "Report",
      &xmPushButtonGadgetClass,
      'R',
     NULL,
     NULL,
      GenerateReport,
      (XtPointer) REACH_ARM_REACH_INDIVIDUAL_CONTROLS,
      NULL },
   NULL,
};
MenuItem reachArmReachAllMissedControlsReportMenu[ ] =
    { "Explanation",
                                        252
      &xmPushButtonGadgetClass,
```

```
'E',
     NULL,
     NULL,
     DisplayTechInfo,
      (XtPointer) REACH_ARM_REACH_ALL_MISSED CONTROLS,
     NULL },
    { "Report",
     &xmPushButtonGadgetClass,
     'R',
     NULL,
     NULL,
     GenerateReport,
      (XtPointer) REACH ARM REACH ALL MISSED CONTROLS,
   NULL,
};
MenuItem reachArmReachControlRegionLeftSidePanelReportMenu[ ] =
   { "Explanation",
     &xmPushButtonGadgetClass,
     'E',
     NULL,
     NULL,
     DisplayTechInfo,
     (XtPointer) REACH_ARM_REACH_CONTROL_REGION LEFT SIDE PANEL,
     NULL },
   { "Report",
     &xmPushButtonGadgetClass,
     'R',
     NULL,
     NULL,
     GenerateReport,
     (XtPointer) REACH ARM REACH CONTROL REGION LEFT SIDE PANEL,
     NULL },
   NULL,
};
MenuItem reachArmReachControlRegionLeftAuxiliaryPanelReportMenu[ ] =
   { "Explanation",
     &xmPushButtonGadgetClass,
     'E',
     NULL,
     NULL,
     DisplayTechInfo,
     (XtPointer) REACH ARM REACH CONTROL REGION LEFT AUXILIARY PANEL,
     NULL },
   { "Report",
     &xmPushButtonGadgetClass,
     'R',
     NULL,
     NULL,
     GenerateReport,
     (XtPointer) REACH ARM REACH CONTROL REGION LEFT AUXILIARY PANEL,
     NULL },
   NULL,
};
MenuItem reachArmReachControlRegionMainInstrumentPanelReportMenu[ ] =
{
   { "Explanation",
     &xmPushButtonGadgetClass,
     'E',
     NULL,
     NULL,
     DisplayTechInfo,
     (XtPointer) REACH ARM REACH CONTROL REGION MAIN INSTRUMENT PANEL,
     NULL },
                                       253
```

```
{ "Report",
     &xmPushButtonGadgetClass,
     'R',
     NULL.
     NULL,
     GenerateReport,
     (XtPointer).REACH ARM REACH CONTROL REGION_MAIN_INSTRUMENT_PANEL,
     NULL },
   NULL,
};
MenuItem reachArmReachControlRegionCenterPedestalReportMenu[] =
   { "Explanation",
     &xmPushButtonGadgetClass,
     'E',
     NULL,
     NULL,
     DisplayTechInfo,
     (XtPointer) REACH ARM REACH CONTROL REGION CENTER PEDESTAL,
     NULL },
   { "Report"
     &xmPushButtonGadgetClass,
     NULL,
     NULL,
     GenerateReport,
     (XtPointer) REACH ARM REACH CONTROL REGION CENTER PEDESTAL,
     NULL },
   NULL.
};
MenuItem reachArmReachControlRegionRightSidePanelReportMenu[] =
   { "Explanation",
     &xmPushButtonGadgetClass,
     'E',
     NULL,
     NULL,
     DisplayTechInfo,
     (XtPointer) REACH ARM REACH CONTROL REGION RIGHT SIDE PANEL,
     NULL },
   { "Report",
     &xmPushButtonGadgetClass,
     'R',
     NULL,
     NULL,
     GenerateReport,
     (XtPointer) REACH ARM REACH CONTROL REGION RIGHT_SIDE_PANEL,
     NULL }.
   NULL,
};
MenuItem reachArmReachControlRegionRightSideAuxiliaryPanelReportMenu[] =
   { "Explanation",
     &xmPushButtonGadgetClass,
     'E',
     NULL,
     NULL,
     DisplayTechInfo,
     (XtPointer) REACH ARM REACH CONTROL REGION RIGHT AUXILIARY PANEL,
     NULL },
   { "Report"
     &xmPushButtonGadgetClass,
     'R',
     NULL,
     NULL,
                                       254
```

GenerateReport,

```
(XtPointer) REACH_ARM REACH_CONTROL REGION RIGHT AUXILIARY_PANEL,
    NULL,
 };
MenuItem reachArmReachControlRegionMenu[ ] =
 {
    { "Left Side Panel",
      &xmPushButtonGadgetClass,
      'Α',
      NULL,
      NULL,
      0,
      0,
      reachArmReachControlRegionLeftSidePanelReportMenu },
    { "Left Auxiliary Panel",
      &xmPushButtonGadgetClass,
      'A',
      NULL,
      NULL,
      0,
      ٥,
      reachArmReachControlRegionLeftAuxiliaryPanelReportMenu },
    { "Main Instrument Panel",
      &xmPushButtonGadgetClass,
      'A',
     NULL,
     NULL,
     Ο,
     0,
     reachArmReachControlRegionMainInstrumentPanelReportMenu },
    { "Center Pedestal",
     &xmPushButtonGadgetClass,
      'A',
     NULL,
     NULL,
     Ο,
     0,
     reachArmReachControlRegionCenterPedestalReportMenu },
    { "Right Side Panel",
     &xmPushButtonGadgetClass,
     'A',
     NULL.
     NULL,
     ٥,
     reachArmReachControlRegionRightSidePanelReportMenu },
   { "Right Auxiliary Panel",
     &xmPushButtonGadgetClass,
     'A',
     NULL,
     NULL,
     0,
     0,
     reachArmReachControlRegionRightSideAuxiliaryPanelReportMenu },
   NULL,
MenuItem reachArmReachMenu[ ] =
   { "Control Region",
     &xmPushButtonGadgetClass,
     'A',
     NULL,
     NULL,
     0,
     reachArmReachControlRegionMenu } 255
```

```
{ "Individual Controls",
     &xmPushButtonGadgetClass,
     'R',
     NULL,
     NULL,
     0,
     0,
     reachArmReachIndividualControlsReportMenu },
   { "List All Missed Controls",
     &xmPushButtonGadgetClass,
     'A',
     NULL,
     NULL,
     0,
     0,
     reachArmReachAllMissedControlsReportMenu },
   NULL,
};
MenuItem reachMenu[ ] =
   { "Arm Reaches",
     &xmPushButtonGadgetClass,
     'A',
     NULL,
     NULL,
     0,
     0,
     reachArmReachMenu },
   { "Rudder Throw",
     &xmPushButtonGadgetClass,
     'R',
     NULL,
     NULL,
     0,
     reachRudderThrowReportMenu },
   NULL,
};
MenuItem overheadClearanceReportMenu[ ] =
{
   { "Explanation",
      &xmPushButtonGadgetClass,
      'Ε',
     NULL,
     NULL,
      DisplayTechInfo,
      (XtPointer) CLEARANCE OVERHEAD,
     NULL },
    { "Report",
      &xmPushButtonGadgetClass,
      'R',
      NULL,
      NULL,
      GenerateReport,
      (XtPointer) CLEARANCE OVERHEAD,
      NULL },
   NULL,
};
MenuItem shinClearanceReportMenu[ ] =
    { "Explanation",
      &xmPushButtonGadgetClass,
      'E',
      NULL,
                                         256
      NULL,
      DisplayTechInfo,
```

```
(XtPointer) CLEARANCE SHIN WITH INSTRUMENT PANEL,
     NULL },
   { "Report",
     &xmPushButtonGadgetClass,
     'R',
     NULL,
     NULL,
     GenerateReport,
     (XtPointer) CLEARANCE SHIN WITH INSTRUMENT PANEL,
   NULL,
};
MenuItem glareShieldClearanceReportMenu[ ] =
   { "Explanation",
     &xmPushButtonGadgetClass,
     'E',
     NULL,
     NULL,
     DisplayTechInfo,
     (XtPointer) CLEARANCE EJECTION WITH GLARE SHIELD,
     NULL },
   { "Report"
     &xmPushButtonGadgetClass,
     'R',
     NULL,
     NULL,
     GenerateReport,
     (XtPointer) CLEARANCE_EJECTION_WITH_GLARE_SHIELD,
     NULL },
   NULL,
};
MenuItem canopyBowClearanceReportMenu[ ] =
   { "Explanation",
     &xmPushButtonGadgetClass,
     'E',
     NULL,
     NULL,
     DisplayTechInfo,
     (XtPointer) CLEARANCE EJECTION WITH CANOPY BOW,
     NULL },
   { "Report",
     &xmPushButtonGadgetClass,
     'R',
     NULL,
     NULL,
     GenerateReport,
     (XtPointer) CLEARANCE_EJECTION_WITH_CANOPY_BOW,
     NULL },
   NULL,
};
MenuItem clearanceMenu[] =
{
   { "Overhead",
     &xmPushButtonGadgetClass,
     10',
     NULL,
     NULL,
     0,
     overheadClearanceReportMenu },
   { "Shin with Instrument Panel",
     &xmPushButtonGadgetClass,
     'S',
                                        257
     NULL,
```

```
NULL,
     0,
     0,
     shinClearanceReportMenu },
   { "Ejection with Glare Shield",
     &xmPushButtonGadgetClass,
     'G',
     NULL,
     NULL,
     0,
     0,
     glareShieldClearanceReportMenu },
   { "Ejection with Canopy Bow",
     &xmPushButtonGadgetClass,
     'C',
     NULL,
     NULL,
     0,
     0,
     canopyBowClearanceReportMenu },
   NULL,
};
MenuItem dataMenu[] =
   { "Clearance",
     &xmPushButtonGadgetClass,
     'C',
     NULL,
     NULL,
     0,
     0,
     clearanceMenu },
   { "Reach",
     &xmPushButtonGadgetClass,
     'R',
      NULL,
     NULL,
     0,
     0,
     reachMenu },
   { "Vision",
     &xmPushButtonGadgetClass,
     'V',
     NULL,
     NULL,
     0,
     visionMenu },
   NULL,
};
MenuItem overheadClearanceMenu[] =
   { "For 1 inch clearance overhead",
     &xmPushButtonGadgetClass,
     NULL,
     NULL,
     NULL,
     updateClearanceSelection,
      (XtPointer)ONE_INCH_CLEARANCE_OVERHEAD,
    { "For 2 inch clearance overhead",
      &xmPushButtonGadgetClass,
     NULL,
                                        258
```

NULL,

```
NULL,
     updateClearanceSelection,
     (XtPointer) TWO_INCH_CLEARANCE OVERHEAD,
   { "For 3 inch clearance overhead",
     &xmPushButtonGadgetClass,
     NULL,
     NULL,
     NULL,
     updateClearanceSelection,
     (XtPointer) THREE INCH CLEARANCE OVERHEAD,
     NULL },
   { "For 4 inch clearance overhead",
     &xmPushButtonGadgetClass,
     NULL,
     NULL,
     NULL,
     updateClearanceSelection,
     (XtPointer) FOUR INCH_CLEARANCE_OVERHEAD,
     NULL },
   NULL,
};
```

constants.h

```
#define dialogBGColor
                          "darkslategray"
#define dialogSectionBGColor
                          "dimgray"
#define dialogSectionTitleColor "lightgray"
#define dialogFillInFieldColor
                          "wheat"
/**********************
                  Maximun number of Aircraft
 *************************
#define MAX AIRCRAFT
/************************
              Aircraft identification codes
 **************************
#define F 16 A
#define C_141_A
#define T^{-}37 \overline{B}
#define T_38_A
#define T_1_A
/**********************
             Crewstation identification codes
#define CREW LEFT
#define CREW_RIGHT
                  2
#define CREW FORWARD 3
#define CREW AFT
                   Limiting Parmeters
**********************
#define MAX_LENGTH_OF_AIRCRAFT_NAME
#define MAX_SEAT_ADJ_DIRECTIONS
                                10
                                 2
#define MAX_CREW_STATIONS PER AIRCRAFT 20
#define MAX LENGTH OF CREWSTATION NAME 20
#define MAX MEASUREMENTS_TAKEN
/***********************
   Seat adjustment direction identification codes
************************
#define VERTICAL
#define HORIZONTAL
/*************************
  Codes for each database or tech information query *
************************
#define CLEARANCE OVERHEAD
#define CLEARANCE SHIN WITH INSTRUMENT PANEL
#define CLEARANCE_EJECTION_WITH_GLARE_SHIELD
#define CLEARANCE EJECTION WITH CANOPY BOW
#define REACH_ARM_REACH_CONTROL_REGION_LEFT_SIDE_PANEL #define REACH_ARM_REACH_CONTROL_REGION_LEFT_AUXILIARY_PANEL
#define REACH_ARM_REACH_CONTROL_REGION_MAIN_INSTRUMENT_PANEL
#define REACH ARM REACH CONTROL REGION CENTER PEDESTAL
                                                   8
#define REACH ARM REACH CONTROL REGION RIGHT SIDE PANEL
#define REACH_ARM_REACH_CONTROL_REGION_RIGHT_AUXILIARY PANEL 10
#define REACH ARM REACH INDIVIDUAL CONTROLS
                                                  11
#define REACH ARM REACH ALL MISSED CONTROLS
                                                  12
#define REACH RUDDER THROW
                                                  13
#define VISION
/*********************************
```

## APPENDIX G PROGRAM CINPUT

## CINPUT PROGRAM LISTING

```
program cinput
    logical*l airflag,sbjflag,inflag,okflag,regflag
    logical*1 seatflag,loopflag,chkflag,doneflag
    character*l inchar,crew(4)
    character*8 aname
    character*10 acat
    character * 60 inline
    character*12 filename
    integer crewcnt,icnt,regcnt(2),crewidx
    integer region(4,12)
    integer crewst(4)
   character*1 regchar(4)
    data regchar /'y','Y','n','N'/
    character*l catchar(6)
    data catchar /'f','F','c','C','t','T'/
    character*1 crewchar(8)
    data crewchar /'f','F','a','A','l','L','r','R'/
    integer crewin(8)
    data crewin /3,3,4,4,1,1,2,2/
    character*10 crewname(4)
    data crewname /'LEFT', 'RIGHT', 'FORWARD', 'AFT'/
    character*30 regname(12)
    data reqname /'LEFT-SIDE-PANEL', 'LEFT-AUXILIARY-PANEL',
1 'MAIN-INSTRUMENT-PANEL', 'CENTER-PEDESTAL', 'RIGHT-AUXILIARY-PANEL',
1 'RIGHT-SIDE-PANEL', 'OVERHEAD-CONTROL-PANEL', 'LEFT-BULKHEAD',
1 'RIGHT-BULKHEAD', 'GLARE-SHIELD', 'CONTROL-STICK', 'SEAT'/
    integer seatcnt(4), seatidx
    character*l seattype(4,3)
    real seatinc(4,3)
    real seatrang(4,3)
    character*l seatadj(4,3)
    character*l seatchar(6)
    data seatchar /'V','v','H','h','T','t'/
    character*2 sadjtyp(4)
    data sadjtyp /'C','c','N','n'/
    character*10 seatname(6)
    data seatname /'VERTICAL', 'VERTICAL', 'HORIZONTAL', 'HORIZONTAL',
                  'SEAT-TILT', 'SEAT-TILT'/
    character*l contchar(8)
    data contchar/ 'G', 'g', 'F', 'f', 'H', 'h', 'T', 't'/
```

```
character*l handchar(6)
           data handchar/ 'R', 'r', 'L', 'l', 'B', 'b'/
           character*l incont,inhand
           integer contcnt(4,12)
           character*60 contname(4,12,100)
           character*l conttype(4,12,100)
           character*l conthand(4,12,100)
          airflag = .false.
           sbjflag = .false.
           inflag = .true.
          do 15 while (inflag)
          write(*,1)
1
          format(///,5x,'Data will be accepted in upper or lower case')
          write (*,3)
3
          format(//,'
                          What type of data would you like to enter?',/)
          write (*,5)
5
          format($,'
                          Enter "A" for aircraft data or "S" for subject da
          read (*,10) inchar
10
          format(al)
          if ( (inchar .eq. 'A') .cr. (inchar .eq. 'a') ) then
             airflag = .true.
             inflag = .false.
          elseif ( (inchar .eq. 'S') .or. (inchar .eq. 's') ) then
             sbiflag = .true.
             inflag = .false.
          endif
15
          end do
          inflag = .true.
C *** Enter Aircraft Data
          if (airflag) then
             write(*,20)
20
             format(//,$,' Aircraft Name: ')
             read(*,25)aname
25
             format(a8)
             if (aname .eq. ^{\prime} ^{\prime} ) then
                doneflag = .true.
             endif
             if (.not. doneflag) then
             open(unit=20,file=aname,status='new')
                                265
```

```
write(20,27)aname
27
             format(2x,'ANAME ',2x,a8)
C *** Enter Aircraft Category
             write(*,30)
30
             format(//,' Aircraft category: ')
             inflag = .true.
             do while (inflag)
                write(*,35)
35
                format(/,$,' F(ighter), C(argo), T(rainer): ')
                read(*,36)acat
36
                format(al0)
                do i=1,6
                   if (acat .eq. catchar(i))then
                   inflag = .false.
                   write(20,37)acat
37
                    format(2x,'CATEGORY ',2x,a10)
                 endif
                end do
                if (inflag) then
                   write(*,38)
38
                format(' **Invalid category, please re-enter**')
                endif
             end do
C *** station
                inflag = .true.
                crewidx = 1
                do 1000 while (inflag)
                 write(*,40)
40
                  format(//,' Enter Crewstation, <cr> when done ')
               write(*,45)
45
               format(/,$'
                              F(orward), A(ft), L(eft), R(ight): ')
               read(*,50)crew(crewidx)
50
               format(al)
               if (crew(crewidx) .eq. ' ') then
                     inflag = .false.
               else
                  okflag = .false.
                  do i = 1.8
```

```
if ( crew(crewidx) .eq. crewchar(i) ) then
                         okflag = .true.
                         crewst(crewidx) = crewin(i)
                      endif
                   end do
                   if (.not. okflag) then
                      write(*,52)
52
                      format(/,5x,'***Invalid crewstation - reenter***')
                   else
                    do i = l,crewcnt
                      if (crewst(crewidx) .eq. crewst(i)) then
                         okflag = .false.
                         write(*,56)
56
                         format(/,5x,
                         '***This crewstation has already been selected***
     1
                      endif
                    end do
                endif
                if (ckflag) then
                      write(*,55)crewname(crewst(crewidx))
55
                      format(/,5x,'CREWSTATION SELECTED: ',al0)
                            crewcnt = crewidx
c *** Regions Within The Selected Crewstation ***
                             regcnt(crewcnt) = 0
                      write(*,60)
60
                      format(/,
     1
                      Is this control region applicable? Y(es) or N(o)',/)
                      do k=1,12
                        loopflag = .true.
                        do while (loopflag)
                         write(*,65)regname(k)
65
                         format($,5x,a30,': ')
                         read(*,70)inchar
7.0
                         format(al)
                         if ( ( inchar .eq. 'y') .or.
     1
                               (inchar .eq. 'Y')) then
                             regent(crewent) = regent(crewent) + 1
                             region(crewidx,regent(crewent)) = k
                             loopflag = .false.
                         elseif ( ( inchar .eq. 'n') .or.
     1
                                (inchar .eq. 'N') )then
                            loopflag = .false.
                         endif
                      end do !while loopflag
                   end do
```

```
else
                        if (.not. okflag) write(*,100)
 C100
                        format('
                                    **Invalid crewstation, re-enter**')
                    endif
                 endif
 C *** Seat Adjustment Data
                 loopflag = .true.
                 icnt = 1
               do while (loopflag .and. inflag .and. okflag .and.
      1
                 (icnt .le. 3))
                   write(*,120)
 120
                   format(//5x,'Seat Adjustment Data')
                   write(*,125)
 125
                   format(5x,'Each Direction will be Processed Separately')
                 write(*,135)
135
                 format(/,$,5x,'V(ertical), H(orizontal), T(ilt Seat): ')
                 read(*,140)seatadj(crewidx,icnt)
140
                 format(al)
                 okflag = .true.
                 if (seatadj(crewidx,icnt) .eq. '') then
                    if (icnt .ne. 1) then
                       loopflag = .false.
С
                       seatcnt = icnt -1
                    endif
                else
                    okflag = .false.
                   do i=1,6
                       if (seatadj(crewidx,icnt) .eq. seatchar(i)) then
                       okflag = .true.
                       seatidx = i
                      endif
                   end do
                   if (.not. okflag) then
                   write(*,250)
250
                   format(' **Invalid seat direction, please re-enter**
                   okflag = .true.
                   else
                      write(*,150)seatname(seatidx)
150
                      format(/,5x,'SEAT DIRECTION: ',al0)
```

```
write(*,160)
160
                       format(/,5x,
     1
                       'Select Type of Adjustment for this Direction: ')
                       seatflag = .true.
                       do while (seatflag)
                       seatcnt(crewidx) = seatcnt(crewidx) + 1
                       write(*,170)
170
                       format(/,$,5x,'C(ontinuous) or N(otched): ')
                       read(*,180)seattype(crewidx,icnt)
180
                       format(al)
                       do n = 1,4
                        if (seattype(crewidx,icnt) .eq. sadjtyp(n)) then
                             seatflag = .false.
                          end if
                       end do
                       if (seatflag) then
                       write(*,185)
185
                        format(5x,'**invalid entry - please re-enter**')
                       end if
                       end do
                       seatflag = .true.
                       do while (seatflag)
                       write(*,190)
190
                             format(/, \$, 5x,
                             'Enter Increment for One Seat Adjustment: ')
     1
                       read (*,200,err=205)seatinc(crewidx,icnt)
200
                       format(f5.0)
                       if (seatinc(crewidx,icnt) .gt. 0.0) seatflag = .false
205
                         if (seatflag) then
                        write(*,185)
                         end if
                       end do
                       seatflag = .true.
                       do while (seatflag)
                      write(*,210)
210
                             format(/, \$, 5x,
                                 269
```

```
1
                'Enter Seat Travel in inches from Full-up to Full-down: '
                       read (*,220,err=225)seatrang(crewidx,icnt)
220
                       format(f5.0)
                      if (seatrang(crewidx,icnt) .gt. 0.0) seatflag = .fal
225
                         if (seatflag) then
                       write(*,185)
                         end if
                      end do
                       icnt = icnt + 1
                   end if
                end if
                end do
                crewidx = crewidx + 1
1000
             end do
c *** Control Data Processing ***
          inflag = .true.
          do 4000 while ( (inflag) .and. (crewcnt .ne. 0))
             do 3500 i = 1, crewent
                if (regcnt(i) .ne. 0) then
                do 3000 j = 1,regcnt(i)
                   loopflag = .true.
                   contcnt(i,j) = 0
                   contnum = 0
                   write(*,2100)
2100
                   format(/,5x,'Enter control data for: ')
                 do 2900 while (loopflag)
                   write(*,2110)crewname(crewst(i)),regname(region(i,j)
2110
                   format(/,5x,'CREWSTATION: ',al0,' REGION: ',a30)
                   write(*,2120)
2120
                   format(5x,
     1
                   'Control Names are 60 chars max, use dashes as delimiter
                   write(*,2122)
```

```
format(/,5X,$,'Control Name: ')
2122
                   contnum = contnum + 1
                   read(*,2125)contname(i,j,contnum)
                   format(a60)
2125
                   if (contname(i,j,contnum) .eq. ' ') then
                      loopflag = .false.
                   else
                   content(i,j) = content(i,j) + 1
                   inflag = .true.
                   do while (inflag)
                      write(*,2135)
                            format(/,$,' G(rip), F(inger), H(ook), T(
2135
                      read(*,2140)incont
                      format(al)
2140
                      do k=1.8
                         if (incont .eq. contchar(k)) then
                          inflag = .false.
                          conttype(i,j,contnum) = incont
                       endif
                            end do
                            if (inflag) then
                      write(*,2145)
                      format(' **Invalid control type, please re-ente
2145
                            endif
                  end do
c *** Which hand reaches this control? ***
                   inflag = .true.
                   do while (inflag)
                      write(*,2150)
                             format(/,$,' R(ight), L(eft), B(oth): ')
2150
                       read(*,2155)inhand
                      format(al)
2155
                      ao k=1.6
                          if (inhand .eq. handchar(k)) then
                           inflag = .false.
                           conthand(i,j,contnum) = inhand
                       endif
                             end do
                                 271
```

```
if (inflag) then
                      write(*,2165)
2165
                                   **Invalid hand, please re-enter**')
                      format(4
                            endif
                  end do
                  endif !if contname .ne. ' '
2900
               end do !while loopflag
3000
                end do
                 endif
3500
                end do
4000
            end do
C *** write out aircraft file ***
          write(20,4010)crewcnt
4010
          format(2x,'CREWCNT
                                 ',2x,i2)
          do 4900 i = 1.crewcnt
             write(20,4015)crewst(i)
4015
             format(3x,'CREWSTATION',2x,i2)
             write(20,4017)seatcnt(i)
4017
             format(4x,'SEATCNT
                                  ',2x,il)
             do 4050 l = 1,3
               if ( (seattype(i,l) .eq. 'c') .or. (seattype(i,l) .eq. 'C'
     1
              .or. (seattype(i,l) .eq. 'n') .or. (seattype(i,l) .eq. 'N'
                write(20,4020)seatadj(i,1)
4020
                format(5x,'SEATADJ
                                        ',2x,al)
                write(20,4030)seattype(i,1)
4030
                format(6x,'SEATTYPE
                                     ',2x,al)
                write(20,4035)seatinc(i,1)
4035
                format(6x,'SEATINC
                                       ',2x,f7.3)
                write(20,4040)seatrang(i,1)
4040
                format(6x,'SEATRANGE ',2x,f7.3)
               endif
4050
             end do
             write(20,4055)regcnt(i)
4055
             format(4x,'REGCNT
                                   ',2x,i2)
             do 4800 j = 1, regcnt(i)
               write(20,4060)region(i,j)
4060
               format(5x,'REGNUM
                                      ',2x,i2)
```

```
write(20,4070)contcnt(i,j)
4070
                format(6x,'CONTCNT
                                       ',2x,i3)
             do 4700 k=1,contcnt(i,j)
                write(20,4080)contname(i,j,k)
4080
                format(7x,'CONTNAME
                                      ',2x,a60)
                write(20,4090)conttype(i,j,k)
4090
                format(8x,'CONTTYPE
                                        ',2x,al)
                write(20,4100)conthand(i,j,k)
4100
                format(8x,'CONTHAND
                                       ',2x,al)
4700
             end do
4800
           end do
4900
             end do
          end if !if .not. doneflag
          close(unit=20)
          else
             call subject
          end if ! if airflag
          write(*,5000)
5000
          format(//,5x,'***Exiting Cockpit Input Program***',///)
          end
          subroutine subject
          logical*l sbjflag,inflag,okflag,loopflag,doneflag,zoneflag
          character*l inchar
          character*8 aname
          character*12 inline(2)
          character*16 filename
          character*30 sbjname
         integer sbjnum
         integer zone
         real acrhtsit, buttknee, kneehtst, sitht, eyehtsit
          real stature, weight, shldrbrt
         real ttreach(2), ttgrip(2), ttfing(2), tthook(2), ttthumb(2)
         integer crewcnt, seatcnt, regcnt(2)
         integer region(4,12)
         integer crewst(4)
         integer crewidx, regidx, contidx
         integer ccount
                               273
```

```
integer contnum(4,12,100)
          integer contcnt(4,12)
          real contdata(4,12,100,2,2)
          character*60 contname(4,12,100)
          character*1 conttype(4,12,100)
          character*l conthand(4,12,100)
          character*1 crewchar(8)
          data crewchar /'f','F','a','A','l','L','r','R'/
          integer crewin(8)
          data crewin /3,3,4,4,1,1,2,2/
          character*10 crewname(4)
          data crewname /'LEFT', 'RIGHT', 'FORWARD', 'AFT'/
          character*30 regname(12)
          data regname /'LEFT-SIDE-PANEL', 'LEFT-AUXILIARY-PANEL',
     1 'MAIN-INSTRUMENT-PANEL', 'CENTER-PEDESTAL', 'RIGHT-AUXILIARY-PANEL
       'RIGHT-SIDE-PANEL','OVERHEAD-CONTROL-PANEL','LEFT-BULKHEAD',
     1 'RIGHT-BULKHEAD', 'GLARE-SHIELD', 'CONTROL-STICK', 'SEAT'/
          inflag = .true.
C *** Enter Aircraft Data
             write(*,20)
             format(//,$,' Aircraft Name: ')
20
             read(*,25)aname
25
             format(a8)
             if (aname .eq. ' ') then
                doneflag = .true.
             endif
             if (.not. doneflag) then
                okflag = .false.
                open(unit=20, file=aname, status='old', err=30, readonly)
      1
                mode='read',err=30)
                filename(1:8)='subject.'
                filename(9:16)=aname
                open(unit=21, file=filename, access='append', status='unkno
                err=30)
     1
                okflag = .true.
                if (.not. okflag) then
30
                write(*,50)
                format(//,5x,'***File Open Error-Check Aircraft Data File
50
                else
                                 274
```

```
write(21,60)aname
60
                 format(2x,'ANAME
                                         ',2x,a8)
: *** read aname, category ***
                    read(20,70)inline(1),inline(2)
70
                    format(2x,al2,2x,a8)
                    read(20,72)inline(1),inline(2)
72
                    format(2x,a12,2x,a1)
c *** read crewcnt ***
                 read(20,75)inline(1),crewcnt
75
                 format(2x,al2,2x,i2)
                 do 300 i = 1, crewent
                    read(20,80)inline(1),crewst(i)
80
                    format(3x,al2,2x,i2)
                    read(20,90)inline(1),seatcnt
90
                    format(4x,al2,2x,il)
                    do j = 1,seatcnt
                       do k = 1,4
                       read(20,100)inline(1),inline(2)
100
                       format(al2,2x,al2)
                       end do
                    end do
                    read(20,110)inline(1),regcnt(i)
110
                    format(4x,al2,2x,i2)
                    ccount = 1
                    do 200 j = 1,regcnt(i)
                       read(20,120)inline(1),region(i,j)
120
                       format(5x,al2,2x,i2)
                       read(20,130)inline(1),contcnt(i,j)
130
                      format(6x,al2,2x,i3)
                      do 180 k = 1, content(i,j)
                          read(20,140)inline(1),contname(i,j,k)
140
                          format(7x,al2,2x,a60)
                          read(20,150)inline(1),conttype(i,j,k)
150
                          format(8x,al2,2x,al)
                          read(20,160)inline(1),conthand(i,j,k)
160
                          format(8x,a12,2x,a1)
                                 275
```

```
ccount = ccount + 1
                      end do
180
                   end do
200
                end do
300
c ***Input Subject Data***
                inflag = .true.
                do 2000 while (inflag)
                    sbjnum = 0
1069
                   write(*,1070)
                   format(//,5x,$,'Subject Number: ')
1070
                    read(*,1075,err=1069)sbjnum
                    format(i4)
1075
                    if (sbjnum .eq. 0) then
                       inflag = .false.
                    endif
                    if (inflag) then
                   write(*,1080)
                    format(/,5x,$,'Subject Name: ')
1080
                    read(*,1085)sbjname
                    format(a30)
1085
                   write(*,1090)
                   format(//,5x,'ENTER SUBJECT ANTHROPOMETRY')
1090
1094
                   write(*,1095)
                    format(/,5x,$,'Stature: ')
1095
                    read(*,1100,err=1094)stature
                    format(f10.0)
1100
                   write(*,1110)
1109
                   format(/,5x,$,'Weight: ')
1110
                    read(*,1100,err=1109)weight
                   write(*,1115)
1114
1115
                   format(/,5x,$,'Sitting-Height: ')
                    read(*,1100,err=1114)sitht
```

contnum(i,j,k) = ccount

```
1119
                    write(*,1120)
1120
                    format(/,5x,$,'Eye-Height-Sitting: ')
                    read(*,1100,err=1119)eyehtsit
1124
                    write(*,1125)
1125
                    format(/,5x,$,'Acromion-Height-Sitting: ')
                    read(*,1130,err=1124)acrhtsit
1130
                    format(f5.0)
1134
                    write(*,1135)
1135
                    format(/,5x,$,'Buttock-Knee-Length:
                                                          ′)
                    read(*,1100,err=1134)buttknee
1136
                    write(*,1137)
1137
                    format(/,5x,$,'Knee-Height-Sitting:
                                                          ′)
                    read(*,1100,err=1136)kneehtst
1139
                    write(*,1140)
1140
                    format(/,5x,$,'Shoulder-Breadth:
                                                       ')
                    read(*,1100,err=1139)shldrbrt
                    write(*,1142)
1142
                    format(//,5x,'LEFT HAND DATA')
1144
                    write(*,1145)
1145
                    format(/,5x,$,'Thumb-Tip-Reach:
                    read(*,1100,err=1144)ttreach(1)
1164
                    write(*,1165)
1165
                    format(/,5x,$,'X to Grip: ')
                    read(*,1100,err=1164)ttgrip(1)
1149
                   write(*,1150)
1150
                    format(/,5x,\$,'X to Finger:
                    read(*,1100,err=1149)ttfing(1)
1154
                   write(*,1155)
1155
                   format(/,5x,\$,'X to Hook:
                   read(*,1100,err=1154)tthook(1)
1159
                   write(*.1160)
1160
                   format(/,5x,$,'X to Thumb:
                   read(*,1100,err=1159)ttthumb(1)
                   write(*,1170)
                                 277
```

```
1170
                    format(//,5x,'RIGHT HAND DATA')
1239
                    write(*,1240)
1240
                    format(/,5x,$,'Thumb-Tip-Reach: ')
                    read(*,1100,err=1239)ttreach(2)
1259
                    write(*,1260)
1260
                    format(/,5x,$,'X to Grip: ')
                    read(*,1100,err=1259)ttgrip(2)
1244
                    write(*,1245)
1245
                    format(/,5x,$,'X to Finger: ')
                    read(*,1100,err=1244)ttfing(2)
1249
                    write(*,1250)
1250
                    format(/,5x,$,'X to Hook: ')
                    read(*,1100,err=1249)tthook(2)
1254
                    write(*,1255)
1255
                    format(/,5x,$,'X to Thumb: ')
                    read(*,1100,err=1254)ttthumb(2)
                   write(21,1265)sbjnum,sbjname,stature,weight,
     1
                       sitht, eyehtsit, acrhtsit, buttknee, kneehtst, shldrbr
1265
                         format(2x,i3,2x,a30,/,2x,8(fl0.3,2x))
                   write(21,1268)(ttreach(kk),ttgrip(kk),ttfing(kk),
                            tthook(kk),ttthumb(kk),kk=1,2)
1268
                         format(5(2x,f10.3))
                   sbjflag = .true.
                   write(*,1270)
1270
                   format(//,5x,'Enter Subject Reach Data',//)
                 do while (sbjflag)
                   write(*,1275)
1275
                   format(//,5x,\$,
     1
                   'For Crewstation F(orward), A(ft), L(eft), R(ight):')
                   read(*,1280)inchar
1280
                   format(al)
                   ckflag = .false.
                   if (inchar .eq. ' ') then
                      sbjflag = .false.
                   else
                      do i = 1.8
```

278

```
if (inchar .eq. crewchar(i)) then
                            do n = 1,crewcnt
                               if (crewin(i) .eq. crewst(n)) then
                                  okflag = .true.
                                        crewidx = n
                               end if
                            end do
                         end if
                      end do
                      if ( .not. okflag ) then
                      write(*,1300)
                      format(5x,'No Data Available for this Crewstation')
1300
                      end if
                   end if
                if ( (sbjflag) .and. (ckflag) ) then
                   write(*,1310)crewname(crewst(crewidx))
                   format(/,5x,'Subject Data for Crewstation: ',al0)
1310
                   loopflag = .true.
                   do 1600 while (loopflag)
                     zone = 0
                     write(*,1320)
                     format(/,5x,$,'Enter data for which Zone? (1 or 2):
1320
                     read(*,1330,err=1600)zone
1330
                     format(il)
                     if (zone .eq. 0) then
                      loopflag = .false.
                     else if ((zone .eq. 1) .or. (zone .eq. 2)) then
                   do 1500 ihand = 1.2
                   do 1400 k=1,regcnt(crewidx)
                      do 1395 j=1,contcnt(crewidx,k)
                         if ( ( (ihand .eg. 1) .and.
                            ( (conthand(crewidx,k,j) .eq. 'L' ) .or.
                            (conthand(crewidx,k,j) .eq. 'l' ) .or.
                            (conthand(crewidx,k,j) .eq. 'B') .or.
                            (conthand(crewidx,k,j) .eq. 'b' ) ) .or.
                              ((ihand .eq. 2) .and.
                            ( (conthand(crewidx,k,j) .eq. 'R' ) .or.
                                 279
```

```
(conthand(crewidx,k,j) .eq. 'r') .or.
     1
     1
                            (conthand(crewidx,k,j) .eq. 'B') .or.
                            (conthand(crewidx,k,j) .eq. 'b' ) ) ) then
     1
                   if (ihand .eq. 1) then
                      write(*,1360)crewname(crewst(crewidx)),zone
                      format(//,5x,'Crewstation: ',al0,' Zone: ',il,
1360
     1
                      ' Left Hand Data')
                   elseif (ihand .eq. 2) then
                      write(*,1365)crewname(crewst(crewidx)),zone
                      format(//,5x,'Crewstation: ',al0,' Zone: ',il,
1365
                      ' Right Hand Data')
                   endif
                         write(*,1370)contname(crewidx,k,j)
1370
                         format(5x,'Control: ',a60)
                         write(*,1375)regname(region(crewidx,k)),
                                  conttype(crewidx,k,j)
     1
                         format(5x,'Region: ',a30,' Control Type: ',al)
1375
                         write(*,1380)
1379
                         format(/,5x,$,'Measured Reach: ')
1380
                         read(*,1385,err=1379)contdata(crewidx,k,j,zone
                         format(f10.0)
1385
                         write(21,1390)crewin(crewidx),region(crewidx,k
                         contnum(crewidx,k,j),contname(crewidx,k,j),zon
     1
                         ihand, contdata(crewidx, k, j, zone, ihand)
     1
                         format(2x,i2,2x,i2,2x,i3,2x,a60,/,
1390
                              3x,i1,2x,i1,2x,f10.3
     1
                      endif
1395
                      end do
1400
                 end do
                end do
1500
                endif
1600
                end do
                            !if sbjflag and okflag
                endif
              end do !if sbjflag
          write(21,1900)
1900
          format(2x,'-1',2x,'-1',2x,'-1')
```

CINPUT AIRCRAFT DATA FILE

```
ANAME
               T-38A
CATEGORY
                T
CREWCNT
                 2
 CREWSTATION
                  3
  SEATCNT
                  2
   SEATADJ
                   V
    SEATTYPE
    SEATINC
                      0.1
    SEATRANGE
                      4.8
   SEATADJ
                   V
    SEATTYPE
                    C
    SEATINC
                      0.1
    SEATRANGE
                      4.8
  REGCNT
                   8
   REGNUM
                    1
    CONTCNT
                      1
     CONTNAME
                     THROTTLE - FWD
      CONTTYPE
                      H
      CONTHAND
                      L
   REGNUM
    CONTCNT
                      6
     CONTNAME
                     FUEL - SHUTOFF - SWITCH - LEFT
      CONTTYPE
                      F
      CONTHAND
                      L
     CONTNAME
                     ENGINE - START - BUTTON - LEFT
      CONTTYPE
                      F
      CONTHAND
                      L
     CONTNAME
                     LANDING-GEAR-ALT-REL-HANDLE
      CONTTYPE
                      Н
      CONTHAND
                      L
     CONTNAME
                     RADIO-TRANSFER-SWITCH-NAV
      CONTTYPE
      CONTHAND
                      L
     CONTNAME
                     INTERCOMM - SWITCH - ILS
      CONTTYPE
                      T
      CONTHAND
                      L
     CONTNAME
                     PITOT-HEAT-SWITCH
      CONTTYPE
                      F
      CONTHAND
                      В
  REGNUM
                    3
   CONTCNT
     CONTNAME
                     LANDING-GEAR-LEVER
      CONTTYPE
                     F
      CONTHAND
                     L
     CONTNAME
                    DOWNLOCK-OVERRIDE-BUTTON
      CONTTYPE
                     F
      CONTHAND
                     L
    CONTNAME
                    AIRSPEED/MACH-INDICATOR
      CONTTYPE
                     T
      CONTHAND
    CONTNAME
                    STEERING - MODE - SWITCH - NORM
      CONTTYPE
                     F
      CONTHAND
                     L
    CONTNAME
                    HSI-HEADING-SET-KNOB
     CONTTYPE
                     T
                                  283
```

```
В
   CONTHAND
                  HSI - COURSE - SET - KNOB
  CONTNAME
   CONTTYPE
                   В
   CONTHAND
                  MASTER-CAUTION
  CONTNAME
                   F
   CONTTYPE
   CONTHAND
                   В
REGNUM
 CONTCNT
                  UHF - COMMAND - RADIO - CONTROL - MAIN
  CONTNAME
   CONTTYPE
                   В
   CONTHAND
                   TACAN - CONTROL - CHANNEL - KNOB
  CONTNAME
   CONTTYPE
                   В
   CONTHAND
                  RUDDER - PEDAL - ADJUST - T - HANDLE
  CONTNAME
                   Н
   CONTTYPE
   CONTHAND
                   В
                  CIRCUIT-BREAKER-LWR-CTR
  CONTNAME
   CONTTYPE
                    Т
   CONTHAND
                    В
                 5
REGNUM
 CONTCNT
                  FUEL - OXYGEN - CHECK - SWITCH
  CONTNAME
   CONTTYPE
                   Н
   CONTHAND
                   R
  CONTNAME
                  CANOPY - JETTISON - T - HANDLE
   CONTTYPE
                   Н
                   R
   CONTHAND
                  GENERATOR - SWITCH - LEFT
  CONTNAME
   CONTTYPE
                    F
                    R
   CONTHAND
REGNUM
                 6
                    3
 CONTCNT
                  OXYGEN - SUPPLY - SWITCH - EMERGENCY
  CONTNAME
                    F
   CONTTYPE
   CONTHAND
                   R
  CONTNAME
                  IFF-CONTROL-MASTER-KNOB
   CONTTYPE
   CONTHAND
                    R
                  LIGHTING - CONTROL - EXTERIOR
  CONTNAME
                    F
   CONTTYPE
   CONTHAND
                   R
                11
REGNUM
 CONTCNT
                  CONTROL - STICK - NEUTRAL
  CONTNAME
   CONTTYPE
                   R
   CONTHAND
                  CONTROL - STICK - FULL - FWD - LEFT
  CONTNAME
   CONTTYPE
                   G
                   R
   CONTHAND
                12
REGNUM
 CONTCNT
                    3
                  SEAT - ADJUST - SWITCH
  CONTNAME
   CONTTYPE
                               284
```

```
R
     CONTHAND
                     INERTIA - REEL - LOCK - LEVER
    CONTNAME
     CONTTYPE
                     T
     CONTHAND
                     L
    CONTNAME
                    EJECTION-HAND-GRIPS
     CONTTYPE
                     G
     CONTHAND
                     В
CREWSTATION
                 4
                 1
 SEATCNT
  SEATADJ
                  V
                   C
   SEATTYPE
                      0.1
   SEATINC
                      4.3
   SEATRANGE
                  8
 REGCNT
  REGNUM
                   1
   CONTCNT
                      1
                    THROTTLE - FWD
    CONTNAME
     CONTTYPE
                     Н
     CONTHAND
                     L
  REGNUM
   CONTCNT
                    ENGINE - START - BUTTON - LEFT
    CONTNAME
     CONTTYPE
                     F
     CONTHAND
                     L
    CONTNAME
                    INTERCOMM - SWITCH - ILS
     CONTTYPE
                     T
     CONTHAND
                     L
                   3
  REGNUM
   CONTCNT
                     6
    CONTNAME
                    LANDING-GEAR-LEVER
     CONTTYPE
                     F
     CONTHAND
                     L
                    DOWNLOCK - OVERRIDE - BUTTON
    CONTNAME
     CONTTYPE
                     F
     CONTHAND
                     L
    CONTNAME
                    AIRSPEED/MACH-INDICATOR
     CONTTYPE
     CONTHAND
                     T.
    CONTNAME
                    HSI-HEADING-SET-KNOB
     CONTTYPE
                     T
     CONTHAND
                     В
    CONTNAME
                    HSI - COURSE - SET - KNOB
     CONTTYPE
                     Т
     CONTHAND
                     В
    CONTNAME
                    MASTER-CAUTION
     CONTTYPE
                     F
     CONTHAND
                     В
                   4
  REGNUM
                      3
   CONTCNT
    CONTNAME
                    UHF - COMMAND - RADIO - CONTROL - MAIN
     CONTTYPE
                    · T
     CONTHAND
                     В
                    TACAN - CONTROL - CHANNEL - KNOB
    CONTNAME
     CONTTYPE
                     Т
     CONTHAND
                     В
                                 285
```

```
RUDDER - PEDAL - ADJ - T - HANDLE
  CONTNAME
   CONTTYPE
                  Н
   CONTHAND
                  В
                5
REGNUM
 CONTCNT
                  0
REGNUM
                6
 CONTCNT
                 OXYGEN - SUPPLY - SWITCH - EMERGENCY
  CONTNAME
   CONTTYPE
                  F
   CONTHAND
                  R
                 LIGHTING - CONTROL - COCKPIT - FLOODS
  CONTNAME
                  F
   CONTTYPE
   CONTHAND
                  R
               11
REGNUM
 CONTCNT
  CONTNAME
                 CONTROL-STICK-NEUTRAL
   CONTTYPE
                  G
   CONTHAND
                 CONTROL-STICK-FULL-FWD-LEFT
  CONTNAME
   CONTTYPE
                  C
                  R
   CONTHAND
REGNUM
               12
                   3
 CONTCNT
                 SEAT-ADJUST-SWITCH
  CONTNAME
   CONTTYPE
                  R
   CONTHAND
                 INERTIA-REEL-LOCKING-LEVER
  CONTNAME
   CONTTYPE
   CONTHAND
                  L
  CONTNAME
                 EJECTION-HAND-GRIPS
   CONTTYPE
                  G
   CONTHAND
                  В
```

CINPUT SUBJECT DATA FILE

```
T-38A
 ANAME
   l WARD
                                                               22.500
                                                    22.300
     62.500 116.000 32.700 29.100
         13.000
.000
                                                    4.750
                                        6.250
                 2.560
                             7.060
     28.000
                                                    5.190
                 3.125
                             7.500
                                       6.750
     26.800
           1 THROTTLE-FWD
     1
            9.250
  1
           2 FUEL-SHUTOFF-SWITCH-LEFT
  3
           15.000
  1
           3 ENGINE-START-BUTTON-LEFT
   3
     2
  1
     1
          4 LANDING-GEAR-ALT-REL-HANDLE
   3
  1
     1
           11.500
          5 RADIO-TRANSFER-SWITCH-NAV
   3
           12.500
   1
     1
          6 INTERCOMM-SWITCH-ILS
   3
           12.500
   1
     1
      2
           7 PITOT-HEAT-SWITCH
   3
           14.750
   Ì
     1
          8 LANDING-GEAR-LEVER
   3
      3
   1
     1
             9.875
          9 DOWNLOCK - OVERRIDE - BUTTON
      3
            11.500
   1
          10 AIRSPEED/MACH-INDICATOR
   3
      3
            11.375
   1
     1
          11 STEERING-MODE-SWITCH-NORM
   3
      3
            10.875
      1
      3
          12 HSI-HEADING-SET-KNOB
   3
            10.750
   1
     1
          13 HSI-COURSE-SET-KNOB
   3
      3
           11.000
     1
           14 MASTER-CAUTION
      3
   3
           13.500
   1
      1
          15 UHF-COMMAND-RADIO-CONTROL-MAIN
   3
            12.750
      1
   1
          16 TACAN - CONTROL - CHANNEL - KNOB
   3
           13.625
   1
           17 RUDDER-PEDAL-ADJUST-T-HANDLE
   3
      4
            15.000
      1
          18 CIRCUIT-BREAKER-LWR-CTR
   3
      4
      1
            17.000
   1
           28 INERTIA-REEL-LOCK-LEVER
   3
      12
   1
      1
             8.875
           29 EJECTION-HAND-GRIPS
   3
      12
   1
      1
             0.000
      2
           7 PITOT-HEAT-SWITCH
   3
           13.250
           12 HSI-HEADING-SET-KNOB
   3
       3
            13.250
   3
      3
           13 HSI-COURSE-SET-KNOB
            12.500
   1
          14 MASTER-CAUTION
      3
            13.500
```

15 UHF-COMMAND-RADIO-CONTROL-MAIN

```
2
         14.750
1
3
        16 TACAN - CONTROL - CHANNEL - KNOB
1
   2
           4.500
        17 RUDDER-PEDAL-ADJUST-T-HANDLE
3
   4
          16.000
1
   2
3
    4
        18 CIRCUIT-BREAKER-LWR-CTR
   2
          18.125
1
3
   5
        19 FUEL - OXYGEN - CHECK - SWITCH
          15.125
1
    5
        20 CANOPY-JETTISON-T-HANDLE
3
          14.125
1
        21 GENERATOR-SWITCH-LEFT
    5
3
          15.750
1
        22 OXYGEN-SUPPLY-SWITCH-EMERGENCY
3
    6
1
          14.375
3
        23 IFF-CONTROL-MASTER-KNOB
    6
          11.875
1
        24 LIGHTING-CONTROL-EXTERIOR
3
   6
           5.750
1
   2
3
  11
        25 CONTROL-STICK-NEUTRAL
           3.625
1
   2
3
   11
        26 CONTROL-STICK-FULL-FWD-LEFT
1
          10.875
   2
        27 SEAT-ADJUST-SWITCH
3
   12
1
          12.000
3
   12
        29 EJECTION-HAND-GRIPS
   2
           0.000
         1 THROTTLE-FWD
3
   1
2
           6.750
   1
         2 FUEL-SHUTOFF-SWITCH-LEFT
3
    2
2
   1
         11.750
         3 ENGINE-START-BUTTON-LEFT
3
2
          11.625
   1
         4 LANDING-GEAR-ALT-REL-HANDLE
3
    2
2
           8.000
   1
         5 RADIO-TRANSFER-SWITCH-NAV
3
    2
           8.875
2
         6 INTERCOMM-SWITCH-ILS
3
    2
2
           8.625
   1
         7 PITOT-HEAT-SWITCH
3
    2
2
   1
           9.750
    3
         8 LANDING-GEAR-LEVER
3
           6.000
2
   1
         9 DOWNLOCK-OVERRIDE-BUTTON
3
    3
2
           7.500
   1
        10 AIRSPEED/MACH-INDICATOR
3
    3
2
           7.125
3
    3
        11 STEERING-MODE-SWITCH-NORM
2
           6.875
        12 HSI-HEADING-SET-KNOB
3
    3
2
           6.875
   1
        13 HSI-COURSE-SET-KNOB
3
   3
2
   1
           7.250
3
    3
        14 MASTER-CAUTION
           9.500
2
   1
                               289
```

```
3
    4
         15 UHF-COMMAND-RADIO-CONTROL-MAIN
            9.125
 2
    1
 3
     4
         16 TACAN - CONTROL - CHANNEL - KNOB
 2
           10,000
    1
 3
     4
         17 RUDDER - PEDAL - ADJUST - T - HANDLE
 2
   1
           11.000
 3
         18 CIRCUIT-BREAKER-LWR-CTR
     4
 2
    1
           13.250
 3
   12
         28 INERTIA-REEL-LOCK-LEVER
 2
    1
            7.625
         29 EJECTION-HAND-GRIPS
 3
   12
 2
            0.000
    1
 3
          7 PITOT-HEAT-SWITCH
     2
 2
    2
           10.375
 3
     3
         12 HSI-HEADING-SET-KNOB
 2
    2
           10.625
         13 HSI-COURSE-SET-KNOB
 3
    3
 2
           10.125
    2
 3
     3
         14 MASTER-CAUTION
 2
           10.875
    2
         15 UHF-COMMAND-RADIO-CONTROL-MAIN
 3
    4
 2
           12.500
    2
         16 TACAN - CONTROL - CHANNEL - KNOB
 3
     Ą
 2
           12.375
    2
 3
     4
         17 RUDDER - PEDAL - ADJUST - T - HANDLE
 2
           13.500
 3
         18 CIRCUIT-BREAKER-LWR-CTR
     4
 2
           15.500
 3
     5
         19 FUEL - OXYGEN - CHECK - SWITCH
           11.250
 2
    2
 3
    5
         20 CANOPY-JETTISON-T-HANDLE
 2
           10.750
    2
         21 GENERATOR - SWITCH - LEFT
 3
 2
    2
           12.375
         22 OXYGEN - SUPPLY - SWITCH - EMERGENCY
 3
    6
 2
           11.000
 3
         23 IFF-CONTROL-MASTER-KNOB
     6
            9.750
 2
    2
 3
         24 LIGHTING-CONTROL-EXTERIOR
     6
 2
            0.000
         25 CONTROL-STICK-NEUTRAL
 3
   11
 2
            1.375
    2
 3
         26 CONTROL-STICK-FULL-FWD-LEFT
   11
 2
    2
            9.000
         27 SEAT-ADJUST-SWITCH
 3
   12
            9.000
2
   2
         29 EJECTION-HAND-GRIPS
3
   12
            0.000
- 1
   -1 -1
```

SAMPLE CINPUT AIRCRAFT SCRIPT

#### Falcon> RUN CINPUT

```
Data will be accepted in upper or lower case
What type of data would you like to enter?
Enter "A" for aircraft data or "S" for subject data: A
Aircraft Name: T-38A
Aircraft category:
F(ighter), C(argo), T(rainer): T
Enter Crewstation, <cr>> when done
F(orward), A(ft), L(eft), R(ight): F
CREWSTATION SELECTED: FORWARD
Is this control region applicable? Y(es) or N(o)
LEFT-SIDE-PANEL
LEFT-AUXILIARY-PANEL
                              : Y
                              : Y
MAIN-INSTRUMENT-PANEL
                              : Y
CENTER-PEDESTAL
RIGHT-AUXILIARY-PANEL
                               : Y
RIGHT-SIDE-PANEL
OVERHEAD-CONTROL-PANEL
                              : N
LEFT-BULKHEAD
RIGHT-BULKHEAD
                              : N
GLARE-SHIELD
                              : Y
CONTROL-STICK
SEAT
Seat Adjustment Data
Each Direction will be Processed Separately
V(ertical), H(orizontal), T(ilt Seat): V
SEAT DIRECTION: VERTICAL
Select Type of Adjustment for this Direction:
C(ontinuous) or N(otched): C
Enter Increment for One Seat Adjustment: .1
Enter Seat Travel in inches from Full-up to Full-down: 4.8
Seat Adjustment Data
Each Direction will be Processed Separately
V(ertical), H(orizontal), T(ilt Seat):
```

Enter Crewstation, <cr>> when done

#### Enter control data for:

CREWSTATION: FORWARD REGION: LEFT-SIDE-PANEL

Control Names are 60 chars max, use dashes as delimiters

Control Name: THROTTLE-FWD

G(rip), F(inger), H(ook), T(humb): H

R(ight), L(eft), B(oth): L

CREWSTATION: FORWARD REGION: LEFT-SIDE-PANEL

Control Names are 60 chars max, use dashes as delimiters

Control Name:

Enter control data for:

CREWSTATION: FORWARD REGION: LEFT-AUXILIARY-PANEL Control Names are 60 chars max, use dashes as delimiters

Control Name: FUEL-SHUTOFF-SWITCH-LEFT

G(rip), F(inger), H(ook), T(humb): F

R(ight), L(eft), B(oth): L

CREWSTATION: FORWARD REGION: LEFT-AUXILIARY-PANEL Control Names are 60 chars max, use dashes as delimiters

Control Name: ENGINE-START-BUTTON-LEFT

G(rip), F(inger), H(ook), T(humb): F

R(ight), L(eft), B(oth): L

CREWSTATION: FORWARD REGION: LEFT-AUXILIARY-PANEL Control Names are 60 chars max, use dashes as delimiters

Control Name:

Enter control data for:

CREWSTATION: FORWARD REGION: MAIN-INSTRUMENT-PANEL Control Names are 60 chars max, use dashes as delimiters

Control Name: LANDING-GEAR-LEVER

G(rip), F(inger), H(ook), T(humb): F

R(ight), L(eft), B(oth): L

CREWSTATION: FORWARD REGION: MAIN-INSTRUMENT-PANEL Control Names are 60 chars max, use dashes as delimiters

Control Name:

Enter control data for:

CREWSTATION: FORWARD REGION: CENTER-PEDESTAL Control Names are 60 chars max, use dashes as delimiters

Control Name: UHF-COMMAND-RADIO-CONTROL-MAIN

G(rip), F(inger), H(ook), T(humb): T

R(ight), L(eft), B(oth): B

CREWSTATION: FORWARD REGION: CENTER-PEDESTAL Control Names are 60 chars max, use dashes as delimiters

Control Name:

Enter control data for:

CREWSTATION: FORWARD REGION: RIGHT-AUXILIARY-PANEL Control Names are 60 chars max, use dashes as delimiters

Control Name: FUEL-OXYGEN-CHECK-SWITCH

G(rip), F(inger), H(ook), T(humb): H

R(ight), L(eft), B(oth): R

CREWSTATION: FORWARD REGION: RIGHT-AUXILIARY-PANEL Control Names are 60 chars max, use dashes as delimiters

Control Name: CANOPY-JETTISON-T-HANDLE

G(rip), F(inger), H(ook), T(humb): H

R(ight), L(eft), B(oth): R

CREWSTATION: FORWARD REGION: RIGHT-AUXILIARY-PANEL Control Names are 60 chars max, use dashes as delimiters

Control Name:

Enter control data for:

CREWSTATION: FORWARD REGION: RIGHT-SIDE-PANEL Control Names are 60 chars max, use dashes as delimiters

Control Name: OXYGEN-SUPPLY-SWITCH-EMERGENCY

G(rip), F(inger), H(ook), T(humb): F

R(ight), L(eft), B(oth): R

CREWSTATION: FORWARD REGION: RIGHT-SIDE-PANEL Control Names are 60 chars max, use dashes as delimiters

Control Name:

Enter control data for:

CREWSTATION: FORWARD REGION: CONTROL-STICK Control Names are 60 chars max, use dashes as delimiters

Control Name: CONTROL-STICK-NEUTRAL

G(rip), F(inger), H(ook), T(humb): G

R(ight), L(eft), B(oth): R

CREWSTATION: FORWARD REGION: CONTROL-STICK Control Names are 60 chars max, use dashes as delimiters

Control Name: CONTROL-STICK-FULL-FWD-LEFT

G(rip), F(inger), H(ook), T(humb): G

R(ight), L(eft), B(oth): R

CREWSTATION: FORWARD REGION: CONTROL-STICK

Control Names are 60 chars max, use dashes as delimiters

Control Name:

Enter control data for:

CREWSTATION: FORWARD REGION: SEAT

Control Names are 60 chars max, use dashes as delimiters

Control Name: SEAT-ADJUST-SWITCH

G(rip), F(inger), H(ook), T(humb): F

R(ight), L(eft), B(oth): R

CREWSTATION: FORWARD REGION: SEAT

Control Names are 60 chars max, use dashes as delimiters

Control Name:

***Exiting Cockpit Input Program***

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### APPENDIX H

VALIDATING COMPUTERIZED HUMAN ANALOGUES USED TO PREDICT COCKPIT ACCOMMODATION

## VALIDATING COMPUTERIZED HUMAN ANALOGUES USED TO PREDICT COCKPIT ACCOMMODATION

To evaluate the ability of computer models to predict accommodation of the human operator in a crew or work station, it is necessary to utilize empirical data as a baseline against which the model can be validated. This report contains data which can be used for this purpose. The validation data used here were not gathered specifically for testing computer models, but to directly examine body size accommodation in aircraft, using human subjects, to develop a computerized aircraft accommodation database. If the computer model is intended to be a cockpit design and evaluation tool, comparisons between its predictions of cockpit accommodation, raw data taken from subjects, and smoothed data from the accommodation database should provide the basis for validating the accuracy of the computer model.

several types of accommodation data are included in this report: actual subject data measured in an F-16A, data predicted from regression equations and average values from the F-16 study, and data derived using the COMBIMAN computer method. The regression and average values were taken from the Cockpit Accommodation Database.

The COMBIMAN can be assessed by entering the anthropometric data obtained from the test subjects used in the empirical study and comparing the computer model predictions to both the subjects' raw data, and the "smoothed data" that the database generates via regression analysis. It will be noticed that the raw data and regression data are somewhat different. The computer model can yield yet a third set of values. The extent to which the model data compare with the database data is a measure of how well the model represents the operator.

Measurements of body size accommodation in cockpits can be quite variable for subjects of similar size and sometimes difficult to repeat accurately on the same subject. There are a number of reasons for this, including variability in posture, restraint harness location or fit, protective equipment fit and effect on body mobility, and others. For these reasons, it is imperative that differences in results be looked at generally, and not examined down to a few tenths of an inch, or one or two degrees of visual angle.

In gathering the data in the cockpit, a number of assumptions concerning body posture must be made which will need to be mimicked by the computer model. We do not claim that these postures are typically assumed by pilots. An example is the frequent requirement that the subject hold his/her head in the Frankfort Plane. They are attempts to bring repeatability into this highly variable environment.

Data are included which describe reach to controls (with the inertial reels locked), vision out of the aircraft, ability to achieve full rudder throw, overhead clearance, and operational and ejection knee and leg clearance with the instrument panel and glareshield. Data were gathered on each of 10 small subjects and 5 large subjects. Their anthropometric measurements are listed in Tables 1 and 2. Anthropometric descriptions are given in Appendix A. Small subjects were used to obtain data on hand reach to controls, rudder pedal actuation, and vision out of the cockpit. Large subjects were used to obtain data on overhead clearance when the seat is full down and operational and ejection leg and knee clearances,

Accommodation data based on multivariate models are included in Appendix B. These models were developed to guide the anthropometric input into COMBIMAN.

TABLE 1

F-16A Anthropometric Data: F-16A Accommodation Subject Panel - Small Subjects (Weight in 1bs; all other values in inches)

26.8 26.8 28.9* 20.5 11.6 13.3 8.4 8.5 6.2 33.6 21.1 18.6 114 32.9 19.9 19.2 21.9 12.3 14.2 8.2 9.1 6.3 27.9 27.7 28.9 120 22.3 12.0 14.2 13.0 7.3 8.7 6.3 26.9 27.4 29.4 33.7 21.9 19.6 107 23.0 13.6 15.8 10.1 9.9 7.0 167 35.0 23.3 20.7 30.0 30.6 30.7 35.0 23.5 19.7 136* 23.1 30.4 30.4 31.0 1 1 1 1 1 ဖ Ø H 29.0 29.0 29.9 34.1 22.3 20.0 22.5 13.6 14.3 15.0 8.6 9.9 6.8 U ខា M b 117 33.5 21.6 18.7 21.5 12.4 13.3 9.2 6.1 26.4 26.3 29.1 Ø Þ 27.4 27.5 29.6 W 127* 33.6 22.1 19.3 m 28.2 28.3 30.1 34.4 22.2 19.4 22.0 132* ŧ 8.7 9.1 6.8 10.1 124 33.9 22.1 19.2 21.9 12.4 14.9 14.8 29.2 27.8 29.6 SHOULDER HT., SITTING HIP BREADTH, SITTING KNEE HEIGHT, SITTING SHOULDER-ELBOW LGTH THUMB-TIP REACH (E)
THUMB-TIP REACH (R)
EYE HEIGHT, SITTING BUTTOCK-KNEE LENGTH BIACROMIAL BREADTH ELBOW-WRIST LENGTH SITTING HEIGHT CHEST DEPTH FOOT LENGTH HAND LENGTH WEIGHT

⁶ were not available for complete measurement. 3, and * Values derived using regression equations. Subjects 2,

TABLE 2

F-16A Accommodation Subject Panel - Anthropometric Data - Large Subjects (Weight in lbs; all other values in inches)

		. ~	က	4	Ŋ
WEIGHT	167	210	192	255	190
SITTING HEIGHT	37.9	39.4	38.7	41.0	37.1
ACROMION HT., SITTING	24.9	26.0	25.5	27.2	24.3
KNEE HEIGHT, SITTING	23.8	24.6*	23.3	25.3	21.5
BUTTOCK-KNEE LENGTH	26.7	27.4	25.8	27.0	24.5
SHOULDER-ELBOW LGTH*	15.4	15.7	15.0	15.6	14.4
BIACROMIAL BREADTH*	16.3	16.6	16.5	16.9	16.1
HIP BREADTH, SITTING*	15.0	15.3	14.6	15.1	14.2
CHEST DEPTH*	10.5	10.7	10.2	10.6	6.6
FOOT LENGTH*	11.3	11.5	11.1	11.8	10.5
HAND LENGTH*	8.0	8.1	7.8	8.1	7.6
ELBOW-WRIST LENGTH*	12.6	13.0	12.4	13.3	11.6
THUMB-TIP REACH*	34.2	34.8	33.4	31.8	32.3
EYE HEIGHT, SITTING	33.2	34.6	34.1	35.7*	32.2*

* Values derived from regression equations. Weight is reported in pounds: Other dimensions in inches.

Tables 3 through 9 list measures of accommodation in the cockpit of the F-16A. Raw data taken from subjects as well as the smoothed data from the database are represented. Subjects wore representative flight gear, including flight suits, boots, G-suit, survival vest, and parachute harness. Helmets and oxygen masks were not worn. Blanks are reserved for the inclusion of COMBIMAN data.

Measurements describing visual angles achieved by subjects looking (1) over the nose with the head in the Frankfort plane, (2) over the nose with the head and neck stretched upward and aft, and (3) over the side at the intersection of the glareshield and canopy are listed in Table 3. These data were used in regression equations to determine the vision algorithms for the Cockpit Accommodation Database. The database predictions for these visual angles are also listed in Table 3.

Table 4 lists measurements made to the farthest forward rudder carriage position that subjects could reach while keeping their heels on the rudder bar and applying full rudder and brake. The subjects' restraint harnesses were snugged down and their hips were not permitted to rotate in order to obtain greater leg reach. These measurements were used to determine the shortest leg length possible for operating the rudders in this fashion. For the F-16A (with the seat adjusted full up) that value is 38.4 inches (Buttock-Knee Length + Knee Height Sitting). In the F-16A, a subject with a one-inch-longer leg would not necessarily adjust the rudder carriage one inch further forward. In some aircraft this is true, but in the F-16A, the seat pan is angled rather sharply upward relative to the deck and the knee cannot be fully extended while the foot is on the rudder. Therefore, the database predicted values merely state how much additional leg length the subject has - not the subject's rudder carriage adjust position.

Subjects' reach miss distances to selected controls are listed in Tables 5 and 6. These measurements are taken by locking the subject's restraint system, snugging it down, and then having the subject reach toward a control. significant fore or aft movement of the shoulders is permitted. A single number is given for the calculation of Zone 2 values. This represents the average amount of "stretch" that the restraint harness will allow when reaching into the various areas of the instrument panels. The values were arrived at by averaging the differences between Zone 1 and 2 values across all subjects for limited regions of the instrument panels. For example, the Fire/Overheat Detect control is on the aft portion of the Left Side Console. To reach it the pilot reaches Only an additional 2.2 inches can be gained by stretching in this downward. direction. On the other hand, to reach the Master Caution, which is on the glareshield forward of the left shoulder, 4.3 inches of additional reach can be obtained for Zone 2. Again, database values listed on the table are derived from regression equations and are "smoothed" predictions of reach capability for a person of that size.

Clearance between the helmet and the underside of the canopy in the F-16A is presented in Table 7. Data are obtained by measuring the distance between the top of the bare head and the underside of the canopy with the seat either full up or raised until the head touches the canopy. Maximum Sitting Height accommodated is calculated by adding the subject's Sitting Height, the amount of remaining downward seat adjustment and the space above the head. One and one half inches has been allowed for the additional height due to the helmet. No allowance has been made for free space above the helmet.

TABLE 3

			F-16A	Vision	F-16A Vision from the Cockpit - in Degrees - Seat Full UP	cockpit	- in	Degrees	- Seat	rull Up	
SUBJECTS	-	7	ო	4	ហ	9	7	<b>&amp;</b>	6	AVERAGES	
EYE HT SIT	29.6	30.1		29.6 29.1	29.9	31.0	30.7	29.4	28.9	29.8	
SUBJECT DATA											
FrPl 0'Nose	-13	-13	-12	-11	-15	*	-16	-12	-12	-13	
Head Up/Aft	-14	-15	-13	-15	-17	*	-19	-15	-13	-15	
Over Side	-26	-24	-25	-25	-26	*	-28	-25	-22	-26	
DATABASE DATA											
FrPl 0'Nose	-13	-14	-13	-11	-14	-17	-16	-12	-11	-13	
Head Up/Aft	-15	-16	-15	-13	-16	-19	-18	-14	-13	-15	

COMBIMAN DATA

-25

-23

-24

-28

-29

-26

-23

-25

-26

over Side

FrPl 0'Nose

Head Up/Aft

Over Side

* Data that, for various reasons, was not measured or provided.

TABLE 4

	F-16A	F-16A Rudder	Pedal	Access - Rudder	Inches Pedals	of in	ess L 1 Aft	Excess Leg Length Full Aft Carrigae	ogth Be	Beyond that Position	: Needed	Beyond that Needed to Actuate Position
SUBJECTS	-	8	m	4	R	9		7	<b>&amp;</b>	6	10	AVERAGES
BUTT KNEE L. KNEE HT, SIT COMBINED LEG	EL. 21.9 SIT 19.2 LEG 41.1	9 22.0 2 19.4 1 41.4	22.0 19.3 41.3	21.5 18.7 40.2	22.5	23.1 19.7 42.8		23.0 20.7 43.7	22.3 19.6 41.9	21.9 19.2 41.1	20.5 18.6 39.1	22.1 19.4 41.5
SEAT FULL UP												
SUBJECT RUDDER CARRIAGE ADJ. POSITION	1.50 :ON	2.50	2.50	0.75	1.75	2.75		2.50	1.00	1.63	-0.25	1.66
DATABASE EXCESS LEG LENGTH	2.70	3.00	2.90	1.80	4.10	4.40		5.30	3.50	2.70	0.70	3.11
COMBIMAN EXCESS LEG LENGTH												
SEAT FULL DOWN												
SUBJECT RUDDER CARRIAGE ADJ, POSITION	5.75 ON	ı	6.75	5.75	6.63	7.25		6.75	5.00	5.88	3.25	5.89
DATABASE EXCESS LEG LENGTH	7.00	7.30	7.20	6.10	8.40	8.70		. 09.6	7.80	7.00	2.00	7.40

COMBIMAN EXCESS LEG LENGTH

^{*} Subject's anthropometric data can be found in Table 1.

TABLE 5 F-16A Left Hand Reaches, Zones 1 and 2 - Individual Subject, Accommodation Database and COMBIMAN

ALL SUBJECTS WERE IN THE FULL-UP SEAT ADJUSTMENT ANTHROPOMETRIC DATA ARE REPORTED IN TABLE 1.

								_	
SUBJECTS		9	10	4	8	1	5	7	
SHLDR HT, S TH-T REACH	(T)	21.5	20.0	20.1	2017				
CONTROL &  * (HAND INTER			сн мі	ss I	) IST	ANCE	s (IN	INC	HES)
•									
1. FIRE/OVE	ERHEAT	DETECT							
SUBJECT DATA	ZONE 1 ZONE 2		-1.0	-2.7 (Add +2	-0.2 2.2 to a	-1.5 ll Zone	-0.2 1 values	2.0	-0.4
DATABASE	ZONE 1 ZONE 2	0.6 2.8	-1.2 1.0	-1.9 0.3	-1.6 0.6	0.5 2.7	-0.5 1.7	1.0 3.2	-0.4 1.8
COMBIMAN	ZONE 1 ZONE 2								
2. ANTI-G	TEST (F	. <del>7</del>							
SUBJECT DATA	ZONE 1 ZONE 2		0.5	-0.7 (Add	1.9 +2.2 to	0.4 all Zo	1.8 ne 1 valu	es)	0.9
DATABASE	ZONE 1		0.0 2.2	-0.7 1.5	-0.5 1.7	1.6 3.8	0.4 2.6	2.0 4.2	0.7 2.9
COMBIMAN	ZONE 2								
3. RUDDER	ARM (T)	<u>)</u>							
SUBJECT DATA	ZONE 2		0.1	-2.6 (Add	0.7 +2.2 to	-0.6 all Zon	-0.1 e 1 value	+	-0.3
DATABASE	ZONE		-0.7 1.5	-1.6 0.6	-1.3 0.9	0.7 2.9	-0.5 1.7	1.0 3.2	-0.1 2.1
COMBIMAN	ZONE :	_							

^{* +} VALUES INDICATE EXCESSIVE REACH (REACH CAPABILITY BEYOND CONTROL).

- VALUES INDICATE INSUFFICIENT REACH (REACH CAPABILITY SHORT OF CONTROL).

** HAND INTERFACE: The interface of the hand with the control: e.g., "F" for

Finger, "G" for Grip, "T" for Thumb/Forefinger, and "H" for Hook.

+ Controls too close to permit measurement. They, therefore, are easily reached.

#### F-16A Left Hand Reaches, Zones 1 and 2 - Individual Subject, Accommodation Database and COMBIMAN

			9	10	4	8	1	5	7	MEAN
SHLDR HT, TH-T REACH	SIT (L)		19.9 27.9	21.1 26.8	21.6 26.4	21.9 26.9	22.1 29.2	22.3 29.0	23.3 30.6	21.7 28.1
CONTROL & (HAND INTE			REAC	н м:	ISS	DIST	ANCES	(I N	INCH	ES)
4. VIDEO S	ELECT	(F	7							
SUBJECT DATA	ZONE ZONE		4.1	3.3		4.7 i +2.2 to	3.4 all Zone	++ 1 valu		3.6
DATABASE	zone zone			2.5 4.7			4.3 6.5	3.4 5.6		3.3 5.5
COMBINAN	ZONE ZONE									
5. AIR REF	UEL O	oen	/Close	<u>(F)</u>						
SUBJECT DATA	ZONE ZONE		2.0	1.9			2,9 all Zone			2.1
DATABASE	zone zone		2.8 5.0	1.2 3.4	0.6 2.8		3.2 5.4	2.5 4.7		2.2 4.4
COMBINAN	ZONE ZONE									
6. CANOPY	JETTI:	ON	<u>(T)</u>							
SUBJECT DATA	ZONE ZONE		++	++			+ o all Zon		-0.4 .ues)	-0.7
DATABASE	zone zone			-0.3 1.9	-1.3 0.9		0.8 3.0	-0.8 1.4		0.0 2.2
COMBIMAN	zone zone									

⁺ VALUES INDICATE EXCESSIVE REACH (REACH CAPABILITY BEYOND CONTROL).

⁻ VALUES INDICATE INSUFFICIENT REACH (REACH CAPABILITY SHORT OF CONTROL).

^{**} HAND INTERFACE: The interface of the hand with the control: e.g., "F" for Finger, "G" for Grip, "T" for Thumb/Forefinger, and "H" for Hook.

+ Controls too close to permit measurement. They, therefore, are easily reached.

⁺⁺ Data that, for various reasons, was not measured or provided.

F-16A Left Hand Reaches, Zones 1 and 2 - Individual Subject, Accommodation Database and COMBIMAN

ALL	SUBJECTS	WERE	IN	THE	FULL-UP	SEAT	ADJUSTMENT.

		9	10	4	8	1	5	7	MEAN
SHLDR HT, TH-T REACH	SIT (L)	19.9 27.9	21.1 26.8	21.6 26.4	21.9 26.9	22.1 29.2	22.3 29.0	23.3 30.6	21.7 28.1
CONTROL & (HAND INTE			H MI	ss D	ISTA	NCES	(I N	INCE	E S)*
7. PITCH T	RIM (F)	L							
Subject Data	ZONE 2		2.9			2.4 all Zone			2.8
DATABASE	ZONE 2	3.6 2 5.8	2.0 4.2	1.4 3.6		4.0 6.2			3.0 5.2
COMBINAN	ZONE 2								
8. MAIN PO	WER (BA	ATT) (T)							
SUBJECT DATA	ZONE 2		-0.3			0.4 all Zone			-0.0
DATABASE	ZONE 2					1.0 3.2			0.1 2.3
COMBIMAN	ZONE 1	-							
9. THROTTL	E Fwd (	<u>H)</u>							
SUBJECT DATA	ZONE 2		-2.9			-0.9 all Zone			-1.9
Database						-0.8 2.8			-1.8 1.8
COMBIMAN	ZONE 2	·							

^{* +} VALUES INDICATE EXCESSIVE REACH (REACH CAPABILITY BEYOND CONTROL).

⁻ VALUES INDICATE INSUFFICIENT REACH (REACH CAPABILITY SHORT OF CONTROL).
** HAND INTERFACE: The interface of the hand with the control: e.g., "F" for Finger, "G" for Grip, "T" for Thumb/Forefinger, and "H" for Hook.
+ Controls too close to permit measurement. They, therefore, are easily

reached.

⁺⁺ Data that, for various reasons, was not measured or provided.

#### F-16A Left Hand Reaches, Zones 1 and 2 - Individual Subject, Accommodation Database and COMBIMAN

			9	10	4	8	1	5	7	MEAN
SHLDR HT, TH-T REACH	SIT (L)		19.9 27.9	21.1 26.8	21.6 26.4	21.9 26.9	22.1 29.2	22.3 29.0	23.3 30.6	21.7 28.1
CONTROL & (HAND INTE	RFACE	] **	REAC	н мі	s s D	ISTA	NCES	(I N	INCH	E S)*
10. EEC of	f/Buc	(F	7							
	zone zone		-0.9	-1.5			0.4 all Zone			-0.7
DATABASE	zone zone	1 2	-0.3 3.3	-1.6 2.0	-2.1 1.5	-1.7 1.9	0.5 4.1	0.0 3.6	1.6 5.2	-0.5 3.1
COMBIMAN	ZONE ZONE									
11. UHF PR	ESET									
SUBJECT DATA	zone zone		-1.2	-0.9			0.0 all Zone			-0.7
DATABASE	zone zone	1 2	0.0 3.6	-1.5 2.1	-2.1 1.5	-1.7 1.9	0.4 4.0	-0.2 3.4	1.3 4.9	-0.5 3.1
COMBINAN	zone zone									
12. <u>JET FU</u>	EL STA	RT	#2 (T	Ĺ						
	zone zone	_	-3.2	-3.9			-2.6 all Zone			-3.3
DATABASE	ZONE ZONE	1 2	-2.5 1.1	-4.1 -0.5	-4.7 -1.1	-4.3 -0.7	-2.0 1.6	-2.7 0.9	-1.1 2.5	-3.1 0.5
COMBIMAN	ZONE ZONE	_								

⁺ VALUES INDICATE EXCESSIVE REACH (REACH CAPABILITY BEYOND CONTROL).

⁻ VALUES INDICATE ENCESSIVE REACH (REACH CAPABILITY SHORT OF CONTROL).

** HAND INTERFACE: The interface of the hand with the control: e.g., "F" for
Finger, "G" for Grip, "T" for Thumb/Forefinger, and "H" for Hook.

+ Controls too close to permit measurement. They, therefore, are easily

⁺⁺ Data that, for various reasons, was not measured or provided.

#### F-16A <u>Left</u> Hand Reaches, Zones 1 and 2 - Individual Subject, Accommodation Database and COMBIMAN

		9	10	4	8	1	5	7	MEAN
SHLDR HT, S TH-T REACH	SIT (L)	19.9 27.9	21.1 26.8	21.6 26.4	21.9 26.9	22.1 29.2	22.3 29.0	23.3 30.6	21.7 28.1
CONTROL & (HAND INTE			н мі	ss D	ISTA	NCES	(I N	INCH	E S)*
13. RADAR	L-BAR	(F)							
	ZONE	1 <b>-2.</b> 0	-3.0	-3.9 (Add	-2.8 +3.6 to	-1.0 all Zone	-1.2 1 value	-0.6 es)	-2.1
DATABASE	ZONE	1 -1.7 2 1.9	-3.1 0.5	-3.7 -0.1	-3.2 0.4	-1.0 2.6	-1.5 2.1	0.0 3.6	-2.0 1.6
COMBIMAN	ZONE	_						•	
14. MANUAL	PITCH	0VERRIDE	<u>(F)</u>						
SUBJECT DATA	ZONE	1 -3.3 2	-3.8	-4.5 (Add	-3.6 +3.6 to	-1.5 all Zone	-2.0 1 valu	-0.8 es)	-2.8
DATABASE	ZONE ZONE	1 -2.6 2 1.0	-3.9 -0.3	-4.4 -0.8	-4.0 -0.4	-1.7 1.9	-2.1 1.5	-0.5 3.1	-2.7 0.9
COMBINAN	zone zone								
15. STORAG	E CONF	IG CAT 1	(F)						
SUBJECT DATA	ZONE ZONE	1 -4.0	-4.7	-5.5 (Add	-4.3 +3.6 to	-1.7 all Zone	-2.5 1 valu	-1.1 es)	-3.4
DATABASE	zone zone	1 -3.4 2 0.2	-4.5 -0.9	-4.9 -1.3	-4.5 -0.9	-2.2 1.4	-2.4 1.2	-0.8 2.8	-3.2 0.4
COMBIMAN	ZONE ZONE	_							

^{* +} VALUES INDICATE EXCESSIVE REACH (REACH CAPABILITY BEYOND CONTROL).

⁻ VALUES INDICATE INSUFFICIENT REACH (REACH CAPABILITY SHORT OF CONTROL).

^{**} HAND INTERFACE: The interface of the hand with the control: e.g., "F" for Finger, "G" for Grip, "T" for Thumb/Forefinger, and "H" for Hook.

⁺ controls too close to permit measurement. They, therefore, are easily reached.

⁺⁺ Data that, for various reasons, was not measured or provided.

# F-16A <u>Left</u> Hand Reaches, Zones 1 and 2 - Individual Subject, Accommodation Database and COMBIMAN

		9	10	4	8	1	5	7	MEAN
SHLDR HT, TH-T REACE	SIT I (L)	19.9 27.9	21.1 26.8	21.6 26.4	21.9 26.9	22.1 29.2	22.3 29.0	23.3 30.6	21.7 28.1
CONTROL & (HAND INTE			н мі	ss D	ISTA	NCES	(I N	INCH	E S)*
16. DOWNLO	CK RELE	ASE (F)							
SUBJECT DATA	ZONE 1 ZONE 2		-4.6			-1.6 all Zone			-3.2
DATABASE	ZONE 1 ZONE 2	-3.6 0.0	-4.5 -0.9	-4.9 -1.3	-4.3 -0.7	-2.0 1.6	-2.1 1.5	-0.5 3.1	-3.1 0.5
COMBIMAN	ZONE 1 ZONE 2								
17. EMERGE	NCY STO	RES JETT	ISON (F)						
SUBJECT DATA	ZONE 1 ZONE 2	-5.8	-6.7			-3.2 all Zone			-4.9
DATABASE	ZONE 1 ZONE 2	-5.5 -1.9	-6.3 -2.7	-6.6 -3.0	-6.0 -2.4	-3.6 0.0	-3.5 0.1	-1.9 1.7	-4.8 -1.2
COMBIMAN	ZONE 1 ZONE 2								
18. <u>PITCH</u>	ALT HOLI	) (F)							
SUBJECT DATA	ZONE 1 ZONE 2	-5.7	-6.3			-2.9 all Zone			-4.9
DATABASE	ZONE 1 ZONE 2	-5.2 -1.6	-6.2 -2.6	-6.5 -2.9	-6.0 -2.4	-3.7 -0.1	-3.8 -0.2	-2.2 1.4	-4.8 -1.2
COMBIMAN	ZONE 1 ZONE 2	++	++	OK	OK	ok	ok	OK	

^{* +} VALUES INDICATE EXCESSIVE REACH (REACH CAPABILITY BEYOND CONTROL).

⁻ VALUES INDICATE INSUFFICIENT REACH (REACH CAPABILITY SHORT OF CONTROL). ** HAND INTERFACE: The interface of the hand with the control: e.g., "F" for Finger, "G" for Grip, "T" for Thumb/Forefinger, and "H" for Hook. Controls too close to permit measurement.

They, therefore, are easily reached.

⁺⁺ Data that, for various reasons, was not measured or provided.

# TABLE 5 (cont'd)

### F-16A Left Hand Reaches, Zones 1 and 2 - Individual Subject, Accommodation Database and COMBIMAN

ALL SUBJECTS WERE IN THE FULL-UP SEAT ADJUSTMENT.

		9	10	4	8	1	5	7	MEAN
SHLDR HT, TH-T REACH	SIT H (L)	19.9 27.9	21.1 26.8		21.9 26.9			23.3 30.6	
CONTROL & (HAND INTE			н мі	ss r	ISTA	NCES	(I N	INCE	ES)*
19. <u>IFF II</u>	DENT (F)								
SUBJECT DATA	ZONE 1 ZONE 2	-5.8	-7.0			-3.6 all Zone			-5.4
DATABASE	ZONE 1 ZONE 2	-5.7 -2.1	-6.7 -3.1	-7.0 -3.4	-6.5 -2.9	-4.2 -0.6	-4.3 -0.7	-2.7 0.9	-5.3 -1.7
COMBIMAN	ZONE 1 ZONE 2		OK	OK	OK	OK	OK	OK	
20. MASTER	CAUTIO	N (F)							
SUBJECT DATA	ZONE 1 ZONE 2	++	++			++ all Zone			-2.8
DATABASE	ZONE 1 ZONE 2					-1.7 2.6			-2.7 1.6

# 21. DIS/LTS (T)

ZONE 1

ZONE 2

++

COMBIMAN

SUBJECT DATA	ZONE 1 ZONE 2	-9.3	-9.8			-7.1 all Zone			-9.0
DATABASE	ZONE 1 ZONE 2	-8.1 -3.8	-9.8 -5.5	-10.4 -6.1	-10.0 -5.7	-7.8 -3.5	-8.5 -4.2	-6.9 -2.6	-8.9 -4.5
COMBIMAN	ZONE 1 ZONE 2	-2.2	-3.0	-3.0	-3.7	-2.0	-0.6	-1.5	-2.3

OK

OK

OK

OK

OK

OK

^{* +} VALUES INDICATE EXCESSIVE REACH (REACH CAPABILITY BEYOND CONTROL).

⁻ VALUES INDICATE INSUFFICIENT REACH (REACH CAPABILITY SHORT OF CONTROL). ** HAND INTERFACE: The interface of the hand with the control: e.g., "F" for Finger, "G" for Grip, "T" for Thumb/Forefinger, and "H" for Hook. + Controls too close to permit measurement. They, therefore, are easily

reached.

⁺⁺ Data that, for various reasons, was not measured or provided.

TABLE 5 (cont'd)

# F-16A Left Hand Reaches, Zones 1 and 2 - Individual Subject, Accommodation Database and COMBIMAN

		9	10	4	8	1	5	7	MEAN
SHLDR HT, TH-T REACH	SIT (L)	19.9 27.9	21.1 26.8	21.6 26.4	21.9 26.9	22.1 29.2	22.3 29.0	23.3 30.6	21.7 28.1
CONTROL & (HAND INTE	RFACE)	REA **	сн м	ISS I	ISTA	NCES	(I N	INCE	i E S)*
22. SELECT	JETTIS	SON (F)							
SUBJECT DATA	ZONE 2	1 <b>-9.</b> 0	-8.7	-9.9 (Add	-9.1 +4.3 to	-5.9 all Zone	-6.1 1 valu	-6.5 les)	-7.9
DATABASE	ZONE 2	1 -8.0 2 -3.7	-9.1 -4.8	-9.5 -5.2	-9.0 -4.7	-6.7 -2.4	-6.9 -2.6	-5.3 -1.0	-7.8 -3.5
COMBINAN	ZONE 2		-1.0	-1.0	-1.7	OK	OK	ok	
23. SHIFT	(MFD)	<u>(F)</u>							
SUBJECT DATA	ZONE 2	1 <b>-8.</b> 1	-8.3	-9.3	-8.3 (Add	-5.1 +4.3 to	-5.6 all Zor	-6.4 ne 1 valu	-7.3 es)
DATABASE	ZONE 2	1 -7.1 2 -2.8	-8.4 -4.1	-8.9 -4.6	-8.5 -4.2	-6.2 -1.9	-6.6 -2.3	-5.0 -0.7	-7.2 -2.9
COMBINAN	ZONE 2		-0.7	-0.7	-1.4	ok	OK	OK	
24. <u>HUD FI</u>	LTER (I	<u>c)</u>							
SUBJECT DATA	ZONE 1	-6.8	-5.9	-8.0 (Add	-6.1 +4.3 to	-3.5 all Zone	-3.6 1 valu	-4.9 les)	-5.5
DATABASE	ZONE 1 ZONE 2	-5.6 -1.3	-6.7 -2.4	-7.1 -2.8	-6.6 -2.3	-4.3 0.0	-4.5 -0.2	-2.9 1.4	-5.4 -1.1
COMBIMAN	ZONE 1 ZONE 2		OK	++	++	OK	OK	OK	

^{* +} VALUES INDICATE EXCESSIVE REACH (REACH CAPABILITY BEYOND CONTROL).

⁻ VALUES INDICATE INSUFFICIENT REACH (REACH CAPABILITY SHORT OF CONTROL).
** HAND INTERFACE: The interface of the hand with the control: e.g., "F" for Finger, "G" for Grip, "T" for Thumb/Forefinger, and "H" for Hook.

+ Controls too close to permit measurement. They, therefore, are easily

reached.

⁺⁺ Data that, for various reasons, was not measured or provided.

TABLE 5 (cont'd)

# F-16A <u>Left</u> Hand Reaches, Zones 1 and 2 - Individual Subject, Accommodation Database and COMBIMAN

		9	)	10	4	8	1	5	7	MEAN
SHLDR HT, S	SIT (L)	19 27	.9	21.1 26.8	21.6 26.4	21. 26.	9 22 9 29	.1 22 .2 29	.3 23.3 .0 30.6	21.7 28.1
CONTROL & (HAND INTE			A C	н мј	ss	DIS	TANC	ES (I	N INC	H E S)*
25. HUD MI	LS-DEP	R (T)	L							
SUBJECT DATA	ZONE ZONE		.4	<b>-7.</b> 0	-8.9 (A)	-7. dd +4.3	0 -4 to all	.8 -4 Zone 1	.7 -5.6 values)	-6.6
DATABASE	zone zone			-8.6 -4.3		-8. 5 -4.	3 -5 0 -1	.9 -5 .6 -1	.8 -4.2 .5 0.1	-7.1 -2.8
COMBIMAN	zone zone		)K	OK	OK	0	K (	OK .	ok <b>o</b> k	OK
26. <u>AIR SP</u>	EED/MA	CH IN	ID (T)	•						
SUBJECT DATA	zone zone		.0.2	-10.3	-11. (A	.8 -10 dd +4.3	.3 -7 to all	.3 -7 Zone 1	.7 -8.0 values)	-9.4
DATABASE	zone zone	1 -	.9.4 -5.1	-10.6 -6.3	-11 -6	.0 -10 .7 -6	).5 -8 5.2 -4	.3 -8 .0 -4	.6 -7.0 .3 -2.7	-9.3 -5.0
COMBINAN	zone zone	1 -	-3.6	-4.3	-4	.3 -5	5.2 -3	.6 -2	.1 -3.3	-3.8
27. TACAN	HEADIN	G (T)	L							
SUBJECT DATA	ZONE ZONE		3.4	-7.9				.1 -6 Zone 1		-7.7
DATABASE	zone zone			-8.8 -4.5			.9 -6. .6 -2.	7 -7 4 -3	7.3 -5.7 3.0 -1.4	-7.7 -3.4
COMBIMAN	ZONE ZONE	1 2 -2	2.7	-3.3	-3.	4 -4	.3 -2.	71	3 -2.5	-2.9

^{* +} VALUES INDICATE EXCESSIVE REACH (REACH CAPABILITY BEYOND CONTROL).

⁻ VALUES INDICATE INSUFFICIENT REACH (REACH CAPABILITY SHORT OF CONTROL).
** HAND INTERFACE: The interface of the hand with the control: e.g., "F" for

Finger, "G" for Grip, "T" for Thumb/Forefinger, and "H" for Hook.
+ Controls too close to permit measurement. They, therefore, are easily reached.

⁺⁺ Data that, for various reasons, was not measured or provided.

# TABLE 5 (cont'd)

F-16A <u>Left</u> Hand Reaches, Zones 1 and 2 - Individual Subject, Accommodation Database and COMBIMAN

		9	10	4	8	1	5	7	MEAN
SHLDR HT, TH-T REACH	SIT (L)	19.9 27.9	21.1 26.8	21.6 26.4	21.9 26.9	22.1 29.2	22.3 29.0	23.3 30.6	
CONTROL & (HAND INTE	RFACE)	REAC	н мі	S S I	) I S T :	ANCES	(I N	INCH	E S)*
28. COURSE	SELEC	T (T)							
SUBJECT DATA	ZONE 2	1 <b>-9.9</b>	<del>-</del> 9.5	-11.0 (Add	-9.9 +4.3 to	-7.3 all Zone	-7.9 1 value	-9.1 s)	-9.2
DATABASE	ZONE 2	1 -8.6 2 -4.3	-10.2 -5.9	-10.7 -6.4	-10.4 -6.1	-8.1 -3.8	-8.8 -4.5	-7.2 -2.9	-9.1 -4.8
COMBINAN	ZONE 2	1 2 -3.8	-4.3	-4.4	-5.3	-3.8	-2.3	-3.6	-3.9
29. <u>HSI Pu</u>	11 to 0	Cage (T)							
SUBJECT DATA	ZONE 2	1 -12.0 2	-12.8	-14.4 (Add	-12.0 +4.3 to	-9.7 all Zone	-10.2 1 value:	-11.0 s)	-11.7
DATABASE	ZONE 2	1 -12.1 2 -7.8	-13.1 -8.8	-13.4 -9.1	-12.9 -8.6	-10.6 -6.3	-10.7 -6.4	-9.1 -4.8	-11.7 -7.4
COMBIMAN	ZONE 2	1 2 <b>-6.</b> 7	-7.2	-7.2	-8.1	-6.7	-5.0	-6.1	-6.7
30. ALTIME	TER Sel	Lect (F)							
SUBJECT DATA	ZONE 1	-11.5 2	-11.8	-12.3 (Add	-10.8 +4.3 to	-8.6 all Zone	-9.0 1 value:	-9.3 s)	-10.5
DATABASE	ZONE 1	-10.9 2 -6.6	-11.6 -7.3	-11.9 -7.6	-11.3 -7.0	-9.0 -4.7	-8.8 -4.5	-7.2 -2.9	-10.1 -5.8
COMBIMAN	ZONE 1 ZONE 2		-5.0	-5.1	-6.0	-4.4	-2.8	-3.9	-4.5

^{* +} VALUES INDICATE EXCESSIVE REACH (REACH CAPABILITY BEYOND CONTROL).

- VALUES INDICATE INSUFFICIENT REACH (REACH CAPABILITY SHORT OF CONTROL).

** HAND INTERFACE: The interface of the hand with the control: e.g., "F" for Finger, "G" for Grip, "T" for Thumb/Forefinger, and "H" for Hook.

+ Controls too close to permit measurement. They, therefore, are easily reached.

⁺⁺ Data that, for various reasons, was not measured or provided.

TABLE 5 (cont'd)

# F-16A <u>Left</u> Hand Reaches, Zones 1 and 2 - Individual Subject, Accommodation Database and COMBIMAN

	9	10	4	8	1	5	7	MEAN
SHLDR HT, TH-T REACH		21.1 26.8	21.6 26.4	21.9 26.9	22.1 29.2	22.3 29.0	23.3 30.6	21.7 28.1
CONTROL & (HAND INTE		н мі	ss I	DISTA	NCES	(I N	INCE	i E S)*
31. FUEL C	QUANT SELECT (T	L						
SUBJECT DATA	ZONE 1 -15.4 ZONE 2	-14.9		-14.9 +4.3 to		_		-15.0
DATABASE	ZONE 1 -14.1 ZONE 2 -9.8	-15.8 -11.5	-16.5 -12.2	-16.1 -11.8	-13.9 -9.6	-14.7 -10.4	-13.1 -8.8	-14.9 -10.6
COMBIMAN	ZONE 1 ZONE 2							

TABLE 6

F-16A Right Hand Reaches, Zones 1 and 2 - Individual Subject, Accommodation Database and COMBIMAN

ALL SUBJECTS WERE IN THE FULL-UP SEAT ADJUSTMENT. ANTHROPOMETRIC DATA ARE REPORTED IN TABLE 1.

		9	10	4	8	1	5	7	MEAN
SHLDR HT, TH-T REACH	SIT (R)	19.9 27.9	21.1 26.8	21.6 26.4	21.9 27.4	22.1 27.8	23.3 29.0	23.3 30.0	21.9 27.9
CONTROL &		REAG	н мі	s s	DIST	ANCES	(I N	INC	H E S)
(HAND INTE	RFACE)	**							
31. FUEL O	UANT SI	ELECT (T)	<u>_</u>						
SUBJECT DATA	ZONE 2		-7.7			-5.1 all Zone			-6.8
DATABASE	ZONE 2	1 -6.9 2 <b>-4.</b> 6	-8.1 -5.8	-8.5 -6.2	-7.5 -5.2	-7.1 -4.8	-6.0 -3.7	-5.0 -2.7	-7.0 -4.7
COMBINAN	ZONE 2	<del>-</del>							
32. CONTRO	L GRIP	(G)							
Subject Data	ZONE 2		0.4			2.2 all Zone			0.6
Datab <b>a</b> se	ZONE 2	1.6 2 3.9	-0.1 2.2	-0.8 1.5	0.0 2.3	0.2 2.5	0.7 3.0	1.7 4.0	0.5 2.8
COMBIMAN	ZONE 2	_							
33. <u>ILS VO</u>	L (T)								
SUBJECT DATA	ZONE 2	-3.9	-3.4	-4.5 (Add	-4.7 +2.3 to	-2.2 all Zone	-1.6 1 value	-2.6 es)	-3.3
Database	ZONE 2	-3.2 2 -0.9	-4.6 -2.3	-5.1 -2.8	-4.2 -1.9	-3.9 -1.6	-3.0 -0.7	-2.0 0.3	-3.7 -1.4
COMBIMAN	ZONE 2	-							

^{* +} VALUES INDICATE EXCESSIVE REACH (REACH CAPABILITY BEYOND CONTROL).

- VALUES INDICATE INSUFFICIENT REACH (REACH CAPABILITY SHORT OF CONTROL).

** HAND INTERFACE: The interface of the hand with the control: e.g., "F" for Finger, "G" for Grip, "T" for Thumb/Forefinger, and "H" for Hook.

TABLE 6 (cont'd)

F-16A Right Hand Reaches, Zones 1 and 2 - Individual Subject,
Accommodation Database and COMBIMAN

			9	10	4	8	1	5	7	MEAN
SHLDR HT, TH-T REACH	SIT (R)		19.9 27.9	21.1 26.8	21.6 26.4	21.9 27.4	22.1 27.8		23.3 30.0	
CONTROL & (HAND INTE				н мі	ss D	IST	ANCES	(I N	INCH	E S)*
34. FUEL O	UANT S	SEL	ECT (T)							
SUBJECT DATA	zone zone	-	-8.3	-7.7			-5.1 all Zone			-6.8
DATABASE	ZONE ZONE	1 2	-6.9 -4.6	-8.1 -5.8	-8.5 -6.2	-7.5 -5.2	-7.1 -4.8		-5.0 -2.7	-7.0 -4.7
COMBIMAN	ZONE ZONE	_								
35. CONTRO	L GRI	? (	<u>G)</u>							
SUBJECT DATA	ZONE ZONE	_	0.0	0.4			2.2 all Zone			0.6
DATABASE	zone zone	_	1.6 3.9	-0.1 2.2	-0.8 1.5	0.0 2.3	0.2 2.5	0.7 3.0	1.7 4.0	0.5
COMBINAN	zone zone									
36. <u>ILS VO</u>	L (T)									
SUBJECT DATA	ZONE ZONE	-	-3.9	-3.4			-2.2 all Zone			-3.3
DATABASE				-4.6 -2.3	-5.1 -2.8	-4.2 -1.9	-3.9 -1.6	-3.0 -0.7	-2.0 0.3	-3.7 -1.4
COMBIMAN	zone zone	_								

^{* +} VALUES INDICATE EXCESSIVE REACH (REACH CAPABILITY BEYOND CONTROL).
- VALUES INDICATE INSUFFICIENT REACH (REACH CAPABILITY SHORT OF CONTROL).
** HAND INTERFACE: The interface of the hand with the control: e.g., "F" for Finger, "G" for Grip, "T" for Thumb/Forefinger, and "H" for Hook.

# TABLE 6 (cont'd)

### F-16A Right Hand Reaches, Zones 1 and 2 - Individual Subject, Accommodation Database and COMBIMAN

		9	10	4	8	1	5	7	MEAN
SHLDR HT, TH-T REACH	SIT (R)	19.9 27.9	21.1 26.8	21.6 26.4	21.9 27.4	22.1 27.8	23.3 29.0	23.3 30.0	21.9 27.9
CONTROL & (HAND INTE			H MI	s s D	ISTA	NCES	(I N	INCH	E S)*
37. <u>SUIT P</u>	RESSURI	E (F)							
SUBJECT DATA	ZONE 2		-1.7			-0.5 all Zone		-0.2 les)	-1.5
DATABASE	ZONE Z	1 -1.3 2 1.0	-2.6 -0.3	-3.1 -0.8	-2.1 0.2	-1.7 0.6	-0.7 1.6	0.2 2.5	-1.6 0.7
COMBINAN	ZONE	_							
38. MAL &	IND LIC	GHTS (F)							
SUBJECT DATA	ZONE 2		0.9			2.1 all Zone			1.6
DATABASE	ZONE 2	2.7 2.5.0	0.9 3.2	0.2 2.5	1.0 3.3	1.3 3.6	1.8 4.1	2.8 5.1	1.5 3.8
COMBIMAN	ZONE 2	_							
39. AERIAL	REFUEI	LIGHTS	<u>(T)</u>						
SUBJECT DATA	ZONE 2		2.7			2.6 all Zone			2.2
Database	ZONE 2	2.8	1.1 3.4	0.5 2.8	1.3 3.6	1.6 3.9	2.3 4.6		1.8
COMBINAN	ZONE 2	_							

^{* +} VALUES INDICATE EXCESSIVE REACH (REACH CAPABILITY BEYOND CONTROL).

⁻ VALUES INDICATE EXCESSIVE REACH (REACH CAPABILITY SHORT OF CONTROL).

** HAND INTERFACE: The interface of the hand with the control: e.g., "F" for Finger, "G" for Grip, "T" for Thumb/Forefinger, and "H" for Hook.

+ Controls too close to permit measurement. They, therefore, are easily

reached.

# TABLE 6 (cont'd)

### F-16A Right Hand Reaches, Zones 1 and 2 - Individual Subject, Accommodation Database and COMBIMAN

			9	10	4	8	1	5	7	MEAN
SHLDR HT, S			19.9 27.9	21.1 26.8	21.6 26.4	21.9 27.4				
CONTROL & (HAND INTE	RFACE			сн м:	ISS	DISTA	NCES	(I N	INCH	E S)*
40. ANTENN	A SEL	UH	F (F)							
SUBJECT DATA	zone zone	_	3.2	2.0		2.8 d +2.3 to	3.1 Zone 1		+	2.8
DATABASE	ZONE ZONE		3.4 5.7	1.8		2.1 4.4				2.6 4.9
COMBINAN	ZONE ZONE	_								
41. OXYGEN	SUPPI	LY_	100% N	orm (F)						
SUBJECT DATA	zone zone	_	3.2	0.7		2.8 d +2.3 to			5.6	2.8
DATABASE	zone zone		2.6 4.9	1.5 3.8			2.5 4.8		4.7 7.0	2.6 4.9
COMBINAN	ZONE ZONE	_								

^{* +} VALUES INDICATE EXCESSIVE REACH (REACH CAPABILITY BEYOND CONTROL).

⁻ VALUES INDICATE INSUFFICIENT REACH (REACH CAPABILITY SHORT OF CONTROL).

^{**} HAND INTERFACE: The interface of the hand with the control: e.g., "F" for Finger, "G" for Grip, "T" for Thumb/Forefinger, and "H" for Hook.

⁺ Controls too close to permit measurement. They, therefore, are easily reached.

TABLE 7

F-16A Overhead Clearance Data, Seat Full Down - in Inches (values in inches)

	SUBJECT DATA									
	1	5	4	3	6	Average				
Sitting Height	37.9	37.1	41.0	38.7	38.0	38.5				
Overhead Clearance	+5.6	+5.5	+1.5	+4.5	+5.0	+4.4				
Less Helmet	-1.5	-1.5	-1.5	-1.5	-1.5	-1.5				
Maximum Sitting Ht. Accommodated	42.0	41.1	41.0	41.7	41.5	41.5				
		D	ATAB	ASE						
Sitting Height	37.9	37.1	41.0	38.7	38.0	38.5				
Overhead Clearance (From Helmet)	+3.6	+4.4	+0.5	+2.8	+3.5	+3.0				
Maximum Sitting Ht. Accommodated	41.5	41.5	41.5	41.5	41.5	41.5				
		c	омві	M A N						
Sitting Height	37.9	37.1	41.0	38.7	38.0	38.5				
Overhead Clearance										
Less Helmet	-1.5	-1.5	-1.5	-1.5	-1.5	-1.5				

Maximum Sitting Ht. Accommodated

Table 8 lists operational clearances between the leg and the main instrument panel in the F-16A. Measurements were made after the subject had adjusted the seat to his/her best flying position. The rudder pedal carriage is adjusted to the most forward position that permits the subject full forward throw and brake, with the knee comfortably, but fully extended, and without squirming either hip forward. The feet then engage the pedals in the neutral position. Clearances are measured between the leg (at the knee or shin) and the lower edge of the main instrument panel, and/or protruding controls and control guards.

Knee clearances with the glare shield are presented in Table 9. The thighs should be set at right angles to the ejection rails and the knees and feet are set 12 inches apart. A straight-edge is placed against the forward surface of the left knee in single cockpits and held in the vertical (X-Z) fore-aft plane. The top of a straight-edge is adjusted to an angle equal to that of the ejection rails. Clearance is measured perpendicular from the aft surface of the straight edge to the nearest non-frangible cockpit structure or other threatening surface or edge forward of the knees.

TABLE 8

F-16A Operational Shin Clearance with Main Instrument Panel (values in inches)

			(valu	es in	inche	3)			
SUBJECT DATA*	NA	NA	NA	NA	NA	NA	1	3	Averages
Buttock Knee Lth	26.1	26.0	25.8	26.4	27.4	26.7	26.7	25.8	26.4
Shin Clearance with MIP	.75	.5	.25	1.0	.12	25 .25	1.37	5 .625	.6
Maximum Buttock Knee L. Accom- modated.	27.1	26.5	26.2	27.4	27.4	27.0	28.1	26.4	27.0
DATABASE									
Buttock Knee Lth	26.1	26.0	25.8	26.4	27.4	26.7	26.7	25.8	26.4
Shin Clearance with MIP	.7	1.0	1.1	.6	3	.3	.3	1.2	.6
Maximum Buttock Knee L. Accom- modated.	26.8	27.0	26.8	27.0	27.1	27.0	27.0	27.0	27.0
COMBIMAN									
Buttock Knee Lth	26.1	26.0	25.8	26.4	27.4	26.7	26.7	25.8	26.4
Shin Clearance with MIP									

Maximum Buttock Knee L. Accommodated.

^{*} Subjects indicated by "NA" were from another program. Complete anthropometric data are not available.

TABLE 9

Clearance Between the Knees and the Glare Shield, F-16A (values in inches)

SUBJECT DATA*	1	2	3	4	AVERAGES
Buttock-Knee Lgth.	26.7	27.4	25.8	27.0	26.7
CLEARANCE	3.5	2.8	2.4	-	2.9
Maximum Buttock- Knee Lgth. Accom- modated	30.2	30.2	28.2	-	29.5
DATABASE					
Buttock-Knee Lgth.	26.7	27.4	25.8	27.0	26.7
CLEARANCE	2.8	2.1	3.7	2.5	2.8
Maximum Buttock- Knee Lgth. Accom- modated	29.5	29.5	29.5	29.5	29.5
COMBIMAN					
Buttock-Knee Lgth.	26.7	27.4	25.8	27.0	26.7

# CLEARANCE

Maximum Buttock-Knee Lgth. Accommodated

#### ANTHROPOMETRIC DESCRIPTIONS

### BIACROMIAL BREADTH

Subject sits erect, head in the Frankfort plane, arms hanging relaxed, elbows flexed to about 90 degrees, and forearms and hands extended forward horizontally - the horizontal distance between the right and left Acromiale.

#### BUTTOCK-KNEE LENGTH

Subject sits erect, feet resting on a surface adjusted so that the knees are flexed to about right angles and thighs horizontal - the horizontal distance from the rearmost surface of the right buttock to the forward surface of the right kneecap.

### CHEST DEPTH

Subject stands erect - the maximum horizontal depth of the torso at the level of the nipples during quiet breathing.

### ELBOW-WRIST LENGTH

Subject stands erect (Typ), right arm hanging at the side, elbow flexed to 90 degrees, the forearm and hand extended forward horizontally, hand flattened - the distance from the tip of the right elbow to the wrist (Stylion).

#### FOOT LENGTH

Subject stands, weight equally distributed on both feet - the maximum length of the foot to the longest toe, parallel to the longitudinal axis of the foot.

### FRANKFORT PLANE

A standard plane of reference of the head, realized when the lowest point of the bony margin of the eye socket (orbit) and the left tragion (top of the tragus or "flap" which forms the forward margin of the "ear hole") are in a common horizontal plane.

# HAND LENGTH

Right hand extended, flattened, palm up, fingers extended and together - the distance from the proximal edge of the navicular bone in the wrist (USAF.MEN) or from the distal wrist crease (USAFLY.MEN, USAF.WOM and USAFLY.WOM) to the tip of the longest finger parallel to the long axis of the hand.

### HIP BREADTH, SITTING

Subject sits, feet resting on a surface adjusted so that the knees are flexed to about 90 degrees and thighs are parallel - the horizontal distance across the widest part of the hips.

### SHOULDER-ELBOW LENGTH

Subject sits erect, arms hanging relaxed at sides, elbow flexed to 90 degrees, forearms and hands directed forward horizontally - the vertical distance from the right Acromion (Acromiale) to the bottom of the elbow (olecranon process).

# SHOULDER (ACROMION) HEIGHT, SITTING

Subject sits erect, head in the Frankfort plane, upper arms hanging relaxed at sides, and forearms and hands extended forward horizontally - the vertical distance from the sitting surface to the right Acromion - bony landmark at the tip of the shoulder.

### SITTING EYE HEIGHT

Subject sits erect, head in the Frankfort plane, upper arms hanging relaxed, forearms and hands extended forward horizontally - the vertical distance from the sitting surface to the right external canthus (outer "corner").

### SITTING HEIGHT

subject sits erect, head in the Frankfort plane, upper arms hanging naturally at sides, elbows flexed to 90 degrees, forearms and hands directed forward - the vertical distance from the sitting surface to the top of the head.

#### SITTING KNEE HEIGHT

subject sits with feet resting on a surface adjusted so that the thighs are horizontal and the knees are flexed to about 90 degrees - the vertical distance from the footrest surface to the superior margin of the right knee cap.

### THUMB-TIP REACH

subject stands erect with heels, buttocks, and back in contact with a wall or other vertical surface. The right arm is rotated forward to the horizontal, thumb and forefinger tips opposed in a finger-tip grasping attitude, thumb extended and parallel to the axis of the arm and forearm - the distance from the wall to the tip of the thumb.

#### WEIGHT

The subject is nude or wearing brief undergarments - read to the nearest pound.

Multivariate models, developed to guide the anthropometric input into COMBIMAN are shown in Table B-1. Usually eight models are used to represent a population and consist of six to eight body dimensions. COMBIMAN, however, requires 12 models and 12 body dimensions, because of the introduction of mass related anthropometric dimensions (breadths, depths, and weight) for the computer model. Some of the additional measurements necessary for representation with COMBIMAN were regressed from Sitting Height, Buttock-Knee Length, and Weight. Selection of these variables as regressors was based upon a principal components analysis. That analysis showed which of these three measurements received the highest factor loadings on each of the first three principal components.

Body size values for each of the multivariate models were run through the Cockpit Accommodation Database. Since the mass-related measurements are not required as input for the database, it was only necessary to run the six models as originally defined (that is, without the lightweight / heavyweight distinctions). Data regarding accommodation of each model in the F-16A are reported in Tables B-2 through B-8.

Most of the values from the database are developed by regression equations based on subjects of various sizes. Others are mean values from a group of subjects selected to be near the "critical value". For example, subjects near 40 inches in Sitting Height were selected for measuring overhead clearance in the F-16A. Each subject's Sitting Height was added to the distance they adjusted the seat upwards to make contact with the canopy. Those values were averaged to determine the maximum Sitting Height that would fit into the aircraft when the seat was adjusted full down.

There is always some variance around the mean in measures such as these. Therefore, the results for the test cases can be interpreted as the "average" values for a group of individuals of that particular size. Some variation around the predicted values the database delivers are expected.

TABLE B-1: ANTHROPOMETRIC MULTIVARIATE MODELS WITH ADDITIONAL MEASURES FOR COMBIMAN.

	MODEL 1	MODEL 2	MODEL 3	MODEL 4	MODEL 5	MODEL 6
	GENERALIZED	GENERALIZED	SMALL FEMALE	SMALL FEMALE	MALE	MALE
	SMALL FEMALE LIGHT WEIGHT	SMALL FEMALE HEAVY WEIGHT	SHORT REACH HIGHER SHLDRS LIGHT WEIGHT	SHORT REACH HIGHER SHLDRS HEAVY WEIGHT	SHORT TORSO LONG LIMBS LIGHT WEIGHT	SHORT TORSO LONG LIMBS HEAVY WEIGHT
WEIGHT	103.0	138.0	110.0	135.0	145.0	197.0
SITTING HEIGHT	34.0	34.0	35.5	35.5	34.9	34.9
	28.9	28.9	30.7	30.7	30.2	30.2
	21.3	21.3	22.7	22.7	22.6	22.6
	19.5	19.5	19.1	19.1	23.3	23.3
THUMBTIP REACH	28.3	28.3	27.6	27.6	33.9	33.9
BUTTOCK-KNEE LENGTH	22.1	22.1	21.3	21.3	26.5	26.5
SHOULDER-ELBOW LGTH	13.0	12.9	12.8	12.7	15.5	15.4
BIACROMIAL BREADTH	14.5	14.9	14.6	15.0	15.4	16.0
HIP BREADTH, STANDING	12.4	13.8	12.6	14.0	12.5	13.9
CHEST DEPTH	8.1	9.6	0.8	9.5	8.5	10.2
FOOT LENGTH	9.3	9.6	9.2	9.5	11.0	11.2
HAND LENGTH	7.1	7.1	6.9	7.0	0.8	8.1
ELBOW-WRIST LENGTH	10.1	10.0	8.6	9.7	12.3	12.3

TABLE B-1: ANTHROPOMETRIC MULTIVARIATE MODELS WITH ADDITIONAL MEASURES FOR COMBIMAN (CONT'D).

	MODEL 7	MODEL 8	MODEL 9	MODEL 10	MODEL 11	MODEL 12
	GENERALIZED LARGE MALE LIGHT WEIGHT	GENERALIZED LARGE MALE HEAVY WEIGHT	MALE SHORT TORSO LONG LIMBS LIGHT WEIGHT	MALE SHORT TORSO LONG LIMBS HEAVY WEIGHT	MALE LONG TORSO SHORT LIMBS LIGHT WEIGHT	MALE LONG TORSO SHORT LIMBS HEAVY WEIGHT
METCHE	195 0	245.0	0 121	9	4	
	) · · · · · · · · · · · · · · · · · · ·	0.044	0.101	0.002	0.641	190.0
SITTING HEIGHT	40.0	40.0	38.0	38.0	38.5	38.5
SITTING EYE HEIGHT	35.0	35.0	32.9	32.9	33.4	33.4
SITTING ACROMION HT	26.9	26.9	25.0	25.0	25.2	25.2
SITTING KNEE HEIGHT	24.7	24.7	24.8	24.8	20.6	20.6
THUMBTIP REACH	35.6	35.6	36.0	36.0	29.7	29.7
BUTTOCK-KNEE LENGTH	27.4	27.4	27.9	27.9	22.7	22.7
SHOULDER-ELBOW LGTH	16.3	16.2	16.3	16.3	14.1	14.1
BIACROMIAL BREADTH	16.7	17.2	16.1	16.6	15.5	16.0
HIP BREADTH, STANDING	14.2	15.5	13.1	14.3	13.0	14.2
CHEST DEPTH	9.6	11.3	8.5	10.0	9°	10.1
FOOT LENGTH	11.7	11.9	11.6	11.7	10.3	10.5
HAND LENGTH	8.3	8.5	8.3	8.4	7.4	7.5
ELBOW-WRIST LENGTH	12.7	12.7	12.9	12.9	10.9	10.9

TABLE B-2: F-16A VISION FROM THE COCKPIT - IN DEGREES*

ALL DATA HAVE BEEN DERIVED FROM THE ACCOMMODATION DATABASE.

	M	U	Ŀ	T	Ι	V	Α	R	I	Α	T	E	M	0	D	E	L	S
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1&2 3&4 5&6 7&8 9&10 11&12

EYE HT SIT 28.9 30.7 30.2 35.0 32.9 33.4

SEAT FULL UP.

FrPl O'Nose -11 -16 -14

Head Up/Aft -13 -18 -16

over Side -23 -28 -27

SEAT AT -1.3 INCHES FROM FULL UP.

FrPl O'Nose -12

Head Up/Aft -14

Over Side -24

SEAT AT -2 INCHES FROM FULL UP.

FrPl O'Nose -12

Head Up/Aft -14

Over Side -24

SEAT AT -4 INCHES FROM FULL UP.

FrPl O'Nose -15

Head Up/Aft -17

Over Side -27

* All visions angles are rounded to the nearest degree.

TABLE B-3: F-16A RUDDER PEDAL ACCESS - INCHES OF EXCESS LEG LENGTH BEYOND THAT NEEDED

TO ACTUATE RUDDER PEDALS IN FULL AFT CARRIAGE POSITION

ALL DATA HAVE BEEN DERIVED FROM THE ACCOMMODATION DATABASE.

	MUI	LTIV	ARIA	TE	MODE	LS
	1&2	3&4	5&6	7&8	9&10	11&12
BUTT KNEE L.	22.1	21.3	26.5	27.4	27.9	22.7
KNEE HT, SIT	19.5	19.1	23.3	24.7	24.8	20.6
COMBINED LEG	41.6	40.4	49.8	52.1	52.7	43.3

SEAT FULL UP

DATABASE EXCESS LEG 3.2 2.0 LENGTH

SEAT -2 INCHES FROM FULL UP

DATABASE EXCESS LEG LENGTH

3.7

SEAT - 4 INCHES FROM FULL UP

DATABASE EXCESS LEG LENGTH

8.3

TABLE B-4: F-16A LEFT HAND REACH MISS DISTANCES, ZONES 1 AND 2.*
ALL DATA HAVE BEEN DERIVED FROM THE ACCOMMODATION DATABASE.

	SEAT FUI	LL UP	-2 IN	EAT ICHES FULL UP	SEAT -4 INCHES FROM FULL UP
	1&2	3&4	3&	4	11&12
SHLDR HT, SIT TH-T REACH	21.3 28.3	22.7 27.6		2.7	25.2 29.7
1. FIRE/OVERHEAT DI	ETECT (F		•		
ZONE 1 ZONE 2	_	-1.5 0.7	-	0.1 2.2	
2. ANTI-G TEST (F)		0.4			
ZONE 1 ZONE 2	_	-0.4 1.8			
3. RUDDER ARM (T)		1 2			
ZONE 1 ZONE 2	-	-1.3 0.9			
4. CANOPY JETTISON	<u>(T)</u>				
ZONE 1 ZONE 2	-	-1.4 0.8			
5. MAIN POWER (BAT	T) (T)				
ZONE 2	_	-0.8 1.4			
6. THROTTLE Fwd (H		2.6	,		
ZONE 1 ZONE 2	2.2	-2.6 1.0		1.9 1.7	

^{*} Controls listed are those for which Zone 1 miss distances (negative values) are found. This list is not all inclusive. It is taken from a sampling of controls. Controls that are not listed should not necessarily be considered accessible under Zone 1 restraint conditions.

TABLE B-4: F-16A <u>LEFT</u> HAND REACH MISS DISTANCES, ZONES 1 AND 2. (CONT'D)

MULTIVARIATE MODELS

	SEAT FU	LL UP	SEAT -2 INCHES FROM FULL UP	SEAT -4 INCHES FROM FULL UP
	1&2	3&4	3&4	11&12
SHLDR HT, SIT TH-T REACH	21.3 28.3	22.7 27.6	22.7 27.6	25.2 29.7
7. EEC Off/Buc (F) ZONE 1 ZONE 2		-1.1 2.5	-0.8 2.8	
8. UHF PRESET ZONE 1 ZONE 2	-0.1 3.5	-1.4 2.2	-0.6 3.0	
9. <u>JET FUEL START</u> ZONE 1  ZONE 2	-2.6	-3.9 -0.3	-3.1 0.5	-1.2 2.4
	) -1.7 1.9		-2.2 1.4	-0.2 3.4
11. MANUAL PITCH OF ZONE 1 ZONE 2	-2.4	(F) -3.4 0.2	-3.0 0.6	-1.0 2.6
12. STORAGE CONFIG ZONE 1 ZONE 2	-3.0	F) -3.8 -0.2	-3.7 -0.1	-1.6 2.0
13. DOWNLOCK RELEATION 2 ONE 1 ZONE 2	-3.0	-3.6 0.0	-3.8 -0.2	-1.6 2.0

TABLE B-4: F-16A LEFT HAND REACH MISS DISTANCES, ZONES 1 AND 2. (CONT'D)

MULTIVARIATE MODELS

	SEAT FU	LL UP	SEAT -2 INCHES FROM FULL UP	
	1&2	3&4	3&4	11&12
SHLDR HT, SIT TH-T REACH	21.3 28.3	22.7 27.6	22.7 27.6	25.2 29.7
14. EMERGENCY STOR	ES JETTI	SON (F)		
ZONE 1 ZONE 2		-5.1 -1.5	-5.6 -2.0	-3.4 0.2
15. PITCH ALT HOLD	<b>(F)</b>			
ZONE 1	-4.7		-5.4	-3.3
ZONE 2	-1.1	-1.6	-1.8	0.3
16. IFF IDENT (F)				
ZONE 1	-5.2		-5.9	-3.8
ZONE 2	-1.6	-2.1	-2.3	-0.2
17. MASTER CAUTION	(F)			
ZONE 1		-3.6	-2.6	-0.7
ZONE 2	2.1	0.7	1.7	3.6
18. DIS/LTS (T)				
	-8.3	-9.6	-8.8	
ZONE 2		-5.3	-4.5	
10				
19. SELECT JETTISO ZONE 1		-8.3	-8.3	-6.2
ZONE 2		-4.0	-4.0	-1.9
20. SHIFT (MFD) (F ZONE 1		-7.9	-7.6	-5.5
ZONE 1 ZONE 2		-7.9 -3.6	-7.6 -3.3	-5.5 -1.2
BORE Z	2.1	5.0	3.3	

TABLE B-4: F-16A LEFT HAND REACH MISS DISTANCES, ZONES 1 AND 2. (CONT'D)

MULTIVARIATE MODELS

	SEAT FU	LL UP	SEAT -2 INCHES FROM FULL UP	SEAT -4 INCHES FROM FULL UP
	1&2	3&4	3&4	11&12
SHLDR HT, SIT TH-T REACH	21.3 28.3		22.7 27.6	25.2 29.7
21. HUD FILTER (T)				
	-5.2 -0.9		-5.9 -1.6	-3.8 0.5
22. HUD MILS-DEPR	(T)			
	<del>-7</del> .0		-7.9	-5.7
ZONE 2	-2.7	-3.1	-3.6	-1.4
23. AIR SPEED/MACH	IND (T)			
ZONE 1	-9.1		<b>-9.</b> 7	
ZONE 2	-4.8	-5.6	-5.4	
24. TACAN HEADING	(T)			
	<del>-7</del> .3	-8.5	-7.8	-5.9
ZONE 2	-3.0	-4.2	-3.5	-1.6
25. COURSE SELECT	/ TT \			
ZONE 1		-10.0	-9.2	
	-4.4		-4.9	
26. HSI Pull to Cac ZONE 1 -		12.2	10.0	
ZONE 1 -		-12.2 -7.9	-12.3 -8.0	-10.2 -5.9
20112 2			-6.0	-5.9
27. ALTIMETER Select				
ZONE 1 -		-10.4	-10.9	
ZONE 2	-5.8	-6.1	-6.6	

TABLE B-4: F-16A <u>LEFT</u> HAND REACH MISS DISTANCES, ZONES 1 AND 2. (CONT'D) FULL-UP SEAT ADJUSTMENT

	SEAT 1	FULL UP	SEAT -2 INCHES FROM FULL UP	SEAT -4 INCHES FROM FULL UP						
	1&2	3&4	3&4	11&12						
SHLDR HT, SIT TH-T REACH	21.3 28.3	22.7 27.6	22.7 27.6	25.2 29.7						
28. FUEL QUANT SEL	28. FUEL QUANT SELECT (T)									
ZONE 1 ZONE 2		-15.8 -11.5	-14.8 -10.5	-12.9 -8.6						

TABLE B-5: F-16A'RIGHT HAND REACH MISS DISTANCES, ZONES 1 AND 2.
ALL DATA HAVE BEEN DERIVED FROM THE ACCOMMODATION DATABASE.

	SEAT FU	ULL UP		SEAT -4 INCHES FROM FULL UP
	1&2	3&4	3&4	11&12
SHLDR HT, SIT TH-T REACH	21.3 28.3	22.7 27.6	22.7 27.6	25.2 29.7
CONTROL & (HAND INTERFACE)	F	REACH MISS	DISTANCES (IN )	INCHES).
28. FUEL QUANT SEL	ECT (T)			
		-7.4 -5.1	-7.2 -4.9	-5.2 -2.9
29. CONTROL GRIP (	G)			
ZONE 1 ZONE 2	-	-0.2 2.1		
30. ILS VOL (T)				
ZONE 1 ZONE 2	-3.1 -0.8	-4.2 -1.9	-3.7 -1.4	-1.7 0.6
31. <u>SUIT PRESSURE</u>	<u>(F)</u>			
	-1.1 1.2		-1.7 0.6	

^{*} Controls listed are those for which Zone 1 miss distances (negative values) are found. This list is not all inclusive. It is taken from a sampling of controls. Controls that are not listed should not necessarily be considered accessible under Zone 1 restraint conditions.

TABLE B-6: F-16A OVERHEAD CLEARANCE DATA - IN INCHES.

ALL DATA HAVE BEEN DERIVED FROM THE ACCOMMODATION DATABASE.

SEAT FULL UP	M U L T	I V A R	I A T E	мор	ELS	
	1&2	3&4	5&6	7&8	9&10	11&12
Sitting Height Overhead Clearance	34.0 3.2	35.5 1.7	34.9 2.3	40.0	38.0	38.5
(From Helmet) Remaining Downward	5.0	5.0	5.0			
Seat Adjust Maximum sitting Ht. Accommodated	42.2	42.2	42.2			
SEAT -2" FROM	MULT	I V A R	I A T E	M O D	ELS	
FULL UP	1&2	3&4	5&6	7 <b>&amp;</b> 8	9&10	11&12
Sitting Height Overhead Clearance (From Helmet) Remaining Downward	34.0	35.5 3.4 3.0	34.9	40.0	38.0	38.5
Seat Adjust Maximum Sitting Ht. Accommodated		41.9				
SEAT -4" FROM	MULT	IVAR	I A T E	MOD	E L S	
FULL UP	1&2	3&4	5&6	7&8	9&10	11&12
sitting Height Overhead Clearance	34.0	35.5	34.9	40.0	38.0	38.5 2.1
(From Helmet) Remaining Downward						1.0
Seat Adjust Maximum Sitting Ht. Accommodated						41.6

TABLE B-6: F-16A OVERHEAD CLEARANCE DATA - IN INCHES (CONT'D).

ALL DATA HAVE BEEN DERIVED FROM THE ACCOMMODATION DATABASE.

SEAT -1.3" FROM FULL UP	MUL	TIVA	RIAT	E MO	DELS		
<u> </u>	1&2	3&4	5&6	7&8	9&10	11&12	
Sitting Height	34.0	35.5	34.9	40.0	38.0	38.5	
Overhead Clearance (From Helmet)	3.4						
Remaining Downward Seat Adjust	3.7						
Maximum Sitting Ht. Accommodated			42.0				
SEAT FULL DOWN	M U L T	IVAR	IATE	мор	ELS		
	1&2	3&4	5&6	7 <b>&amp;</b> 8	0.10	11&12	
	102	244	240	/ <b>e</b> z O	9&10	11412	
sitting Height	34.0	35.5	34.9	40.0	38.0	38.5	
Sitting Height  Overhead Clearance (From Helmet)							
Overhead Clearance					38.0		

TABLE B-7: F-16A OPERATIONAL SHIN CLEARANCE WITH MAIN INSTRUMENT PANEL

ALL DATA HAVE BEEN DERIVED FROM THE ACCOMMODATION DATABASE.

SEAT FULL UP	MULTI	VARIATE	MODELS
	1&2 3&4	5&6 7&8	9&10 11&12
Buttock Knee Lth	22.1 21.3	26.5 27.4	27.9 22.7
Shin Clearance with MIP		0.5	
Maximum Buttock Knee L. Accom- modated.		27.0	
SEAT -1.3" FROM FULL UP	MULTI	VARIATE	MODELS
	1&2 3&4	5&6 7&8	9&10 11&12
Buttock Knee Lth	22.1 21.3	26.5 27.4	27.9 22.7
Shin Clearance with MIP		0.5	
Maximum Buttock Knee L. Accom- modated.		27.0	
SEAT FULL DOWN	MULTI	VARIATE	MODELS
	1&2 3&4	5&6 7&8	9&10 11&12
Buttock Knee Lth	22.1 21.3	26.5 27.4	27.9 22.7
Shin Clearance with MIP			-0.9
Maximum Buttock Knee L. Accom-			27.0

modated.

TABLE B-8: CLEARANCE BETWEEN THE KNEES AND THE GLARE SHIELD, F-16A - IN INCHES

ALL DATA HAVE BEEN DERIVED FROM THE ACCOMMODATION DATABASE.

SEAT FULL UP	м и	MULTIVARIATE MODEL			s	
	1&2	3&4	5&6	7&8	9&10	11&12
Buttock Knee Lth	22.1	21.3	26.5	27.4	27.9	22.7
Knee Clearance Glare Shield			3.0			
Maximum Buttock Knee L. Accom- modated.			29.5			
SEAT -1.3 FROM	MULTIVARIATE MODELS					
FULL UP	1&2	3&4	5&6	7 <u>&amp;</u> 8	9&10	11&12
Buttock Knee Lth	22.1	21.3	26.5	27.4	27.9	22.7
Knee Clearance Glare Shield			3.0			
Maximum Buttock Knee L. Accom- modated.			29.5			
SEAT FULL DOWN	M U	LTIV	ARIA	TE M	ODEL	s
	1&2	3&4	5&6	7 <b>&amp;</b> 8	9&10	11£12
Buttock Knee Lth	22.1	21.3	26.5	27.4	27.9	22.7
Knee Clearance Glare Shield					1.6	
Maximum Buttock Knee L. Accom- modated.					29.5	